# DEPARTMENT OF MECHANICAL ENGINEERING

SCHEME OF INSTRUCTION AND SYLLABI OF

# M.E.

# (Mechanical Engineering)

**Specialization:** 

# CAD/CAM



# 2016-17 – CBCS

CHAITANYA BHARATHI INSTITUTE OF TECHNOLOGY (Autonomous) Affiliated to Osmania University Hyderabad – 500 075, Telangana, INDIA

# CHAITANYA BHARATHI INSTIUTE OF TECHNOLOGY

# (AUTONOMOUS)-CBCS

Gandipet, Hyderabad - 500 075

# INSTITUTE

## Vision

To be a centre of excellence in technical education and research

# Mission

To address the emerging needs through quality technical education and advanced research

# DEPARTMENT

## Vision

To be a Pace Setter in the field of mechanical Engineering by providing conducive environment for understanding and applying its principles to cater the needs of Society

# Mission

To impart quality & innovative technical education to the students of mechanical engineering for their professional achievements in consultancy, R&D and to become successful entrepreneur enabling them to serve the society in general and the industry in particular

# CHAITANYA BHARATHI INSTIUTE OF TECHNOLOGY (AUTONOMOUS) Gandipet, Hyderabad – 500 075 MECHANICAL ENGINEERING Programme: M.E (CAD/CAM)

# **Programme Educational Objectives:**

- 1. Will become professional contributors in the industry related to the area of CAD/CAM
- 2. Will excel in research & development and consultancy
- 3. Will become entrepreneurs in CAD/CAM industry.

POs describe what students are expected to know or be able to do by the time of graduation from the program.

- 1. To demonstrate knowledge in core subjects of CAD/CAM with mathematical & numerical orientation.
- 2. To exhibit proficiency in usage of software packages of solid modeling, meshing and analysis.
- 3. To understand advanced technologies in the area of Manufacturing & Automation in Manufacturing
- 4. To posses the necessary skills to prepare the project proposals by referring technical papers in various reputed journals, pertaining to CAD/CAM.
- 5. To Understand the concepts and principles of Engineering Research Methodology and apply the same for designing and conducting experiments related to the area of CAD/CAM.
- 6. To acquire leadership qualities by organizing and participating in various events.

Note: PEOS are expected to achieve after 2 years of graduation

				Semester - I	4 Semesters			
		No. of Hr	s. per	Duration		Marks for		
SI. No	Subject	week Lecture		(Hrs)	Internal Assessment	End Exam	Total Marks	Credits
1.	Core	3	1	4	30	70	100	4
2.	Core	3	1	4 4	30	70	100	4
<u>2.</u> 3.	Core	3	1	4 4	30	70	100	4
<u> </u>	Elective	3		3	30	70	100	3
<u>4.</u> 5.	Elective	3		3	30	70	100	3
<u> </u>	Elective	3		3	30	70	100	3
7.	Laboratory		3	3	50		50	2
8.	Seminar - I		3	3	50		50	2
<u> </u>	Soft Skills							Z
9.	Total	18	09			360	700	
	TULAI	10	09	Somootor II	340	300	700	25
			0 000	Semester - II	Mark	s for		
		No. of Hr week		Duration	Internal	5 101	Total	
SI.		week		(Hrs)	Assessment	End Exam	Marks	Credits
No	Subject	Lecture	T/P/S	(115)	Assessment		iviai kā	Credits
1.	Core	3	1/F/3		30	70	100	4
2.	Core	3	1		30	70	100	4
<u>2.</u> 3.	Core	3	1		30	70	100	4
	Elective	3			30	70	100	3
<u>4.</u> 5.	Elective	3				70	100	
5. 6.	Elective	3			30 30	70	100	3
<u>0.</u> 7.			 3		50		50	2
	Laboratory - II		3					2
8.	Seminar - II		2		50		50	<u> </u>
9.	Mini Project	18	 11		50 <b>390</b>		50 <b>750</b>	-
	Total	10				360	750	26
	1			Semester - III				1
SI. No		bject		Mar Internal Assessment	ks for End Exam	Total Ma	arks	Credits
1	Project Seminar* (i)Problem formulation synopsis within 8 were commencement of 3 (50 Marks) (ii) Preliminary work implementation. (50 Marks)	eeks from the 3rd Semester.	sion of	100		100		6
	Total			100		100		6
				Semester - IV				
SI.					ks for		-	Credits
SI. No	Su	bject		Internal Assessment	End Exam	Total Ma	arks	Creats
NO								

#### Scheme of Instruction & Examination M.E. (CAD/CAM) – Mechanical Engineering - 4 Semesters (Full Time)

Note: Six core subjects, Six elective subjects, Two Laboratory Courses and Two Seminars, Mini Project

and Soft Skills should normally be completed by the end of semester II.

\* Project seminar presentation on the topic of Dissertation only, 50 marks awarded by the project guide

and 50 marks by the internal committee

Credit requirements for the award of degree, lower limit and upper limit of credits for registration by a student in a semester Credit Requirement for the award of M.E/M. Tech. Degree is 69

# Scheme of Instruction & Examination Post Graduate course in Mechanical Engineering

# with specialization in CAD/CAM

# Course duration: 4 Semesters (Full – Time)

				me of	Schem	e of Exa	mination	Credits
SI.	Syllabus			s per				
No	Ref.No.	Subject		ek	Duration	Ма	x. Marks	
			vve		in Hours	End		
			L	T/P	in riours		Internal Assessment	
		CORE SUBJECTS						
1.	16MEC101	Automation	3	1	4	70	30	4
2.	16MEC102	Computer Aided Modeling and Design	3	1	4	70	30	4
3.	16MEC103	Computer Integrated Manufacturing	3	1	4	70	30	4
4.	16MEC104	Computer Aided Mechanical Design and Analysis	3	1	4	70	30	4
5.	16MEC105	Finite Element Techniques	3	1	4	70	30	4
6.	16MEC205	Computational Fluid Dynamics	3	_1	4	70	30	4
		ELECTIVES				<u> </u>		
1	16MEE101	Failure Analysis and Design	3		3	70	30	3
2.		Integrated Mechanical Design	3	- 1	3	70	30	3
3.		Robotic Engineering	3		3	70	30	3
4.		Programming Methodology and Data Structures	3		3	70	30	3
5.	16MEE105	Optimization Techniques	3		3	70	40	3
6.	16MEE106	Vibrations Analysis and Condition Monitoring	3		3	70	30	3
7.	16MEE107	Engineering Research Methodology	3		3	70	30	3
8.	16MEE108	Tribology In Design	3		3	70	30	3
9.	16MEE109	Advanced Mechanics of Materials	3		3	70	30	3
10.	16MEE110	Mechanics of Composite Materials	3		3	70	30	3
11.	16MEE111	Theory of Elasticity and Plasticity	3		3	70	30	3
12.	16MEE112	Experimental Techniques and Data Analysis	3		3	70	30	3
13.		Design for Manufacture	3		3	70	30	3
14.		Data Base Management Systems	3		3	70	30	3
15.		Fracture Mechanics	3		3	70	30	3
16.		Design of Press Tools	3		3	70	30	3
17.		Design of Dies	3		3	70	30	3
18.		Rapid Prototyping Principles & Applications	3		3	70	30	3
19.		Flexible Manufacturing Systems	3		3	70	30	3
		Non-Traditional Machining & Forming	3		3	70	30	3
21	16MEE121	Product Design and Process Planning	3		3	70	30	3
		DEPARTMENTAL	REQU		NTS			
1.	16MEC106	CAD/CAM Lab (Lab –I)		3			50	2
2.	16MEC107	Computation Lab (Lab –II)		3			50	2
3.	16MEC108	Seminar – I		3			50	2
4.	16MEC109	Seminar – II		3			50	2
5	16MEC110	Mini Project		2			50	1
6	16MEC111	Project Seminar		6			100	6
7	16MEC112	Project work		6		100	100	12

CBIT	Autonomous Regulation		Seme	ester-1			AY - 2006	5-17	
Department	Mechanical Engineering		amme Co	ode & Na	ame	M.E. CA	AD/CAM		
Course Code	Course Name	Hours	/Week		Credit	Maximu	ım Marks		
		L	Т	Р	C	E	I	Tota	al
16MEC 101	AUTOMATION	3	1	0	4	70	30	100	)
Objective (s)	Student will 1. To learn & understand industries 2. To understand Detroi 3. To conceptualize & d 4. To learn about autom 5. To understand differed 6. To design effective a	it type au esign as nated ma ent auton	Itomatior sembly li terial ha nated sto	n & flow l ne balan ndling sy prage/ret	lines. ncing ⁄stems rieval sys	tem	ficance in	manufact	turing
Outcome (s)	1. Ability to conceptualiz					Systems			
	<ol> <li>Ability to implement li</li> <li>Ability to understand operations</li> <li>Ability to design, imp</li> <li>Ability to understand operations</li> </ol>	ine balar and dev lement a and dev	ncing cor velop au nd use a velop au	ncepts in tomated and appro tomated	productic material opriate au material	handling tomated i handling	system sui nspection f system sui	itable for facility itable for	
1.	6. Ability to design, imp	lement a	nd use a	nd appro	opriate au	tomated i	nspection f		9
Information Pr Production Ec Analysis, Unit <b>2.</b> Detroit-Type Au Storage, Contro Analysis of Au Storage, Partial Flow Lines <b>3.</b> Assembly Syste	Definition of automation, Type ocessing in Manufacturing, Pro- conomics: Methods of Evaluat cost of production, Cost of Mar <i>utomation</i> : Automated Flow lin ol Functions, Automation for <i>tomated Flow Lines</i> : General I Automation, Automated Flow <i>tomated Flow Lines</i> : General I Automation, Automated Flow <i>tomated Flow Lines</i> : The <i>A</i> Problem, Methods of Line E	aduction ing Inve nufacturin es, Meth Machinin Termino Lines w	v Process	and Ma Alternativ time and Workpart ations, I d Analys age Buff s, Assen	athematica ves, Cost I Work-in- t Transpo Design ar sis, Analy fers, Com nbly Syste	al Models, s in Man process. rt, Transf nd Fabric ysis of Tr puter Sim ems, Man	Automatic ufacturing, er Mechan ation Cons ransfer Lin nulation of Total ual Assem	In Strateg Break-E Hrs   iism, Buff sideration ies Witho Automate Hrs   bly Lines	gies, even 9 fer hs. but ed 9 s, The
Automated Ass	ine Balancing, Flexible Manusembly, Types of Automated Anines, Analysis of a Single Stati	Assembly	/ System	ns, Part					
4.							Total		9
Material Handli Automated Sto Storage System 5. Automated Insp Principles and I Contact Inspect Manufacturing Simulation Mod	erials Handling: The material h ing Systems, Design of the S prage Systems: Storage Systems, Work-in-process Storage, In pection and Testing: Inspecti Methods, Sensor Technologies ction Methods, Machine Vi Systems: Role of Performanc dels, Analytical Models. The tory, Human Workers in the Fut	System, em Perfo iterfacing on and s for Aut sion, O e Model <i>Future</i>	Conveyormance I Handlin testing, omated ther op ing, Perf Automate	or Syste , Automa ig and Si Statistic Inspection formance ed Facto	ems, Auto ated Stor torage wit cal Qualit on, Coord spection e Measur ory: Trend	mated G rage/Retri- h Manufa y Control linate Mea Methods es, Perfo ds in Ma	uided Veh eval Syste <u>cturing</u> <b>Total</b> I, Automat asuring Ma . <i>Modelin</i> rmance M	Hrs	tems. ousel 9 ection Other mated Γools:
	ory, numan workers in the Ful		maleu F		tal hours		ght		45
Education	Grover, Automation, Productio n Asia. sfahl, Robots and manufacturing							Pearson	
India Pvt.	adham and Y.Narahari, Perform Ltd., . Derby, Design of Automatic N		-			-	-		
	Pvt. Ltd, Chennai.	aorinary,	opecial		.anon, wa		51, INGW (C	IN ICOUR	0

CBIT	Autonomous Regulation		Sem	ester-1			AY - 200	6-17	
Department	Mechanical Engineering	Progra	amme C	ode & Na	ame		M.E. CAI	D/CAM	
Course Code	Course Name	Hours	/Week		Credit	Maximu	ım Marks		
16MEC 102	COMPUTER AIDED	L	Т	Р	С	E	1	Тс	tal
	MODELING AND DESIGN	3	1	0	4	70	30	1	00
Objective (s)	Student will Understand the				•				
	1. Understand the basics o			design					
	2. To impart knowledge on								
	3. Recognize and explain the					ties			
	4. Understand and apply va				ations				
	5. Understand various adva	anced m	odeling c	oncepts					
Outcome (s)	Students are able to								
	1. apply design concepts i	n desig	n, analy	sis and o	can visual	lize the m	odels throu	igh the g	Iraphics
	standards 2. implement Various trans	formatio	ne on der	omotric m	odels for m	aninulatio	- -		
	3. recognize various wiref					anipulatio			
	4. apply surface modeling t					parts and i	mplement		
	5. differentiate various soli				.g raileac j				
	6. apply various advanced				calculate	e the in	terference	between	mating
	objects		•						
1.								l Hrs	9
Criteria for sele	ection of cad workstations, Sh	igle de	sign pro	ocess, De	esign crite	eria, Geo	metric mo	odeling	,
Windowing - Vie	totation and Scaling about arbitration and Scaling about arbitration arbitration of the second statement of the second stateme	ns				u sheam	ig, rionio	geneous	>
Windowing - Vie Graphics standa <b>2.</b>	ew ports -Clipping transformation ards: GKS , IGES , PDES and th	ns neir rele					Tota	-	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves	ew ports -Clipping transformation ards: GKS , IGES , PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, N	ns neir rele JRBS.	vance Curve M	ransform	ations			-	
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode	ew ports -Clipping transformation ards: GKS , IGES , PDES and th : Lines, Circles, Ellipse, Conics.	ns neir rele JRBS.	vance Curve M	ransform	ations		Tota	l Hrs	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3.	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Ni eling and its advantages and Lin	ns heir rele JRBS. hitation	vance Curve M	ransform	ations		Tota	l Hrs	
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Ni eling and its advantages and Lin es: Plane Surface, Ruled Surfac	JRBS. nitation: e, Surfa	vance Curve M s	ransform anipulation,	ations ons	d Cylinde	Tota	l Hrs	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Ni eling and its advantages and Lin	JRBS. nitation: e, Surfa	vance Curve M s	ransform anipulation,	ations ons	d Cylinde	<b>Tota</b> Tota Tota r. ing_Techr	l Hrs	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface 4.	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Ni eling and its advantages and Lin es: Plane Surface, Ruled Surfac	JRBS. nitation: e, Surfa	vance Curve M s ace of Re rface Ma	anipulation, anipulation,	ations ons , Tabulate ns , Surfa	d Cylinde ce Model	Tota	I Hrs I Hrs niques	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface 4. Boundary Represent	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Nu eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv	JRBS. nitation: e, Surfa ons ,Su e Solid	Vance Curve M s ace of Re fface Ma Geomet	ransform anipulatio evolution, inipulatio ry (CSG)	ations ons , Tabulate ns , Surfa Modeling	d Cylinde ce Model	Tota Tota Ing Techr	I Hrs I Hrs niques I Hrs	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface 4. Boundary Repre Graph Based M	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Nu eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo	JRBS. nitation: e, Surfa ons ,Su e Solid	Vance Curve M s ace of Re fface Ma Geomet	ransform anipulatio evolution, inipulatio ry (CSG)	ations ons , Tabulate ns , Surfa Modeling	d Cylinde ce Model	Tota Tota r. ing Techr Tota cy Enume	I Hrs I Hrs niques I Hrs ration	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface Synthetic Surface Graph Based M 5.	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Ni eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv lodel, Boolean Models, Instance	JRBS. neir rele nitation: e, Surfa ons ,Su e Solid s, Cell I	vance Curve M s ace of Re rface Ma Geomet Decompo	ransform anipulatio evolution, inipulatio ry (CSG) osition &	ations ons , Tabulate ns , Surfa Modeling Spatial –	d Cylinde ce Model l Occupan	Tota Tota r. ing Techr Tota cy Enume Tota	I Hrs I Hrs hiques I Hrs ration I Hrs	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface Synthetic Surface Graph Based M 5. Feature Based	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Nu eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv	JRBS. nitation: e, Surfa ons ,Su e Solid s, Cell I	vance Curve M s ace of Re rface Ma Geomet Decompo	ransform anipulatio evolution, inipulatio ry (CSG) osition &	ations ons , Tabulate ns , Surfa Modeling Spatial –	d Cylinde ce Model l Occupan	Tota Tota r. ing Techr Tota cy Enume Tota	I Hrs I Hrs hiques I Hrs ration I Hrs	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface Synthetic Surface Graph Based M 5. Feature Based M Modeling Feature	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, NI eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv lodel, Boolean Models, Instance Modeling, Assembly Modeling, C	JRBS. nitations e, Surfa ons ,Su e Solid s, Cell I Concept es	vance Curve M ace of Re fface Ma Geomet Decompo	anipulatio evolution, inipulatio ry (CSG) osition & gn and T	ations ons Tabulate ns , Surfa Modeling Spatial – op down	d Cylinde ce Model Occupan design, P	Tota Tota r. ing Techr Tota cy Enume Tota arametric	I Hrs I Hrs hiques I Hrs ration I Hrs	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface Synthetic Surface Graph Based M 5. Feature Based M Modeling Feature	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Ni eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv lodel, Boolean Models, Instance Modeling, Assembly Modeling, C re recognition, Design by Feature	JRBS. nitations e, Surfa ons ,Su e Solid s, Cell I Concept es	vance Curve M ace of Re fface Ma Geomet Decompo	ransform anipulatio evolution, inipulatio ry (CSG) osition & gn and T Detection	ations ons Tabulate ns , Surfa Modeling Spatial – op down	d Cylinde ce Model Occupan design, P	Tota Tota r. ing Techr Tota cy Enume Tota arametric	I Hrs I Hrs hiques I Hrs ration I Hrs	9
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface Synthetic Surface Graph Based M 5. Feature Based M Modeling Feature	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Ni eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv lodel, Boolean Models, Instance Modeling, Assembly Modeling, C re recognition, Design by Feature	JRBS. nitations e, Surfa ons ,Su e Solid s, Cell I Concept es	vance Curve M ace of Re fface Ma Geomet Decompo	ransform anipulatio evolution, inipulatio ry (CSG) osition & gn and T Detection	ations ons , Tabulate ns , Surfa Modeling Spatial – op down	d Cylinde ce Model Occupan design, P	Tota Tota r. ing Techr Tota cy Enume Tota arametric	I Hrs I Hrs hiques I Hrs ration I Hrs	9 9 9 iational
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface Synthetic Surface Graph Based M 5. Feature Based M Modeling Featur Computer Aideo Text book (s) 1. Ibrahim	ew ports -Clipping transformation ards: GKS , IGES , PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, Ni eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv lodel, Boolean Models, Instance Modeling, Assembly Modeling, C re recognition, Design by Feature d Design of mechanical parts an Zeid, —CAD/CAM, Theory and	URBS. nitation: e, Surfa ons ,Su e Solid s, Cell I Concept es d Interfa Practic	vance Curve M s ace of Re fface Ma Geomet Decompo ual Desi erence D erence D	ransform anipulatio evolution, inipulatio ry (CSG) osition & gn and T Detection To Graw Hill,	ations ons Tabulate ns , Surfa Modeling Spatial – op down by Motior tal hours	d Cylinde ce Model Occupan design, P n analysis to be taug	Tota Tota r. Tota r. Tota v. Tota arametric	I Hrs I Hrs hiques I Hrs ration I Hrs and Var	9 9 9 iational 45
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface Synthetic Surface Graph Based M 5. Feature Based M Modeling Featur Computer Aideo Text book (s) 1. Ibrahim	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, NI eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv lodel, Boolean Models, Instance Modeling, Assembly Modeling, C re recognition, Design by Feature d Design of mechanical parts an Zeid, —CAD/CAM, Theory and /an Dam, Feiner and Hughes, –	URBS. nitation: e, Surfa ons ,Su e Solid s, Cell I Concept es d Interfa Practic	vance Curve M s ace of Re fface Ma Geomet Decompo ual Desi erence D erence D	ransform anipulatio evolution, inipulatio ry (CSG) osition & gn and T Detection To Graw Hill,	ations ons Tabulate ns , Surfa Modeling Spatial – op down by Motior tal hours	d Cylinde ce Model Occupan design, P n analysis to be taug	Tota Tota r. Tota r. Tota v. Tota arametric	I Hrs I Hrs hiques I Hrs ration I Hrs and Var	9 9 9 iational 45
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface Synthetic Surface Graph Based M 5. Feature Based M 5. Feature Based M Modeling Featur Computer Aideo Text book (s) 1. Ibrahim 2. Foley, V	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, NI eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv lodel, Boolean Models, Instance Modeling, Assembly Modeling, C re recognition, Design by Feature d Design of mechanical parts an Zeid, —CAD/CAM, Theory and /an Dam, Feiner and Hughes, –	URBS. nitation: e, Surfa ons ,Su e Solid s, Cell I Concept es d Interfa Practic	vance Curve M s ace of Re fface Ma Geomet Decompo ual Desi erence D erence D	ransform anipulatio evolution, inipulatio ry (CSG) osition & gn and T Detection To Graw Hill,	ations ons Tabulate ns , Surfa Modeling Spatial – op down by Motior tal hours	d Cylinde ce Model Occupan design, P n analysis to be taug	Tota Tota r. Tota r. Tota v. Tota arametric	I Hrs I Hrs hiques I Hrs ration I Hrs and Var	9 9 9 iational 45
Windowing - Vie Graphics stands 2. Analytic curves Synthetic curves Wireframe Mode 3. Analytic Surface Synthetic Surface Synthetic Surface 4. Boundary Represe Graph Based M 5. Feature Based M 5. Feature Based M Modeling Featur Computer Aideo Text book (s) 1. Ibrahim 2. Foley, V Wesley Reference (s)	ew ports -Clipping transformation ards: GKS, IGES, PDES and th : Lines, Circles, Ellipse, Conics. es – Cubic, Bezier, B-Splines, NI eling and its advantages and Lin es: Plane Surface, Ruled Surfac ce - Cubic, Bezier, B-spline, Coo esentation (B-rep) & Constructiv lodel, Boolean Models, Instance Modeling, Assembly Modeling, C re recognition, Design by Feature d Design of mechanical parts an Zeid, —CAD/CAM, Theory and /an Dam, Feiner and Hughes, –	JRBS. nitation: e, Surfa ons ,Su e Solid s, Cell I Concept d Interfe Practic -Comple	vance Curve M s ace of Re frace Ma Geomet Decompo ual Desi erence D ell, Mc C uter Gra	ransform anipulatio evolution, inipulatio ry (CSG) osition & gn and T <u>Detection</u> To Graw Hill, phics Prir	ations ons Tabulate ns , Surfa Modeling Spatial – op down by Motior tal hours	d Cylinde ce Model Occupan design, P n analysis to be taug	Tota Tota r. Tota r. Tota v. Tota arametric	I Hrs I Hrs hiques I Hrs ration I Hrs and Var	9 9 9 iational 45

CBIT	Autonomous Regulation		Sen	nester-1			AY - 200	6-17
Department	Mechanical Engineering	Progra		ode & Na	ame		M.E. CAD	
Course Code	Course Name	Hours	/Week		Credit	Maximu	ım Marks	
16MEC 103	COMPUTER INTEGRATED	L	Т	Р	С	E	I	Total
	MANUFACTURING	3	1	0	4	70	30	100
Objective (s)	<ol> <li>To identify the main e</li> <li>To use computer in t computers to all the unnecessary costs.</li> <li>To study about computer</li> <li>To obtain an overview collection, networks, n floor operation</li> <li>To describe the integri</li> </ol>	he area manufa uter aide v of con machine ation of	of man cturing of ed plann nputer te e contro	ufacturin machines ing, artific echnologi I, as they	g to reduces and incr cial intellig es includi apply to	ce manua rease the gence and ng compu factory r	al processin productivir l expert sys uters, datal nanageme	ng and linking ty, reduce the stems base and data nt and factory
	<ol> <li>the basic of CIM, Cocycle, collaborative p</li> <li>to create the manufaction of computer aided product design, definition of computer aided product design.</li> <li>the CIM technologies manufacturing system</li> <li>the importance of protection of the importance of protection of the concepts life cycle and process</li> </ol>	roduct of turing d esign fo cess plas s such s such s rinciple ifferent of lean	developn latabase or manuf anning as cell s of ne models manufa	nent and stor acturabili ular man tworking, of CIM cturing, a	e and retr ty and de uufacturing topology ugile & we	ieve data sign for a g, shop-fl y, networ b based r	from datab ssembly co oor contro k devices	base bacepts, types I and flexible , selection of
1.		planac	ang trie	developi		produot.	Total	Hrs 9
Engineering: Engineering, C Concurrent Er (PLM), Collabo <b>2.</b> Introduction, M models, Datat (SQL): Basic Language (sto	damentals of Communication: Definition, Sequential Engine Characteristics of concurrent En- orative Product Development Manufacturing Data: Types, so base Management System, DI structure, Data definition Langure, retrieve, update, delete). Illo bowledge Base Query Language	ering V ngineeri ted Pro urces; I 3MS A guage ustratio	Versus ( ing, Fran oduct De Databas rchitectu (Create, n of Cre	Concurree mework f evelopme e Termin re, Quer Alter, D ating and	nt Engine or integra nt(IPD), I ology, Da y Langua rop, Trur I Manipula	eering, B ation of Li Product L atabase r age, Struct acate, Vie ating a M	enefits of fe-cycle ph ife-Cycle I <b>Total</b> equiremen ctural Que ew), Data anufacturir	Concurrent hases in CE, Management Hrs 9 ts, Database ry Language Manipulation ng Database.
	Product Data Management (PD	M), Adv	/antages	of PDM.				
(DFM): Compor process plan, Planning. Mate Manufacturing: Group Analysis Logging and A Flexible Manufa Linear Single M Problems of FM <b>4</b> . Introduction to N Selection of Ne Signaling meth Interconnection	Needs of the market, Design nent Design, Design for Assemb Variant and Generative Proc Prial Requirements Planning Design of Cellular Manufactur, Similarity Coefficients-Based Acquisition, Automated Data Co acturing Systems: Physical Con Machine Layout, Circular Mac IS. FMS benefits Networking, Principles of Netwo twork Technology: Communication and Devices, Network Performation SPRIT-CIM OSA Model, NIST-A	oly. Cor ess Pla (MRP), iring Sy Approa Collectic mponer hine La rking, N tion me and P ance. Fi	nputer-A anning, Manuf ystems, aches. E on, Prog nts of ar ayout, C letwork dium, N rotocols: ramewor	ided Pro Feature acturing Cell For valuatior prammable FMS. T cluster M Cluster M	cess Plar Recognit Resource mation A of Cell le Logic ypes of achine L ogy, Type opology, I lodel, M. erprise-wi	nning: Bas tion in C e Plannir pproache Design. S Controlle Flexibility, ayout, Lo s of Netw Medium a AP & T de Integra	sic Steps ir computer-A ng (MRP es: Machin Shop-floor rs, Sensor , Layout C pop Layout <u>Total</u> rorks: LAN, iccess cont OP, TCP/	nufacturability developing a ided Process –II), Cellular e–Component Control: Data Technology. onsiderations: t; Operational <u>Hrs 9</u> MAN, WAN; trol Methods,

5. Total Hrs	9
Lean Manufacturing: Definition, Principles of Lean Manufacturing, Characteristics of Lean Manufacturing, Va	alue of
Product, Continuous Improvement, Focus on Waste, Relationship of Waste to Profit, Four Functions of	f Lean
Production, Performance Measures, The Supply Chain, Benefits of Lean Manufacturing. Introduction to Ag	ile and
Web Based Manufacturing systems.	
Total hours to be taught	45
Text book (s)	
1. S.Kant Vajpayee: Principles of Computer Integrated Manufacturing, Printice-Hall India	
2. Singh: Systems Approach to Computer Integrated Design and Manufacturing- John Wiley	
Reference (s)	
1. P.Radhakrishnan, S.Subramanyam: CAD/CAM/CIM, New Age International	
2. Alavudeen, Venkateshwaran: Computer Integrated Manufacturing, Printice-Hall India	

CBIT	Autonomous Regulation		Sem	ester-1			AY - 2006	5-17	
Department	Mechanical Engineering	Progra		ode & Na	ame		M.E. CAD		
Course Code	Course Name		/Week		Credit	Maximu	m Marks		
16MEC 104	COMPUTER AIDED	L	Т	Р	C	E	Ι	To	tal
	MECHANICAL DESIGN AND ANALYSIS	3	1	0	4	70	30	10	00
Objective (s)	<ol> <li>To develop the necess</li> <li>To achieve fundamen loading and boundary</li> <li>To Understand design</li> </ol>	tal unde conditio	erstandir ons	ng of the	theory of	bending o	of flat plate	es with v	/arious
	approaches 4. To enable the importa concepts of matrix alg 5. To understand the diff 6. To understand the fur	ebra erent m ndamer	iode ext	raction m epts varie	ethods in ous algori	vibrations thms used	; d for dynai	mic ana	lysis
Outcome (s)	<ol> <li>Ability to apply know stresses &amp; strains in p</li> <li>Demonstrate the abili bending applications</li> <li>An ability to design a</li> </ol>	oressure ity to ic	e vessel lentify, f	s ormulate	and solv	ve problen	ns for a g	iven fla	t plate
	<ul> <li>4. Students are able to u</li> <li>5. Students will understa</li> <li>6. Student will understa</li> <li>analysis problems</li> </ul>	ndersta nd diffe	ind and rent mo	solve var de extrac	ious Eiger tion meth	n value ar ods to cal	nd Eigen ve culate freq	ectors uencies	5
1.							Total		9
	sure Vessels: Introduction and o els, shrink fit stresses in built up icance.								
2.							Total		9
directions, The	at plates: Introduction, Bending ermal stresses in plates, Bendi of constant thickness								
3.							Total	Hrs	9
Fracture Mecha rate of DCB spo plastic analysis stress strain rela	nics: Introduction, Modes of fra ecimen; Stress Intensity Factor through J-integral method: R ation, Strain Energy Release Ra	: SIF's elevanc	for edge e and s	e and cei scope, D	ntre line o	crack, Fra	ase rate, E cture toug ral, Path i	nergy r hness, ndepen	elease Elastic dence,
4. Figon Volue F	Problems: Properties of Figer	volues	and E		tore Tore		Total		9
lateral vibration	Problems: Properties of Eigen n, Sturm sequence. Subspace it	eration	and Lar	-			-		,
Eigen value proi	blems applied to stepped beams		a15				Total	Hre	9
Dynamic Analy Mode superpos Rayleigh damp	vsis: Direct integration method, ( sition, Single degree of freedom bing, Condition for stability. ated algorithms and codes to be	system	n respon	se, Multi udents)	degree of	f freedom	, Newmark system res	< metho	d,
				То	tal hours	to be taug	ht		45
Pvt. Ltd	. Harvey, Pressure Vessel Desig ., 1969 h Kumar, Elements of Fracture	-						West P	ress
	i, Computer Aided Mechanical I I., Finite Element Procedures, P					w Hill-199	2		

BIT         Autonomous Regulation         Semester-1         AY - 2006-17           Department         Programme Code & Name         M.E. CAD/CAM & Thermal									
Department	Mechanical Engineering	Progra	amme C	ode & Na	ame	M.E. CA Enginee		Thermal	
Course Code	Course Name	Hours	/Week		Credit		m Marks		
16MEC 105	FINITE ELEMENT	L	Т	Р	C	E	I	Tota	al
	TECHNIQUES	3	1	0	4	70	30	100	)
Objective (s)	1. Identify mathematical mo						blems		
	<ol> <li>Enable the students to fo</li> <li>Enable the students to perform the students to per</li></ol>						Element A	nalvsis	
	software		Ingineen	ing sinia		ng i inite		anary 515	
Outcome (s)	Students are able to								
	1. implement finite element			axial and	d quadrati	c elemen	ts and sol	ve proble	ems
	<ul><li>with hand calculations nu</li><li>formulate numerically the</li></ul>			nd frame	elements	and solve	e for defle	ntion stra	ins
	and stresses	5 11 400,	boama		olomonito				
	3. formulate numerically the								
	elements then solve for o								
	<ol> <li>apply FE formulations to heat flux in slabs, walls a</li> </ol>			1D and	2D eleme	nts and s	olve for tel	mperatur	e and
	5. apply FE formulations to			sis of 1D	and 2D e	lements a	and solve t	for eigen	
	values and eigen vectors	s in bar	s and be	ams				Ū	
	6. apply FE formulations to	o 3D so	lids, plat	es and fo	or non line	ar problei			
	LMES AND MODELING Finite Element Method of solving	field n	roblome	Stroce o	nd Equilib	rium Rou	Tota		9
	ment relations. Stress-strain rela		iobiems.	Sliess a		mum. Bot	unuary cor	iuitions.	
	al Problem: Finite element mo								
	y approach: Assembly of Glo			natrix ar	nd load v	ector. Fi	nite elem	ent equa	tions,
	undary conditions. Quadratic sha	ape fun	ctions				Tata		•
	F TRUSSES AND FRAMES e truss with number of unknown	s not e	vceeding	n two at e	ach node		Tota	Hrs	9
	ms: Element stiffness matrix for		-				le for bear	n elemer	nt
	es with two translations and a ro								
	SIONAL STRESS ANALYSIS						Tota		9
Finite element	modeling of two dimensional :	stress a	analysis	problem	s with cor	nstant stra	ain triangles	treatme	nt of
	litions. Two dimensional four no our noded isoparametric eler								
	solids subjected of axisymmetr						element	modelinų	y Ui
Convergence r	equirements and geometric isot	ropy	•	•					
	SFER PROBLEMS AND DYNA						Tota		9
	at transfer analysis: One dimen							ion analy	sis of
	e dependent field problems: App is: Formulation of finite element							ad boom	
	gen values and Eigen vectors, A								
Element Analys									
	INSIONAL PROBLEMS IN SRE						Tota	Hrs	9
	ormulation of three dimensional							-::	
Bending of elast analysis softwar	tic plates: Thin and Thick plate for	ormulat	tions, Int	roduction	to non-lir	near probl	ems and I	-inite Ele	ment
analysis soltwar	e 5			То	tal hours	to he taur	nht		
Text book (s)				10			,		
1. Tirupath	ni R Chandrupatla and Ashok.D. ndia, 2004	Belegu	undu, Int	roduction	of Finite	Element i	n Enginee	ring. Prei	ntice
2. Rao S.S	S., The Finite Element Methods in								
	Hutton, " Fundamentals of Finit	e Elem	ent Anal	ysis", Tat	a McGrav	v Hill,2003	3		
References:	Cook "Conconte and annliactic	ne of fi	nito alam	ent and			w and con	e 2000	
	Cook , "Concepts and applicatio J.N., An Introduction to Finite El							3,2009	
3. K.J Bat	the, Finite element procedures, 2	2 <sup>nd</sup> Edn	Prentice	Hall of I	ndia.2007	pariy, 10			
	D. L. (2011). First course in finite						outhWeste	ern, Ceng	age
Learnin	g.								

CBIT		Autonomous Regulation								
Depa	rtment	Mechanical Engineering	Program		de & l	Name	M.E. Therr	mal Er	ngineerir	ng
			Semest							
Cours	se Code	Course Name	Hours/ V	Veek		Credit	Maximum	Marks		
			L	Т	Р	С	E	I		otal
16ME	EC 205	COMPUTATIONAL FLUID DYNAMICS	3	1	0	4	70	30	1	00
Objec	ctive (s)	1. To understand the basic equ								
		2. To make the students to lear								
		<ol> <li>To study various types of gri</li> <li>To learn the Crank-Nihcolso</li> </ol>						on.		
		5. To prepare the students with								
		6. To enkindle the students im			Joidoi		mothodo			
Outco	ome (s)	Students will be able to								
		1. derive CFD governing equat					hooleward a	nd oo	ntor diff.	
		<ol> <li>apply elliptical, parabolic and methods .</li> </ol>	и пурепро		is and	iorwaru,	backward a	and ce	nter am	erence
		3. understand errors, stability,	consisten	icv and	devel	op O H a	and C arid a	eneral	ted mod	els
		4. evaluate the use of Crank-N								
		5. analyze problem by Jacobi,								
		6. solve conduction and convect		lems us	sing F	VM				
1	BASIC E	QUATIONS IN FLUID DYNAMIC	S					To	tal Hrs	9
Conti	nuity, Mom	entum and Energy equations, Na	vier Stoke	es equa	ations,	Reynold	ls and Favre	avera	aged N -	- S
equat	tions. Introd	duction to turbulence, Turbulence	models-n	nixing l	ength	model, K	ε turbulenc	e Moo	del.	
2	CLASSIF	ICATION OF PDEs						Tota	al Hrs	9
Ellipti	c, paraboli	c and hyperbolic equations, Initial	and bour	dary co	onditio	ons.				
		te difference methods - forward,					e.			
3	GRID GE	NERATION						Tot	al Hrs	9
		<ul> <li>Types of grid O,H,C. Coordinate</li> </ul>				uctured g	grid generati	on, Er	rors,	
Cons	istency, Sta	ability analysis by von Neumann.	Converge	nce cri	teria.					
4	FINITE D	FFERENCE SOLUTIONS						Tot	al Hrs	9
-		solutions-Parabolic PDEs – Eu	ler. Crank	Nicho	lson.	Implicit r	nethods. El			
		ADI, methods. FD- solution for								
methe	od & MAC	method								
5		OLUME METHOD							al Hrs	9
		Finite volume method. Finite volu								
		on algorithm for pressure velocit	y coupling	g in ste	eady fi	ows. Us	e of Stagge	erea g	rias SIIV	IPLE
Algor	iumi.				Tota	l houre to	be taught	1	45	
Toyt	book (s)				TOLA				45	
1	DOOK (3)									
	John D A	nderson, 'Computational Fluid Dy	ynamics',	Mc Gra	aw Hill	, Inc., 20	15.			
				<i>"</i>						
2		teeg - 2015, Malala Shekara, Intr								
3	Muralidh 2003	ar K, Sundararajan T, 'Computati	onai Fiuid	now ar	ia Hea	ai transfe	er, Narosa F	rublisľ	iing Hou	ise,
4		S.V, 'Numerical Heat transfer an	d Fluid flo	w', Her	nisphe	ere Publi	shing Comp	any, N	lew Yor	k,1980

BIT	Autonomous Regulation		Sem	ester-1			AY - 2006	5-17	
Department	Mechanical Engineering	Progra		ode & Na	ame	M.E.C.	AD/CAM		
Course			/Week		Credit		um Marks		
Code	Course Name		,		Crown				
16MEE101	FAILURE ANALYSIS AND	L	Т	Р	С	E		To	tal
	DESIGN	3	1	0	4	70	30		00
Objective (s)	<ol> <li>To understand importan</li> <li>To understand buckling</li> </ol>					ternal pre	11		
Outcome (s)	<ol> <li>Graduate will be able to understa</li> <li>design methodology and</li> <li>different creative and inv</li> <li>different types of design</li> <li>concept of buckling of cy</li> <li>the fundamentals of frac</li> <li>prediction and various si</li> <li>basic crack propagation</li> <li>fracture toughness of we</li> </ol>	d variou ventive proces ylinders ture, fra tress th conce	problem s, conce under v acture ty eories o pt, conc	solving te epts of rel arious loa pes and o f failure v	echniques iable and ading con concepts essels	s safe desi ditions of fatigue	ign crack grov under com	bined lo	bading,
1.							Total		10
for design- ( Identification	design- The design process-Con Computer Aided Engineering –( – Competition Bench marking. I ications- Human Factors in Design	Concurr dentific	ent Engation of	gineering custome	– Produer needs-	ict and	process c	vcles –	Market
2.							Total	Hrs	10
<ul> <li>Simulation –</li> <li>Buckling phe walled cylind</li> </ul>	ecture-Configuration Design-Para - Design for Reliability –Introduction nomenon – Elastic Buckling of cir ers or tubes under external press ned External pressure and axial lo	on to Ro cular rii ure – E	bust De	sign-Faile	ure mode under ext	Effect Ar	nalysis <b>Total</b> ssure – col	Hrs lapse of	10 f thick
4.	ied External precedie and axial le	Juding					Total	Hrs	10
Failure analys types in tensic	is and determination of stress pat on—Fatigue crack growth– Fatigue -Thermal stress fatigue	terns fro e life pro	om plast ediction-	ic Flow o Cumulat	bservatio tive fatigu	ns – Dyna e damage	amic loadin	g– Frac	
5.							Total	Hrs	10
	Through cracks emanating from h ding-Fatigue crack growth binder- s								/ice
				То	tal hours	to be tau	ght		
Intern 2. Pahl, G	George E., —Engineering De ational Editions, Singapore, 2000. , and Beitz, W.,I Engineering Des					•	pproachll,	McGrav	w Hill,
References: 1. David Publis 2. Presh	Broek, IElementary Engineerin her, 1978 ant Kumar, —Elements of Fractur F. Harvey, Theory and Design of I	g Fract	ture Me nanicsII,	chanics - Wheeler I	—, Fiftho Publishing	ff and N g, 1999			onal

CBIT	Autonomous Regulation		Sem	ester-1			AY - 20	06-17	
Department	Mechanical Engineering	Proar	amme C	ode & Na	ime	M.E. CA	AD/CAM		
Course Code	Course Name		/Week	00.0 0.110	Credit		m Marks		
16MEE 102	INTEGRATED	L	Т	Р	C	E			otal
	MECHANICAL DESIGN	3	0	0	3	70	30		.00
Objective (s)	1. To know the importance of I		-	-	-	-			
	<ul> <li>components</li> <li>2. To learn design criteria of m</li> <li>3. To learn application of princ</li> <li>4. To provide the design conce equipments for dynamics and</li> <li>5. To provide the students the plants and Construction fields</li> </ul>	iples to epts of therma knowle	design machine l aspect edge of c	different ( tools, au s. lesign of I	gears and tomobiles Mechanic	l gear box s and meo al handlin	kes. chanical ł ng equipn	nandling nents like	epower
Outcome (s)	<ol> <li>Be able to know the importa and manufacturing</li> <li>Be able to do the complete design and machining allowan</li> <li>Be able to do the design and</li> <li>Be able to do the design of l equipments for dynamics and</li> <li>Be able to design of Mechar</li> </ol>	design ces aco d analy brakes therma	and ana cording t rsis of Di of mach I aspects	lysis of sh o standar fferent ge ine tools, s.	nafts, bea ds and re ars and g automob	rings and equiremer jear boxe	casings nts. s.	by consi	dering
1.							Tot	al Hrs	9
<ul> <li>Ductile vs. b</li> <li>Analysis and I</li> <li>for rigidity.</li> <li>2.</li> </ul>	ses – Transformation Matrix – Pr prittle component design - Design of shafts for different app gear tooth action – Gear correction	lication	ns – inte	grated de	sign of sh	naft, beari	ng and c		
- Component d	lesign of spur, helical, bevel and and multi-speed gear boxes – a	worm g	gears – I	Design for	r sub asse			design o	of
3.							Tot	al Hrs	9
	d thermal aspects of vehicle nd mechanical handling equipme		ing –	Integrated	d design	of brak	kes for	machine	tools,
4.								al Hrs	9
Integrated Desig	gn of systems consisting of shaft eel etc. Example - Design of Elev	t, beari vators,	ngs, spri Escalato	ors, Gear	Box, Valv	e gear M	e, chain, p echanisn	oulleys, C	Cam &
				To	tal hours	to be tau	ght		
Text book (s)		_							
2. Newcoml Edition,19 3. Maitra G 4. Shigley, 5. Prasad. I 6. Alexandr	Machine Design – An Integrated b, T.P. and Spur, R.T., —Automo 975. .M., —Hand Book of Gear Desig J.E., —Mechanical Engineering L. V., —Machine DesignII, Tata M rov, M., Materials Handling Equip ol, A., Materials Handling Handbo	nll, Tat Design AcGrav	rakes an a McGra ll, McGra v Hill, Ne , MIR Pu	d Braking w Hill, 19 w Hill, 19 w Delhi, <sup>-</sup> iblishers,	9 Systems 985 986 1992 1981	⊧II, Chapm	nan and F	lall, 2 <sup>nd</sup>	
	Books: n., —Design Data Bookll, Kalaika K. and Narayana Iyengar, —Mac								

Dementers	Autonomous Regulation		Sem	ester-1			AY - 200	6-17	
Department	Mechanical Engineering	Progra	amme C	ode & Na	ame		M.E. CAD	D/CAM	
Course Code	Course Name	Hours	/Week		Credit	Maximu	m Marks		
16MEE 102		L	Т	Р	C	E	I	То	otal
	ROBOTIC ENGINEERING	3	0	0	3	70	30	10	00
Objective (s)	<ul> <li>To be familiar with the brief</li> <li>To give the student familiari</li> <li>To give knowledge about ro</li> <li>To give knowledge about va</li> </ul>	ties with bot end	n the kin effector	ematics or rs and the	of robots. eir design		ıts.		
Outcome (s)	<ol> <li>Students will be equipped w</li> <li>Students will have good knd</li> <li>Understand different orienta</li> <li>Students will be familiarized</li> <li>Able to solve the static and</li> <li>Students will be equipped w</li> <li>concept of robot vision</li> </ol>	rith the owledge itions of with th dynami	brief hist about r f robot e kinem c analys	tory of rol obot end atic motic is of Plar	bot config effectors ons of rob nar robots	uration , s and their ot and	ubsystem design co pplication	ncepts. s in robo	
1.							Tota	l Hrs	9
freedom of robo and Different t actuators, applie <b>2.</b>	ypes of robots, Overview of rob ots, Robot configurations and co ypes of grippers, vacuum and cations of robots, specifications	ncept c other of differ	of works methods ent indu	pace, Me s of gripp strial robe	chanisms oing. Pne ots.	and transeumatic, h	smission, hydraulic a	End effe and elec	ectors ctrical 9
	ces, Euler angle and RPY re								
Hartenberg not kinematics.	ation, representation of absolu	ite pos	ition and	d orienta	tion in te	erms of jo	oint paran	neters,	direct
3.					-		Tata		
							l ota	l Hrs	9
interpolation, ta	atics, inverse orientation, inver sk space interpolation, executin Tangent Bug Algorithm, The Inc	ng user	specifie	ed tasks,	sensor b		jectory P	lanning:	joint
interpolation, ta	sk space interpolation, executir	ng user	specifie	ed tasks,	sensor b		jectory P	lanning: ing: The	joint
interpolation, ta Algorithm, The 4. Static force ana Euler formulation feedback, acture	sk space interpolation, executir	ng user rementa anar rot oots, , I	specifie al Voron pots, Dyr ndepend	ed tasks, oi Graph. namic ana dent joint	sensor b alysis usir control, F	ng Lagran D and PI	ijectory P tion plann <b>Tota</b> gean and D trol	lanning: ing: The I Hrs Newton	joint e Bug 9
interpolation, ta Algorithm, The 4. Static force ana Euler formulatic feedback, actua 5.	sk space interpolation, executir Tangent Bug Algorithm, The Inc lysis of RP type and RR type pla ons of RR and RP type planar rol ator models, nonlinearity of man	ng user rementa anar rok pots, , I ipulator	specifie al Voron pots, Dyr ndepend models	ed tasks, oi Graph. namic ana dent joint , force fe	sensor k alysis usir control, F edback, h	ng Lagran D and PII Nybrid cont	ijectory P tion plann <b>Tota</b> gean and D trol <b>Tota</b>	lanning: ing: The I Hrs Newton	joint e Bug <b>9</b>
interpolation, ta Algorithm, The 4. Static force and Euler formulation feedback, actua 5. Sensors and co sensors, force s Robot vision: im	sk space interpolation, executir Tangent Bug Algorithm, The Inc lysis of RP type and RR type pla ons of RR and RP type planar rol ator models, nonlinearity of man introllers: Internal and external s sensors, laser range finder nage processing fundamentals for	ng user rementa anar rok oots, , I ipulator ensors, or robot	specifie al Voron pots, Dyr ndepend models position ic applic	ed tasks, oi Graph. namic and dent joint , force fe n, velocity ations, im	sensor b alysis usir control, F edback, h r and acce	based moto ng Lagran 2D and PII bybrid conto eleration s	ijectory P tion plann <b>Tota</b> gean and C trol <b>Tota</b> ensors, pr d preproce	lanning: ing: The I Hrs Newton I Hrs roximity essing.	joint e Bug 9
interpolation, ta Algorithm, The 4. Static force and Euler formulation feedback, actua 5. Sensors and co sensors, force s Robot vision: im	sk space interpolation, executir Tangent Bug Algorithm, The Inc lysis of RP type and RR type pla ons of RR and RP type planar rol ator models, nonlinearity of man introllers: Internal and external s sensors, laser range finder	ng user rementa anar rok oots, , I ipulator ensors, or robot	specifie al Voron pots, Dyr ndepend models position ic applic	ed tasks, oi Graph. namic and dent joint , force fe n, velocity ations, im c image m	sensor b alysis usir control, F edback, h and acce nage acqu	based moto ng Lagran 2D and PII bybrid conto eleration s	ijectory P tion plann <b>Tota</b> gean and D trol <b>Tota</b> ensors, pr d preproce on featur	lanning: ing: The I Hrs Newton I Hrs roximity essing.	joint e Bug 9
interpolation, ta Algorithm, The 4. Static force ana Euler formulation feedback, actua 5. Sensors and co sensors, force se Robot vision: im Segmentation a	sk space interpolation, executir Tangent Bug Algorithm, The Inc lysis of RP type and RR type pla ons of RR and RP type planar rol ator models, nonlinearity of man introllers: Internal and external s sensors, laser range finder nage processing fundamentals for	ng user rementa anar rok oots, , I ipulator ensors, or robot	specifie al Voron pots, Dyr ndepend models position ic applic	ed tasks, oi Graph. namic and dent joint , force fe n, velocity ations, im c image m	sensor b alysis usir control, F edback, h and acce nage acqu	based moto ng Lagran 2D and PII bybrid conto eleration so uisition and and based	ijectory P tion plann <b>Tota</b> gean and D trol <b>Tota</b> ensors, pr d preproce on featur	lanning: ing: The I Hrs Newton I Hrs roximity essing.	joint e Bug 9
interpolation, ta Algorithm, The 4. Static force ana Euler formulatic feedback, actu 5. Sensors and co sensors, force s Robot vision: im Segmentation a Text book (s) 1. Nagrath	sk space interpolation, executir Tangent Bug Algorithm, The Inc lysis of RP type and RR type pla ons of RR and RP type planar rol ator models, nonlinearity of man introllers: Internal and external s sensors, laser range finder mage processing fundamentals for and region characterization object and Mittal, —Robotics and Contr	anar rok oots, , I ipulator ensors, or robot et recog	specifie al Voron ndepend models position ic applic nition by	ed tasks, oi Graph. namic ana dent joint , force fe n, velocity ations, im <u>r image m</u> To aw-Hill, 2	sensor b alysis usin control, F edback, h r and acce nage acqu natching a tal hours 003	pased mot ng Lagran PD and PII pybrid cont eleration s uisition and and based to be taug	ijectory P tion plann gean and D trol ensors, pr d preproce on feature ght	lanning: ing: The I Hrs Newton I Hrs roximity essing.	joint e Bug 9
interpolation, ta Algorithm, The 4. Static force ana Euler formulation feedback, actua 5. Sensors and co sensors, force as Robot vision: im Segmentation as Text book (s) 1. Nagrath a	sk space interpolation, executir Tangent Bug Algorithm, The Inc Ilysis of RP type and RR type pla ons of RR and RP type planar rol ator models, nonlinearity of man introllers: Internal and external s sensors, laser range finder mage processing fundamentals for and region characterization object	anar rok oots, , I ipulator ensors, or robot et recog	specifie al Voron ndepend models position ic applic nition by	ed tasks, oi Graph. namic ana dent joint , force fe n, velocity ations, im <u>r image m</u> To aw-Hill, 2	sensor b alysis usin control, F edback, h r and acce nage acqu natching a tal hours 003	pased mot ng Lagran PD and PII pybrid cont eleration s uisition and and based to be taug	ijectory P tion plann gean and D trol ensors, pr d preproce on feature ght	lanning: ing: The I Hrs Newton I Hrs roximity essing.	joint e Bug 9

CBIT	Autonomous Regulation		Sem	ester-1			AY - 200	6-17	
Department	Mechanical Engineering	Progr	amme C	ode & Na	ame		M.E. CAD		
Course Code	Course Name		/Week		Credit	Maximu	m Marks		
16MEE 103	PROGRAMMING	L	Т	Р	С	E	I	То	otal
	METHODOLOGY AND	3	0	0	3	70	30	10	00
	DATA STRUCTURES	ļ., ,							
Objective (s)	To improve logical thir				ام ام ممار				
	<ul> <li>To encourage the stud engineering Problems</li> </ul>		use their	own coo	to solve	mechani	cal		
Outcome (s)	1. Different types of data stora		their str	uctures					
Outcome (3)	2. Implementing the concepts								
	3. Apply different sorting techr				ineerina A	Applicatio	ns		
	4. Classify the different Data S				,	+ F			
	5. differentiate between Linked			d queues	;				
	6. Understand the concept of	Trees a	nd their	traversals	s				
1.							Tota		9
	Methodology: Introduction, Alg	gorithm,	Data F	low Diag	rams, De	cision Tre	e, Decisio	on Table	e and
	roject Development.								
2.		· _		0			Tota		9
	in 'C': Data types & Memory								
<b>3.</b>	ures, Functions, Dynamic Memo		ation ar	ia Simple	program	s in Mech	Total		y. 9
	earching Techniques: Selection	on sort	Quick	sort Rac	liv sort H	loon sort			-
	d Applications in Mechanical En			50H, Hat		10ap 3011			Jinary
4.		3	-3				Tota	Hrs	9
Data Structure	s: Classification of Data Structu	res, De	finitions	of Linked	l Lists, Do	uble Link	ed Lists, S	tacks a	nd
	ions and Implementations of Sta	ack, Qu	eues an	d Linked	List. Gen	eral and M	/lechanica	l Engine	ering
Applications									-
5.							Tota		9
	Structures: Tree, Basic Termi					on Binary	tree, Tree	travers	als,
Graph, Graph re	epresentation Adjacency matrix,	Adjace	ncy List				wh t		
Taythealt (a)				10	tal hours		grit		
Text book (s)	ael Schneider, Steven C.Bruel		noonto	in Data	Structure	o and Si	ftworo		
Develop	oment", Jaico Publishing House,	2002	•						
2. Kernigh	an B.W, Ritchie D.M, — <i>The C F</i>	Progran	nming La	anguage"	, 2 <sup>na</sup> Editi	on, Prenti	ce-Hall of	India, 2	003
References:	$\sim$								
	_, Bruce RL, Cloris Lt, <i>—Data S</i>	tructure	s and P	rogram D	esian in (		991		
	W Stress Analysis of Fibre Re							8	

- Hyer, M.W., Stress Analysis of Fibre Reinforced Composite Materials, Mc Graw Hill Co., 1998.
   Trembly and Sorenson, —An Introduction to Data Structures with application", McGraw Hill, 1984

6. Prem Kumar Gupta, "Operations Research", S Chand publications, 2008

CBIT	Autonomous Regulation	Semester-1 AY - 2006-17							
Department	Mechanical Engineering	Progra	amme C	ode & Na	ame	1	M.E. CAD	D/CAM	
Course Code	Course Name	Hours	/Week		Credit	Maximu	um Marks		
16MEE105	VIBRATION ANALYSIS	L	Т	Р	С	E	I	Tot	tal
	AND	3	0	0	3	70	30	10	
	CONDITION MONITORING	-	•						
Objective (s)	To familiarization with								
	<ul> <li>To apply the vibration</li> </ul>						inery		
Outcome (s)	1. Understand the Causes of V								
	2. Understand Single degree a								
	transient characteristics of vib		imple ha	armonic n	notion, pe	riodic mo	tion, peak	to	
	Peak,RMS and average value								
	3. Vibration measuring instrum			nd record	ing to eler	ments, fre	equency ar	nalysis	
	and filters, Vibration limits and								
	4. Know and be able to explain								
	<ul><li>5. Be aware of some methods</li><li>6. Appreciate and understand</li></ul>						tural baaltk	_	
	monitoring and vibration- base								
1				ntoning, r	tiow the g	eneral st	Total		9
1.	ects of vibration. Vibrations of Si				o and Mu	lti Dograc			9
	y state and transient characteris			NO Degre		ili Degree		11	
	,								
2.	Condition Monitoring Eailure two	os inve		and occ		Causas	Total	Hrs	9
2. Introduction to Characteristics	Condition Monitoring, Failure typ of vibration – SHM, Periodic mo d logarithmic scales and phase a	tion, Dis	estigatior				of failure,		9
2. Introduction to Characteristics		tion, Dis	estigatior				of failure,	peak &	9
2. Introduction to Characteristics RMS, linear and 3. Vibration meas	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr	tion, Dis angle	estigation splacem	ent, Velo	city and a	cceleratic	of failure, on Peak to <b>Total</b>	peak & Hrs	9
2. Introduction to Characteristics RMS, linear and 3. Vibration meas	of vibration – SHM, Periodic mo d logarithmic scales and phase a	tion, Dis angle	estigation splacem	ent, Velo	city and a	cceleratic	of failure, on Peak to <b>Total</b>	peak & Hrs and rec	9
2. Introduction to Characteristics RMS, linear and 3. Vibration mease elements. Vibra 4. Condition Monir systems, vibrat	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr	tion, Dis angle ransduc	estigation splacem ers, sig ency ana	ent, Velo nal conc	litioning e ers, Vibra	cceleratic elements.	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act	peak & Hrs and rec	9 ording
2. Introduction to Characteristics RMS, linear and 3. Vibration mease elements. Vibrat 4. Condition Monir systems, vibrat techniques	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr ation meters and analyzers toring through vibration analysis.	tion, Dis angle ransduc	estigation splacem ers, sig ency ana	ent, Velo nal conc	litioning e ers, Vibra	cceleratic elements.	of failure, on Peak to <b>Total</b> Display <b>Total</b> ature of act nt monitori	peak & Hrs and rec Hrs tive ng	9 ording 9
2. Introduction to Characteristics RMS, linear and 3. Vibration measelements. Vibra 4. Condition Monifisystems, vibratitechniques 5.	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr tion meters and analyzers toring through vibration analysis. tor limits and standards. Contam	tion, Dis angle ransduc Freque hinant a	estigation splacem ers, sig ency ana nalysis,	ent, Velo nal conc Ilysis, Filt SOAP ar	city and a litioning e ers, Vibra nd other co	cceleratic elements. tion signa	of failure, on Peak to <b>Total</b> Display <b>Total</b> ature of act of monitori	peak & Hrs and rec Hrs tive ng Hrs	9 ording 9 9
2. Introduction to Characteristics RMS, linear and 3. Vibration meas elements. Vibra 4. Condition Moni systems, vibrat techniques 5. Special vibratio	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr ation meters and analyzers toring through vibration analysis.	tion, Dis angle ransduc Freque ninant a ge in so	ers, sig ency ana nalysis,	ent, Velo nal conc llysis, Filt SOAP ar thod, Ulti	litioning e ers, Vibra ad other co rasonic m	tion signation easuremode	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act nt monitorio <b>Total</b> ent method	peak & <u>Hrs</u> and rec <u>Hrs</u> ive ng <u>Hrs</u> d, Shock	9 ording 9 9 s pulse
2. Introduction to Characteristics RMS, linear and 3. Vibration meas elements. Vibra 4. Condition Monir systems, vibrati techniques 5. Special vibratio measurement,	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr ation meters and analyzers toring through vibration analysis. ion limits and standards. Contam	tion, Dis angle ransduc Freque ninant a ge in so	ers, sig ency ana nalysis,	ent, Velo nal conc llysis, Filt SOAP ar thod, Ultr um analy	city and a litioning e ers, Vibra nd other co rasonic m sis, Moda	tion signa elements. tion signa ontaminal easuremo I analysis	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act nt monitori <b>Total</b> ent methoo s, critical s	peak & <u>Hrs</u> and rec <u>Hrs</u> itive ng <u>Hrs</u> d, Shock peed an	9 ording 9 9 s pulse
2. Introduction to Characteristics RMS, linear and 3. Vibration measelements. Vibra 4. Condition Monir systems, vibratitechniques 5. Special vibration measurement,	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr ation meters and analyzers toring through vibration analysis. ton limits and standards. Contar n measuring techniques - Chan Kurtosis, Acoustic emission mo	tion, Dis angle ransduc Freque ninant a ge in so	ers, sig ency ana nalysis,	ent, Velo nal conc llysis, Filt SOAP ar thod, Ultr um analy	litioning e ers, Vibra ad other co rasonic m	tion signa elements. tion signa ontaminal easuremo I analysis	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act nt monitori <b>Total</b> ent methoo s, critical s	peak & <u>Hrs</u> and rec <u>Hrs</u> ive ng <u>Hrs</u> d, Shock	9 ording 9 9 s pulse
<ul> <li>2. Introduction to Characteristics RMS, linear and</li> <li>3. Vibration mease elements. Vibrate</li> <li>4. Condition Monification systems, vibrate</li> <li>5. Special vibration measurement, Shaft –orbit &amp; p</li> <li>Text book (s)</li> </ul>	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr ation meters and analyzers toring through vibration analysis. ton limits and standards. Contam n measuring techniques - Chan Kurtosis, Acoustic emission mot osition analysis	tion, Dis angle ransduc Freque hinant a ge in so nitoring,	ers, sig ency ana nalysis, ound me Cepstru	ent, Velo nal conc Ilysis, Filt SOAP ar thod, Ulti um analy To	itioning e ers, Vibra nd other co rasonic m sis, Moda	tion signation elements. tion signation tamination easureme l analysis	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act nt monitori <b>Total</b> ent methoo s, critical s ont <b>Tota</b>	peak & Hrs and rec Hrs tive ng Hrs d, Shock peed an al Hrs	9 ording 9 9 x pulse alysis,
2. Introduction to Characteristics RMS, linear and 3. Vibration mease elements. Vibrat 4. Condition Monif systems, vibrat techniques 5. Special vibration measurement, Shaft –orbit & p Text book (s) 1. Collacc	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr toring through vibration analysis. toring through vibration analysis. ton limits and standards. Contam n measuring techniques - Chan Kurtosis, Acoustic emission mo osition analysis	tion, Dis angle ransduc Freque ninant a ge in so nitoring,	ers, sig ency ana nalysis, ound me Cepstru	ent, Velo nal conc Ilysis, Filt SOAP ar thod, Ultr um analy <u>To</u>	city and a litioning e ers, Vibra nd other co rasonic m sis, Moda <u>ital hours t</u> oring, Cha	tion signation elements. tion signation tanalysis to be taug	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act nt monitori <b>Total</b> ent method s, critical s oht <b>Tota</b> Hall, Londo	peak & Hrs and rec Hrs tive ng Hrs d, Shock peed an hl Hrs on, 1982	9 ording 9 9 x pulse alysis,
2. Introduction to Characteristics RMS, linear and 3. Vibration mease elements. Vibrat 4. Condition Monif systems, vibrat techniques 5. Special vibration measurement, Shaft –orbit & p Text book (s) 1. Collacc 2. John S	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr ation meters and analyzers toring through vibration analysis. ton limits and standards. Contam n measuring techniques - Chan Kurtosis, Acoustic emission mot osition analysis	tion, Dis angle ransduc Freque ninant a ge in so nitoring, osis and inery Ar	ers, sig ency ana nalysis, ound me Cepstru	ent, Velo nal conc Ilysis, Filt SOAP ar thod, Ultr um analy <u>To</u>	city and a litioning e ers, Vibra nd other co rasonic m sis, Moda <u>ital hours t</u> oring, Cha	tion signation elements. tion signation tanalysis to be taug	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act nt monitori <b>Total</b> ent method s, critical s oht <b>Tota</b> Hall, Londo	peak & Hrs and rec Hrs tive ng Hrs d, Shock peed an hl Hrs on, 1982	9 ording 9 9 x pulse alysis,
2. Introduction to Characteristics RMS, linear and 3. Vibration mease elements. Vibrat 4. Condition Monif systems, vibrat techniques 5. Special vibration measurement, Shaft –orbit & p Text book (s) 1. Collacc 2. John S	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr ation meters and analyzers toring through vibration analysis. ion limits and standards. Contam n measuring techniques - Chan Kurtosis, Acoustic emission mon osition analysis	tion, Dis angle ransduc Freque ninant a ge in so nitoring, osis and inery Ar	ers, sig ency ana nalysis, ound me Cepstru	ent, Velo nal conc Ilysis, Filt SOAP ar thod, Ultr um analy <u>To</u>	city and a litioning e ers, Vibra nd other co rasonic m sis, Moda <u>ital hours t</u> oring, Cha	tion signation elements. tion signation tanalysis to be taug	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act nt monitori <b>Total</b> ent method s, critical s oht <b>Tota</b> Hall, Londo	peak & Hrs and rec Hrs tive ng Hrs d, Shock peed an hl Hrs on, 1982	9 ording 9 9 s pulse alysis,
2. Introduction to Characteristics RMS, linear and 3. Vibration mease elements. Vibra 4. Condition Monir systems, vibratitechniques 5. Special vibration measurement, Shaft –orbit & p Text book (s) 1. Collacco 2. John S Publish Reference(s) 1. Nakra,	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr ation meters and analyzers toring through vibration analysis. ion limits and standards. Contam n measuring techniques - Chan Kurtosis, Acoustic emission mon osition analysis	tion, Dis angle ransduc Freque ninant a ge in so nitoring, osis and inery Ar a, 1993.	ers, sig ency ana nalysis, bund me Cepstru d Conditi nalysis a	ent, Velo nal conc llysis, Filt SOAP ar thod, Ultr um analy <u>To</u> <i>To</i> <i>To</i> <i>Monit</i>	city and a litioning e ers, Vibra nd other co rasonic m sis, Moda <u>tal hours t</u> oring, Cha oring, Pen	tion signa elements. tion signa pontaminal easureme l analysis to be taug pman & l n Well Bo	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act nt monitorin <b>Total</b> ent method s, critical sp oht <b>Tota</b> Hall, Londo poks, Penr	peak & Hrs and rec Hrs dive hrs div	9 ording 9 s pulse alysis, 45
2. Introduction to Characteristics RMS, linear and 3. Vibration meas elements. Vibra 4. Condition Monir systems, vibrati techniques 5. Special vibratio measurement, Shaft –orbit & p Text book (s) 1. Collacco 2. John S Publish Reference(s) 1. Nakra, <i>Counci</i> 2. Pox an	of vibration – SHM, Periodic mo d logarithmic scales and phase a suring instruments, vibration tr ation meters and analyzers toring through vibration analysis. toring through vibration analysis. ton limits and standards. Contain n measuring techniques - Chan Kurtosis, Acoustic emission mot osition analysis ott, R.A., <i>Mechanical Fault Diagne</i> . Mitchell, <i>Introduction to Mach</i> ing Company, Tulsa, Oklahoma B.C. Yadava, G.S. and Thueste	tion, Dis angle ransduc Freque ninant a ge in so nitoring, osis and inery Ar a, 1993. ed, L., V	ers, sig ency ana nalysis, bund me Cepstru d Conditi nalysis a	ent, Velo nal conc llysis, Filt SOAP ar thod, Ultr um analy <u>To</u> <i>To</i> <i>To</i> <i>Monit</i>	city and a litioning e ers, Vibra nd other co rasonic m sis, Moda <u>tal hours t</u> oring, Cha oring, Pen	tion signa elements. tion signa pontaminal easureme l analysis to be taug pman & l n Well Bo	of failure, on Peak to <b>Total</b> Display a <b>Total</b> ature of act nt monitorin <b>Total</b> ent method s, critical sp oht <b>Tota</b> Hall, Londo poks, Penr	peak & Hrs and rec Hrs dive hrs div	9 ording 9 spulse alysis, 45

CBIT	-	A	utonor	nous R	egula	ation				
Departme	ent	Mechanical Engineering	Pr	ogramn Nar			M.E. CAI Engineer	D/CAM & ing	Therm	al
			nester-l							
Course Co	ode	Course Name	Hours	/ Week		Credit		m Marks		atal
		ENGINEERING RESEARCH	L	Т	Р	С	E	- 1		otal
16MEE		METHODOLOGY	3	0	0	3	70	30		100
Objective	(S)	<ol> <li>To motivate the students to choose</li> <li>To make the students to formulate t</li> <li>To identify various sources for litera</li> <li>To prepare the research design</li> <li>To equip the students with good me</li> <li>To write a report and interpret the research the r</li></ol>	the resent ture reveations t	earch pr view an	oblen d data	n. a collectio				
Outcome (	(s)	Students will be able to 1. define research problem 2. review and asses the quality of liter 3. understand and develop various re 4. collect the data by various methods 5. analyze problem by statistical techn 6. improve the style and format of writi	rature fi search : obser iiques: /	designs vation, i ANOVA	s. intervi ., F-te	iew, ques st, Chi-se	quare			
1	Rese	arch Methodology:	0					Total H	rs	9
Significar Problems <b>Defining</b>	nce of s Enco t <b>he F</b>	<b>hodology:</b> Objectives and Motivation Research, Research Methods verses I buntered by Researchers in India, Bene <b>Research Problem</b> : Selection of Resea ining a Problem	Method fits to t	ology, F he socie	Resea ety in	arch Proc general.	ess, Crite	eria of Go	od Re	search,
2	Lite	erature Survey:						Total H	Irs	9
		rvey: Importance and purpose of Lite	erature	Survey	, So	ources o	f Informa			
Quality of	f Jour	nals and Articles, Information through li	nternet.	-				ŗ		
		view: Need of Review, Guidelines for R	Review,	Record	l of Re	esearch I	Review	Tatal	11	
3 Bosoaro		search Design: sign: Meaning of Research Design,	Nood	of Poc	oorch	Docian	Footure	Total		9
Importan	t Con	cepts Related to Research Design, Dif poping a Research Plan, Steps in sample	ferent l	Researd	ch De	signs, Ba	asic Princ			
4		a Collection:	0				Ŭ	Total	Hrs	9
variance	of two	on: Methods of data collection, import o normal population, and Non Paramet : Tests for significance: Chi-square, AN	ric test,	relatior						
5		erpretation and report writing:						Total H		9
Mechanic	cs of v n Prop	and report writing: Meaning of int writing a report. bosal Preparation: Writing a Research	•				•			•
Text Book									-	
		Research Methodology, Methods & Tec Research Methodology for Engineers, I					al Publisl	hers, 200	4	
Reference	es:									
Pvt., Ltd	۱., Ne	Statistical Methods: Concepts, Applica w Delhi, 2004					-	,		
New De	elhi, 20	e and Aravind Shende, Research Meth 009 and A. Wilson Aruni, Research and Writ					•	shers		

CBIT	Autonomous Regulation		Ser	nester-1			AY - 200	)6-17	
Department	Mechanical Engineering	Progr	amme C	ode & Na	me		M.E. CAD	D/CAM	
Course Code	Course Name	Hours	/Week		Credit	Maximu	um Marks		
16MEE 108		L	Т	Р	С	E	I	Tot	tal
	TRIBOLOGY IN DESIGN	3	0	0	3	70	30	10	0
Objective (s)	1. To impart knowledge	in the fr	iction, v	vear and	lubrication	aspects	of machin	e compo	nents
	2. To understand the r	naterial	properti	es which	influence	the tribo	logical cha	aracteris	tics of
	surfaces								
Outcome (s)	After the completion of the co	-							
	1. Have a knowledge of					a rough	engineerii	ng surfac	ce
	2. Understand friction								
	3. decide upon lubrica			0		lifferent	operating	conditio	ons
	4. Understand Hertz co		-						
	5. Ability to select	materia	al / s	urface p	properties	based	on the	e tribol	ogical
	requirements	_							
	<ol><li>Analysis ability of dif</li></ol>	ferent ty	pes of b	pearings for	or given lo	ad/ spee	d conditio	ns.	
1.	f Surfaces Surface feature	Drong	rtico or	d maaau	romont	Surface	Total	-	9
	If Surfaces – Surface feature ng Friction –Rolling Friction-F								
	ions –Thermal considerations					in-metam	C material	5 – mcu	
<b>2.</b>			9 0011100				Total	Hrs	9
Types of wear	- Mechanism of various types	of wear	r – Laws	s of wear	-Theoretic	al wear	models-W	ear of M	letals
and Non metal	s – Surface treatments – Surf	ace mod	lification	s – surfac	ce coatings	s method	ls- Surface	e Topogr	aphy
	–Laser methods – instrument	ation - Ir	nternatio	nal stand	ards in fric	tion and			
3.							Total		9
	their physical properties- V								
	ricants standards ISO,SAE,A lubricated contacts- Bound								
	Magneto hydrodynamic lubrica							lo anu	ριαδίο
<b>4</b> .						labiloat	Total	Hrs	9
	ation,-Assumptions and limitati	ons-One	and two	o dimensi	onal Reyn	olds Equ			
	Id boundary conditions- Press								
	bearings-Long and short bear							effects-	
	derations-Hydrostatic lubrication								
	iffness considerations- Various	types o	of flow re	strictors i	n hydrosta	tic bearir			•
5. Bolling contacts	of Electic colide contact star		Uortziere	otroco -	quotion 0	phorical	Total		9
	of Elastic solids- contact stre life- Oil film effects- Elasto Hy								
	odynamic lubrication Film s								
	ing bearings- Stresses and de				oomaat 2				
	Å				tal hours to	o be taug	ght Tota	al Hrs	45
Text book (s)									
Reference(s)									
	vicz.E, —Friction and Wear of					1995			
2. Cameron,	A. —Basic Lubrication Theory	l, Ellis H	erward	Ltd., UK,	1981	1995			
<ol> <li>Cameron,</li> <li>Halling, J.</li> </ol>	<ul> <li>A. —Basic Lubrication Theory</li> <li>(Editor) – —Principles of Tribo</li> </ul>	l, Ellis H logy —,	erward Macmill	Ltd., UK, ian – 198	1981	1995			
<ol> <li>Cameron,</li> <li>Halling, J.</li> <li>Williams J</li> </ol>	<ul> <li>A. —Basic Lubrication Theory (Editor) – —Principles of Tribo A. — Engineering Tribologyll,</li> </ul>	l, Ellis H logy —, Oxford L	erward Macmill Jniv. Pre	Ltd., UK, ian – 198 ess, 1994	1981 4		India Pvt	Ltd	
<ol> <li>Cameron,</li> <li>Halling, J.</li> <li>Williams J</li> </ol>	A. —Basic Lubrication Theory (Editor) – —Principles of Tribo .A. — Engineering Tribologyll, S.N.Sengupta & B.B.Ahuja ,IFu	l, Ellis H logy —, Oxford L	erward Macmill Jniv. Pre	Ltd., UK, ian – 198 ess, 1994	1981 4		India Pvt.	Ltd.,	

CBIT	Autonomous Regulation		Ser	nester-1			AY - 200	06-17	
Department	Mechanical Engineering	Progra		ode & Na	ame		M.E. CAL		
Course Code	Course Name	0	/ Week		Credit	Maximu	m Marks	-, 0, 00	
16MEE 109	ADVANCED	L	T	Р	C	E		Tr	otal
	MECHANICS OF	3	0	0	3	70	30		00
	MATERIALS	_	-	_			50	1	00
Objective (s)	1. To understand the var								
	2. To understand the str	ess-stra	in relati	ons and f	ailure theo	ories			
Outcome (s)	Students will be able to								
	1. understand the analys			tion, stres	ss-strain r	elations, f	allure theo	ories	
	2. analyze and design the				allia ar				
	<ol> <li>determine the stresse</li> <li>locate the shear centr</li> </ol>								
	5. Determine the stress								
	6. calculate the residual				ndor torsi	on/bondin	a analyze	the to	rcion of
	noncircular cross-sect		55 111 1110				y analyze		5011 01
1.							Tota	Hrs	9
	relations and general equation	ons of e		in Carte	esian Po	lar and c			-
	lations of equilibrium-compatibi								
	generalized hook's law - St. \								
methods	,			•					0,
2.							Tota	l Hrs	9
Location of sh	ear center for various thin secti	ons - sł	near flov	vs. Stress	ses and D	eflections	in beams	subjec	ted to
unsymmetrical	loading-kern of a section							-	
3.							Tota		9
Circumference	and radial stresses – deflectior	ns - curv	/ed bea	m with res	strained e	nds - clos	ed ring su	bjected	to
concentrated le	oad and uniform load - chain lin	ks and	crane ho	oks. Solu	ution of re	ctangular			
4.					-		Tota	l Hrs	9
Torsion of rect	angular cross section - St.Vena	nts theo	ory - ela	stic memb	orane ana	logy - Pra	ndtl's stre	SS	•
function - torsi	onal stress in hollow thin walled	tub							
5.							Tota	l Hrs	9
	pential stresses in solid disc and							wable s	speeds.
Methods of com	puting contact stress deflection	of bodi	es in po						
				То	tal hours	to be taug	ht <b>Tota</b>	al Hrs	45
Text book (s)									
Reference(s)									
	oresi, Richard J. Schmidt, —Ad				aterialsII,J	ohn Wiley	, 2002		
	ko and Goodier, "Theory of Elas						• • •		
	Cook, Warren C. Young, "Adva					millan pul	o. Co., 19	85	
	S., —Advanced Mechanics of s				, 1992				
	r Strength of Materials Macmilla				مأما المطاحية	. Edition	2012 201		
	ower, —Applied Mechanics of S								Delhi
7. K. Baskar 2009	and T.K. Varadan, —Theory	UI ISOT	pic/Ortr	IOUTOPIC E	LIASUCITY!!,	ALLE ROO	KS PVI. LI	u., New	i Deini,
2009									

CBIT	Autonomous Regulation		Ser	nester-1			AY - 2006	5-17	
Department	Mechanical Engineering	Progr		ode & Na	ame		M.E. CAD/		
Course Code	Course Name		/Week		Credit	Maximu	um Marks		
16MEE 110	MECHANICS OF	L	Т	Р	С	E	1	Тс	tal
	COMPOSITE MATERIALS	3	0	0	3	70	30		00
Objective (s)	<ol> <li>An ability to identify composites, as well as</li> <li>An ability to predict t properties.</li> <li>An ability to analyze from lamina properties</li> <li>An ability to predict the</li> </ol>	s some he elas a lamii	commo stic prop	n manufa erties of ate in bei	cturing tec fiber com nding, incl	chniques. posites b luding fin	based on th	e con	stituent
Outcome (s)	<ol> <li>Classify the composite</li> <li>Recognize the fundan and macro level.</li> <li>Understand different f</li> <li>Demonstrate the fund stress and strain.</li> <li>Understand the failure</li> <li>Analyze different type</li> </ol>	abricati amenta of corr	of ortho on meth Is of dire	tropic ma ods of co ectional st including	terials and mposites. tresses an fracture.	l mechan	ics of mater . Transform nell theory	ation c	of
1.							Total I		9
matrix composit	bres, Matrix materials, interfacters and carbon carbon composit		ymer ma	atrix com	posites, m	netal mat	· · · ·		
2.				·			Total I		9
	s of lamina and mechanical prop in-Tsai equations. Thermal prop								
<b>3.</b>							Total I	Irs	9
Macro-mechani stiffness and c	cs of lamina: Elastic constants compliances. Variation of lamir rains with orientation, inter-lamir nated beams	na prop	perties v	with orier	ntation, ar	alysis of	constants laminated mposite be	and re comp am so	educed posites, lutions.
4.							Total I		9
fracture modes failure, fatigue of Max stress theo Designing with of	re, fatigue and design: Tensile a in composites: single and multip of laminate composites. Effect of ory, max strain criteria, maximum composite materials	le fract variabi	ures, de ility of fit	-bonding, pre streng	, fibre pullo th. Streng	out and d th of an c	e-lamination orthotropic la tion criteria.	n amina:	
5.						<u> </u>	Total I		9
	inated plates and shells: Plate e es of composite materials. Analy			e cylindri	cal shells	under axi	ally symme	tric loa	ids.
Toxt book (a)				10	tal hours t	o de tauç	ght <b>Total</b>	HIS	45
Text book (s)	R.M., Mechanics of Composite	Vatorio	Is Mar	raw Lill C	D 1067				
							0040		
	arwal et.al, Analysis and perform								
	Barbero, Introduction to compos	ite mate	eriais de	sign, Tay	ior &Franc	cis, 1999.			
Prentice 2. Hyer, M	y, I.M. Daniel, R.B. Pipes, <i>Exper</i> e Hall, 1984 I.W., <i>Stress Analysis of Fibre Re</i> Herakovich, <i>Mechanics of Fibr</i> o	einforce	d Comp	osite Mat	<i>erials,</i> Mc	Graw Hil	I Co., 1998	erials,	

CBIT	Autonomous Regulation	Semester-1 AY - 2006-17							
Department	Mechanical Engineering	Progra		ode & Na	ame		M.E. CAD		
Course Code	Course Name		/Week		Credit	Maximu	ım Marks		
16MEE 111	THEORY OF ELASTICITY	L	Т	Р	С	E	I	To	tal
	AND PLASTICITY	3	0	0	3	70	30	10	00
Objective (s)	Students should able to								
	<ol> <li>solve the problems se</li> </ol>	lected t	o stress	-strain ter	nsors and	an consti	tutive rela	tions	
	2. apply suitable plastic	city rel	ations 1	o solve	the prob	lems in	various	metal fo	orming
	operations								
Outcome (s)	Students can								
	1. demonstrate the unde		-	ndamenta	ils stress a	nd its coi	ncepts.		
	2. understanding of conc								
	3. solve the problems rel								
	4. to apply the constitut	ive equ	ations, o	compatibl	liity equati	on and e	equilibrium	equation	ons for
	problem solving	aa far a		ablama					
	5. apply plasticity relation				de				
1	6. can choose and apply	plastici	Ly allalys	sis metrio	us		Total	Ure	9
1. Basic Concents	of Stress : Definition, State of S	Strose	t a noin	t Stroce	tonsor in	variante c			-
	ellipsoid, derivation for maxim								
	eviatoric and Hydrostatic compo								
2.				Invaliant			Total		9
	of Strain : Deformation tensor, S	Strain te	nsor an	d rotation	tensor; inv	variants o			-
	derivation for maximum shear								
	c and Hydrostatic components o	of strain	tensor,	Invarianc	e of Devia	toric stra	in tensor,	plane	
strain.									
3.							Total		9
	oke's Law : Stress-strain relatio								
	d plane strain conditions, different	ential e	quations	s of equili	brium, cor	npationity	/ equation	s, Mater	iai (D)
matrix for Orthor	itopic materials						Total	Ure	9
	true strain, von-Mise's and Tres	ca viel	d critoria	Haidh \	Mostorgar	detroce			-
	d Tresca yield criteria, effectiv								
	and Levy–Mise's constitutive e					Vonanto		plaotio	now,
	vork hardening theories, work of								
5.							Total	Hrs	9
Analysis method	s: Slab method, Slip line field n	nethod,	uniform	deformat	tion energy	/ method	, upper an	d lower	bound
solutions. Applic	ation of Slab method to forging,	wire dr	awing, e	extrusion	and rolling	process			
				То	tal hours to	o be taug	ght <b>Tota</b>	al Hrs	45
Text book (s)						rd			
1. Timosh	nenko and Goodieer, Theory of	Elasticit	ty, Mcgra	aw Hill Pu	ublications	3 <sup>ra</sup> Editio	on		
2. Madles	on, Theory of Plasticity								
Reference(s)									
	rabarty, Theory of Plasticity, 2 <sup>110</sup>					1998			
2. George E	Dieter, Mechanical Metallurgy,	McGra	w Hill Pu	uplication	s 1988				

CBIT	Autonomous Regulation		Sen	nester-1			AY - 200	06-17	
Department	Mechanical Engineering	Progra		ode & Na	ame		M.E. CAD		
Course Code	Course Name		/Week		Credit	Maximu	ım Marks		
16MEE 112	EXPERIMENTAL	L	Т	Р	С	E	I	Tota	al
	<b>TECHNIQUES AND DATA</b>	3	0	0	3	70	30	100	)
	ANALYSIS								
Objective (s)	1. To get acquainted	with in	nproving	quality	of produ	ct/proces	s by stu	idying va	rious
	parameters	rogor	dina imn	rovomont	of produc	+1, 11+, 1			
Outcome (s)	2. To gain the knowledge     1. Show the general prin					livity			
Outcome (s)	2. Classify and apply diff				overting cu	itting forc	es into su	itable sign	nals
	3. State the design requi							lable sign	
	4. Understand various su								
	5. Able to apply Taguchi					problems			
1.				•			Tota	Hrs	9
Measurement of	of Cutting Forces: Strain g	auge a	and pie	zoelectri	c transdu	cers an	d their o	characteri	stics.
	construction, Bridge circuits						placemen	t and s	strain
	by photoelasticity. Holography, i	nterferc	ometer, l	Moir tech	niques, str	ain gauge			
2.							Tota	Hrs	9
	easurement: Circuits and instr					ers viz, b	oimetallic,		
	electrical resistance, thermister						ooiblo fluir	40	
	ent : Transducers for flow meas drag methods. Vortex shreddin							15.	
	ow visualization techniques, Sha								
3.		uuon g			onotograpi	ly. Intone	Tota	Hrs	9
	udies: Optical and electron m	icrosco	pv. X-R	av diffra	ction. Brad	ooʻs Law			-
	al structure and residual st								
	Micro hardness, roughness,								
machines									
4.							Tota		9
	esign & data analysis: Statist			Randomi	sed block	design,	Latin an	d orthogo	onal
	ial design. Replication and rand								
	Deterministic and random data								
	ression modeling, direct and and autoregressive modeling			mecis. /	ANOVA, I	r-lesi. I	ine Sei	les allaly	/515,
<b>5.</b>	rand autoregressive modeling						Tota	Hrs	9
	s: Experiment design and plan	nina wit	h Ortho	nonal arra	avs and lin	ear grap			
	tion of response level. Identifica					iour grup		0 00000 0	511001
	aluation and Optimization by sig					s function	and its ap	plication.	
					tal hours to			al Hrs	45
Text book (s)							•		
1. Holman, 、	J.P.: Experimental Methods for	Engine	ers, Mo	Graw Hill	Int., New	York			
2. Venkates	h, V.C., and Chandrasekharan,	Experii	mental N	lethods ii	n Metal Cu	<i>itting</i> , Pre	entice Hall	of India, I	Delhi
Reference(s)									
	V.; The Design and Analysis of								
	Jenkins; <i>Time Series analysis, F</i>							- D."'	
	Adams, Experimental stress an						all of Indi	a, Delhi	
4. Tapan P.	Bagchi, Taguchi Methods Expl	ainea,	Prentice	e mail of li	nula, Delhi				

CBIT	Autonomous Regulation		Sen	nester-1			AY - 200	)6-17					
Department	Mechanical Engineering	Progr		ode & Na	me		M.E. CAE						
Course Code	Course Name	0	/ Week		Credit	Mavim	Im Marks						
16MEE 113	DESIGN FOR		T	Р	Credit	E	1	Та	tal				
	MANUFACTURE	L 3					1						
		-	0	0	3	70	30 100						
Objective (s)	1. To provide understand								oturing				
Outcome (a)	2. To make the students Student will able to	unders	tand the	linkage i	equired be	elween d	esign and	manula	cluning				
Outcome (s)	1. understand constrain	to of m	onufact	uring pro	voocoo th	ot limit	docian na	ecibilitic	o with				
	respect to cycle time,						uesign po	SSIDIIIIIE	s with				
	2. design suitable manuf						llic compo	nonte					
	3. design suitable manuf				0	0			nts				
	4. design welded assem					ing non		mpone	11.5				
	5. design suitable manuf					ning the	bolted, sc	rewed. f	langed				
	connections etc.		9 P. 0000		e e. ace.g	inig nie			.agea				
	6. prepare a project or re	port ap	plying D	FM princ	iples per a	n examp	le from inc	dustry					
1.				•			Tota		9				
Introduction: G	eneral design principles for r	nanufa	cturabilit	y, streng	th and n	nechanic	al factors	, mech	anisms				
	ation method, geometrical tole												
	ous steel, hot rolled steel, colo												
copper, brass, r	non metallic materials, plastics, r	ubber a	and com	posites									
2.							Tota		9				
Metallic Compo	nents Design: Metal extrusion,	metal	stampin	ig, fine b	lanking, fo	our slide	parts, spi	ring and	wire				
	tal parts, cold headed parts, ex												
	ging electro forming parts, sp	ecialize	d formir	ng metho	ds, turned	l parts, r	machined	round h	noles,				
drilled parts, mil	led parts.								-				
3.							Tota		9				
	omponents Design: Thermoset	ting pla	istic, inje	ection mo	oulded an	d rotation	hal mould	ed parts	s, blow				
	d plastic articles, ceramics												
4.							Tota		9				
	ts Design: Welded parts, arc, re	esistanc	e, braze	ed and so	oldered pa	rts, gear	box asser	mbly, be	earing				
assembly							Tatal		•				
5.	to Decima Determine Indiad		4			(I.e	Tota		9				
	ts Design: Retension, bolted												
	ess fitted connections, surface							nining, g	group				
lechnology, IOW	cost automation, computer aide	u mant	naciure,	product	uesiyii ieq	unement	з.						
Case Studies:	Identification of economical desi	ign and	redesig	n for man	ufacture								
				То	tal hours t	o be taug	ght Tota	al Hrs	45				
Text book (s)													
	. Bralla, —Hand book of produc						o., 19 <mark>86</mark>						
	t —Knowledge based design fo	r Manui	facturell.	Kogan n	ane Limite	d 1987							
2. K.G. SWI	i — Milowieuge baseu uesigii io			rtogun p	uge Linnie	a, 1001.							
2. K.G. 3WI	t —Milowieuge based design to			rtogun p		<u>a, 1007.</u>							
2. R.G. Swi	T — Nilowiedge based design io		<u></u> ,	rtogun p		<u>, 1001.</u>							
2. K.G. Swi			<u></u>	rtogun p		<u>, 1001.</u>							
2. K.G. Swi			<u></u>	Roganp		<u>, 1001.</u>							
2. K.G. Swi			<u></u>	Rogan p		<u>a, 1001.</u>							
2. K.G. Swi			<u></u>	rogan p		<u>u, 1001.</u>							

CBIT	Autonomous Regulation		Sen	nester-1			AY - 200	6-17	
Department	Mechanical Engineering	Progra	amme C	ode & Na	me		M.E. CAD	/CAM	
Course Code	Course Name	Hours	/Week		Credit	Maximu	um Marks		
16MEE 114	DATA BASE	L	Т	Р	С	E	I	Тс	otal
	MANAGEMENT SYSTEMS	3	0	0	3	70	30	1	00
Objective (s)	1. To understand the diffe	rent issu	es imple	mentation	of a datab	ase syster	n.		
	2. To study the logical data		•			•		els	
	3. To understand data mar		•						
Outcome (s)	After the completion of the cou					0			
	1. Understand the basic co					systems.			
	2. Familiarized with com	-							
	3. Demonstrate an unde					del			
	4. Familiarized with indexi								
	5. work successfully in a te						pplication		
	6. Understand the basics of								
1.	-						Total	Hrs	9
Introduction a	and E.R. Model: Purpose of dat	abase	svstems	. Data ab	straction.	Data mo	dels. Data	indepe	ndent
	BA. Entities and entity sets. Rela								
	, reducing E-R Diagram to tables							,	,
2.							Total		9
	odel and relational database de								
	query languages. Modifying th	e data	base vi	ews. Pit	falls in re	elational	database	desigr	1 and
normalization.									
3.							Total		9
	nodel and hierarchical data mode								etrieval
	t processing facility, Three struct	ure diag	gram, da	ta retriev	al and upo	late facilit			
4.							Total		9
	n Structure, Indexing and Hashir							nanage	ment,
5.	ons, networks and hierarchies to	liles - l	nuex - s	equentia	i illes. Di-l	ree index	Total	Uro	9
	abase essurity and integrity.	Decian	tranana	-	d outono				-
	abase, security and integrity: I introl, deadlock handling and coo								
concurrency co		Junato			tal hours t				<b>45</b>
Text book (s)				10				1115	43
· · · ·	.F. Silbenhatz, A., Database Cor	aconte	Mc Gray		86				
	derhold, Database Design, Mc G			w i iii, 19	00				
Reference(s)	aemola, Dalabase Design, MC G		, 1903						
	O Ullman, Principles of databas	se sveto	ms						
	e, An Introduction to database sy			Wiselv	1980				
	y and Soreson, An Introduction to					Mc Gra	w Hills		
o. ricinole	y and coroson, An introduction t	- Data	Saucial	s marap	Piloulorio				

Department			Ser	AY - 2006-17					
	Mechanical Engineering	Progr	amme C	ode & Na	ame		M.E. CAD	D/CAM	
Course Code	Course Name	Hours	/Week		Credit	Maxim	um Marks		
16MEE 115	FRACTURE MECHANICS	L	Т	Р	С	E	Ι	То	otal
		3	0	0	3	70	30	1	00
Objective (s)	1. To introduce students to	the co	ncepts of	materials	fracture a	nd failure	analvsis		
,	2. To equip them with kno		-				-		
Outcome (s)	At the completion of the cours				0	•			
( )	1. Identify and explain the				engineered	d materia	Is and the	ir chara	cteristi
	features;				-				
	2. Understand the differer	nces in th	ne classif	ication of	fracture m	echanics (	LEFM and E	PFM)● a	ind hov
	their corresponding par	ameters	can be u	utilized to	determine	conditior	ns under wh	ich engi	neerin
	materials will be liable t								
	3. Understand and explain		-	-					
	4. Appreciate the theoretic					ies utilized	for fractur	e	
	5. Develop expertise on th			-					
	6. Learn simple LEFM testi	-		-				-	
1.	· · ·	<u> </u>					Total		9
Introduction: C	Crack in a Structure – Griffth C	riterion	<ul> <li>Cleav</li> </ul>	age fract	ure – Duc	tile fractu	ure – Fatig	ue Cra	cking.
Service failure	analysis.			-			_		
2.							Total		9
	Elastic Crack tip stress field – S es – Irwin plastic zone correction								factor
3.	•						Total		9
Energy Principl	e: Energy release rate – Criteri	on for	crack gr	owth – C	rack resis	tance cu	rve – Prin	ciples o	f crac
arrest – Crack a	arrest in practice							-	
	Growth: Fatigue crack growth to		ess inter	nsity facto	or, factors	affecting	stress int	ensity f	actor
	ude service loading, retardation	model							
4.						<u> </u>	Total		9
	Fracture Mechanics: Elastic plas ermination of J-using FEM	stic frac	ture con	icept – C	rack tip op	pening di	splacemer	nt – J-in	tegral
5.							Total	Hrs	9
	Fracture Mechanics: Fracture d			on of ma	nterials – f	atigue cr	ack growt	h rate o	curve ·
Stress intensity	factor range - Use of crack grow	wth law							
				То	tal hours t	to be tau	ght <b>Tota</b>	al Hrs	45
Text book (s)									
	<ul> <li>Elementary Engineering Fract</li> <li>The Analysis of Laminated Co</li> </ul>						al Publish	ers – 19	978.
Reference(s)									
	ve and Jean Louis Chboche Me	chanics	of Solid	Material	s, Cambrid	dge Unive	ersity Pres	s Camb	ridge,
1987									
$\mathbf{C}$									

CBIT	Autonomous Regulation	Semester-1 AY - 2006-17					06-17			
Department	Mechanical Engineering	0		ode & Na			M.E. CAD	D/CAM		
Course Code	Course Name	Hours	/Week	1	Credit	Maximu	ım Marks	1		
16MEE 116	DESIGN OF PRESS	L	Т	Р	C	E		То	tal	
	TOOLS	3	0	0	3	70	30	1(	00	
Objective (s)	1. To make the students									
	2. To make students capable of designing various press tools which are safe, easy to									
	operate, reliable and e	conom	ical for r	nanufactu	uring.					
Outcome (s)	Student will be able to					1				
	<ol> <li>classify types of press</li> <li>understand the termine</li> </ol>					les.				
	<ol> <li>understand the termine</li> <li>understand Elements</li> </ol>				35.					
	4. understand the basic of				volved in c	desianina	press too	ls.		
	5. ne in a position to inde									
	requirement of industry			0	·					
	<ol><li>understand the different</li></ol>	nt types	s of dies							
1.							Tota		9	
	of Mechanical, Hydraulic, and									
	ciples of stretch forming mac	hines,	principle	es of fee	eding and	unloadii	ng equipr	nent. D	esign	
principles of pr 2.	esses.						Tota	Ure	9	
	s: Introduction terminology shea	nina di	oc turo	c of diac	analyci				-	
	inces of die opening and punch									
	<ul> <li>– strip layouts, economical stoc</li> </ul>			, chorgy i	in onearing	jiodali	ig ocinici,	oncanny	g with	
3.							Tota	Hrs	9	
	nearing dies – die plates – split	dies, ru	les of d	evelopme	ent for split	dies, ins			ches,	
	punches - strippers - calculation							•	,	
<ul> <li>pilots – stock</li> </ul>	guides – alignment system desig	gn for p	ress too	ls						
4.							Tota		9	
	, progressive dies, stock feedin									
	ng dies, shaving dies, laminatio					bending	developm	nent of t	olank,	
<b>5.</b>	ling, flanging and press brake di	les, bei	laing on	press bia	аке		Tota	Ure	9	
	ming Dies: Theory of drawing, b	Jank de	Nelonm	ont strai	n factor c	alculation				
•	awing dies – Drawing of recta									
	rubber and hydraulic system) -									
	arious computer software for she							,	40.00	
			Ŭ		tal hours t	o be tauc	ht Tota	al Hrs	45	
Text book (s)							<b>I</b>		·	
1. Fundamental	s of tool Design – ASTME, Pren	tice Ha	II, New I	Delhi, 198	37					
2. Die design Ha	and book – AISME, Mc Graw Hi	lls, New	/ York, 1	965						
Reference(s)										
	Makelt, Mechanical Presses, E				1968					
	Kalpakjain, Mechanical Process									
	kov V.A and Chaturvedi. R.C. F d Redds, Shear Working of Met				)olhi 1060	<b>`</b>				
	eme R.W.K., The plastic Deform						968			
	schikov, <i>Forging Practice</i> , Mir. P									
	elocity Forming of metals, ASME									
	harya.A, New Technology, Instit				ta 1073					

CBIT	Autonomous Regulation	Semester-1 AY - 2006-17					06-17	
Department	Mechanical Engineering	Progra	amme Co	de & Na	ame		M.E. CAI	D/CAM
Course Code	Course Name	Hours	/Week		Credit	Maximu	m Marks	
16MEE 117		L	Т	Р	С	E	Ι	Total
	DESIGN OF DIES	3	0	0	3	70	30	100
Objective (s)	1. To make students unders	tand th	e various	s steps	and proce	edure inv	olved in	designing and
	manufacturing dies							
	<ol> <li>To make students capable making</li> </ol>	e or so	iving con	npiex g	eometric p	problems	related t	o tool and die
Outcome (s)	Upon completion of the subject	t, stude	nts will be	e able to	):			
	1. Apply contemporary design	nrincinl	es when	designir	na advance	ed moulds	and dies	<u>.</u> .
	2. Assess the performance of							,
	3. Evaluate the effects of a giv							
	4. Describe the principles of cl							
	5. Design fixtures for milling, b	oring, la	athe, grind	ding, we	elding; iden	tify fixture	es and cu	tting
	tools for NC machine tools			aian				
1.	6. Explain the principles of die	s anu m		sign			Tota	IHrs 9
	les for dies of thermo-plastic an	d therm	o-settina	compor	nents Imn	ression co		
	pillars and bushes, ejection sy							
	splits, moulds of threaded com							
	on principles and standards for							
	ls: Mould for a spindle compor	nent wit	n sleeve,	pin eje	ction. Mou	ld with sp	olits Multi	-cavity mould
	ate, inserts, ejectors.							
2.	for motol mould Contings. Die		Challing	بالمائية مر			lota	I Hrs 9
	for metal mould Castings, Die o ing cavity, sprue, slug, fixed an				com corr	nin dra	ft oigeto	r pipe giactor
	bose-neck, nozzle, over-flow, p							
	chamber machines, vertical,							
	ms, rack and pinion, knockou							
machines								1
3.							Tota	
	us types of dies – Single cavity							
	h for die elements. Selection o ys – types of die casting allo							
	nspection. Gravity die casting and							
<b>4.</b>	hispeetion. Oravity die basting	Die det		50105 01		Buiktion	Tota	
	ng, Advantages of open die	forging	over clo	sed die	e forging.	Calculatio		
tolerances. Met	hods of open die forging. Desig	gn of di	es. Close	ed die fo	orging. Pre	paration	of materi	al for forging.
	aw-stock, cutting off, heating in	furnace	s. Allowa	inces ar	nd tolerand	ces for clo	osed die f	orging as per
IS: 3469 1974								
5.	family providence Design of	fulles :		. Della		an Dan	Tota	
	forging operations. Design of isher impression. Swaging to		•	-	•			
	additional operations on forgin							
	ign of upsetting dies. Calcula							
	but of forge shop. Roll forming,							
	<b>X</b>				otal hours t		ht <b>Tot</b>	al Hrs 45
Text book (s)								
	S.E., Forging & Forming Metals			Bombay	, 1952			
	I.H., <i>Die Casting Dies</i> , Mc Graw	/hill, 19	51					
Reference(s)	ndards, BSI., New Delhi.							
	G.W., Injection Mould Design, Lo	onoman	scientific	& Tech	nical Publi	ishers I o	ndon. 19	89
	,,					·····, <b>-·</b>	,	

CBIT	Autonomous Regulation	Semester-1 AY -					AY - 200	Y - 2006-17		
Department	Mechanical Engineering	Progra			le & Na	me		M.E. CAD		
Course Code	Course Name	Hours	/Wee	k		Credit	Maximu	um Marks		
16MEE 118	RAPID PROTOTYPING	L	Т		Р	С	E		Tot	al
	PRINCIPLES AND	3	0		0	3	70	30	10	0
Objective (s)	APPLICATIONS 1. To make students technologies.	unders	tand	the	basic	concepts	of va	rious rapio	d proto	typing
	<ol> <li>To understand and a application.</li> </ol>	pply crit	erion	for s	electing	g appropri	ate RPT	technique	for any	given
Outcome (s)	<ol> <li>identify different proce used RP systems</li> <li>describe various CAE</li> </ol>		•				Ū			
	model generation and 3. Explain and summariz	l manipu	lation							
	plastic and metal parts	S	-					·		
	<ol> <li>critically explore tec parameters, applicati implications</li> </ol>									
	<ol> <li>distinguish the types of customer demands ar</li> </ol>						es basec	l on part ge	eometry	
1.	6. identify different post						r rapid p	rototyping. Total	Ure	9
	Prototyping fundamentals,	Historic	al de	velo	oment	Fundam	entals (			-
Advantages ar	nd Limitations of Rapid Prototy ocess Chain: Fundamental Auto	ping, Co	ommo	nly i	ised Te	erms, Clas				
2.								Total	Hrs	9
	<b>Rapid Prototyping Systems</b>									
	ng principle, photopolymers, ph									
Applications,	Advantages and Disadvantage	ges, Ca	ase s	tudie	es. Sol	lid ground	d curing	(SGC):	Models	and
	Process, working principle, A									
	Prototyping Systems: Lami									
	ing principle, Applications, Ac M): Models and specification									
Disadvantages		ns, Fiu	cess,	woi	King p	principie,	Applicati	ons, Auva	mayes	anu
<b>3.</b>								Total	Hrs	9
	d Rapid Prototyping Syster	ms: Se	lective	las	er sint	ering (SL	S): Mod			-
	ing principle, Applications, Ad									
	): Models and specifications , Case studies.	s, Proc	ess,	worł	king p	rinciple,	Applicatio	ons, Adva	ntages	and
	Introduction to Rapid Tooling	g (RT),	Conve	entio	nal To	oling Vs F	RT, Need	d for RT. I	Rapid T	ooling
Classification: I Investment Cas	ndirect Rapid Tooling Metho ting, Spin Casting, Die casting,	ds: Spi Sand C	ay M asting	etal , 3D	Depos Keltoo	sition, RTV I process.	/ Epoxy Direct Ra	<ul> <li>Tools, C</li> <li>apid Toolin</li> </ul>	eramic	tools,
<b>4.</b>	M Rapid Tool Process, EOS Dir	rect 100	Proc	ess a	and Dir	ect ivietai	l ooling u	Total	Hre	9
Rapid Prototy	ping Data Formats: STL Forn odels, STL file Repairs: Generic							uilding Valio	and In	-
Rapid Prototyp	ing Software's: Features of va ity 2, Rhino, STL View 3 Data E	arious R	P soft	ware	's like l					ert,
<b>5.</b>	The second s			4001				Total	Hrs	9
	s: Application – Material Relation	tionship	, Appli	icatio	on in D	esign, Apr	olication			
and Planning, A	erospace Industry, Automotive	Industr	y, Jew	velry	Indust	ry, Coin In	dustry, C	GIS applica	tion, Art	ts and
	P Medical and Bioengineer									
	plants & Prosthesis, Desigr isulization of Biomolecules	n and	Produ	ctior						e and
Text book (s)					To	tal hours to	be taug	ght <b>Tota</b>	Hrs	45
	totyping: Principles and Application	ns - Chua	a C.K.,	Leon	g K.F. a	and LIM C.S	, World S	cientific pub	lications	, Third
2. Rapid Man Reference(s)	nufacturing – D.T. Pham and S.S. I									
1. Wholers	Report 2000 – Terry Wohlers, Wol ototyping & Manufacturing – Paul I					6				

CBIT	Autonomous Regulation		Ser	nester-1			AY - 2006	-17	
Department	Mechanical Engineering	Progr		ode & Na	me		M.E. CAD/		
Course Code	Course Name		/Week		Credit	Maximu	m Marks		
16MEE 119	Flexible Manufacturing	L	Т	Р	C	E		Tot	al
	Systems	3	0	0	3	70	30	10	
Objective (s)	The course covers the signific	-	-	-	_				
	methods. The fundamentals c concepts that include usage c removal, washing station, fixtu	of flexib of opera ring etc	ole manu ation cyo c	ufacturing cle descri	system a	re clearly	v stated from	m the o	design
Outcome (s)	Upon completion of the subjec 1. the understand the ele 2. Students can indeper be performed for mar 3. understand the functi 4. understand Automated 5. understand the concep 6. understand the FMS d	ments ndently nufactu oning d storag ot of jus	of flexib develo ring of of progra ge and re at in time	le manufa p the sec a produc ammable etrieval sy	quence of t logical con rstems	f operatio	ons that an	e to	
1.							Total H	Irs	9
Manufacturing Systems Planr system descrip	Manufacturing Systems: FM cells, Cellular versus Flexible M ning: Objective, introduction plan otion and sizing, facility preparat ommunication and involvement ning	lanufac nning,   ion plai	turing. preparat nning, F	ion guide MS layou	lines, the ts. Human	project te resource	am, supplie s: staff con	er seleo siderat	ction, ions,
2.							Total H	Irs	9
Group Techno	gle manufacture Cell – design so plogy: Concepts, classification ng rank order clustering techniq	and co							Iroup 9
	Jsing Bottleneck, Extended bott	lonooli	madala	Dragoni					-
Machining cent holding and wor and operation	re, construction and operation rk-changing equipment, automation description, importance to au digeneral function, operation cyc	s perfo ted feat tomate	ormed, a tures an d manu	axes, pro d capabili ifacturing,	ogramming ities, clear , coordina	, and fo ning and c ate meas	rmat inforn leburring – uring macł	nation, station nines,	work- types
	vement and storage systems-A	GVs F	20hots	automate	d storage	and retr			
space design, q auxiliary support Management, t considerations, automated and t	ueuing carousels and automatic t equipment, cutting tools and to cool strategies, data transfer, General fixturing, Modular fix transfer lines design aspects	c work o ol Man tool n	changer agemer nonitorir	s, coolant it – introd ig and fa	and chip uction, get ault deteo	Disposal tting contr ction, gui	and recove ol of cutting delines, we orkstations	ry systo tools, ork ho – Ma	ems, Tool Iding nual,
5.							Total H		9
	<ul> <li>Hardware, Software, Communusages, hardware configuration implementation</li> </ul>								
				To	tal hours t	o be taug	ht Total	Hrs	45
2. Groover, Reference(s)	D.J., _Flexible Manufacturing', - M.P., _Automation, Production	System	ns and C	<i>IM</i> ', - Pre	ntice Hall		9		
2. Considine	A., _Intelligent Manufacturing S e,D.M., & Considine,G.D., _Star .G., _Design and Operation of F	ndard H	landboo	k of Indus	trial Autor	nation',-C	hapman & I	Hall, 19	)86

CBIT	Autonomous Regulation						AY - 2006-17		
Department	Mechanical Engineering	<u> </u>		ode & Na			M.E. CA	D/CAM	
Course Code	Course Name	Hours	/Week		Credit	Maximu	m Marks		
16MEE 120	NON-TRADITIONAL	L	Т	Р	С	E	1	Тс	otal
	MACHINING AND FORMING	3	0	0	3	70	30		00
Objective (s)	1. To make the students un	derstan	d the ne	ed and th	e applicat	tions of no	ntraditior	nal	
	machining processes.								
	2. To choose the NTM pr	ocesses	s for pai	ticular ap	oplications				
Outcome (s)	Students can understand,								
	1.the importance ,principles of			aditional p	processes				
	2.the processes of Thermal M								
	3.the parameters and chemist			emical pro	ocess				
	4.the principles of Plasma Arc				م ما ما				
	5.the principles of laser Beam 6.to make the comparison of c					ing motho	de		
1.	0.10 make the companyon of c	onvenu	unai and	i nigri vei	OCILY IOITI	ing metho		l Hrs	9
	Need for non-traditional mach	ining p	nnesses	Proces		rtion clas		-	
study of differe		ming p	0003363	. 110083	303 36160		Sincation	, compa	
	Process: Ultrasonic Machining-I	Definitio	n-Mecha	anism of	metal ele	ments of t	the proce	ess- Too	l feed
	heories of mechanics of causing								
	Machining: Principles - parame					dvantages	s and dis	advanta	aes.
	chining (WJM): Schematic diag								0
2.								l Hrs	9
Thermal Meta	al Removal Process: Electric c	lischarg	e machi	ning Prin	ciple and	operation	- mecha	anism of	meta
removal hasi	c EDM circuitry-spark erosion	Amelia							
relaxation circ	uits- critical resistance parame	ters in I	Ro Circu	uit-Die ele	ectric fluid	ls- Electro	des for	surface	finish.
relaxation circ Applications. V		ters in I	Ro Circu	uit-Die ele	ectric fluid	ls- Electro	odes for a	surface	finish. ns
relaxation circ Applications. V 3.	uits- critical resistance parame Vire EDM principle and operation	ters in on. Wire	Ro Circu materia	uit-Die ele s, wire te	ectric fluic ension and	ls- Electro Lits param	odes for neters. Ap <b>Tota</b>	surface oplication I Hrs	finish. ns <b>9</b>
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma	uits- critical resistance parame Vire EDM principle and operation <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a - applications. Electro Chemica achining: Introduction-Plasma-0	s: Election meters of E al Grindi Generat	Ro Circu materia ro chem of the p CM pro ing-Elect ion of Pl	uit-Die ele s, wire te ical mach rocesses poess-pol tro Chem asma and	nining (EC -determin arization. ical holdir	Is- Electro its param CM) Classi ation of th Tool De ng Electroo	indes for interes. Ap interes. Ap interest of the interest of	surface pplication I Hrs ECM pro removal rantages deburrin	finish. ns 9 ocess- rate - s and ng.
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter	uits- critical resistance parame Vire EDM principle and operation <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a - applications. Electro Chemica	s: Election meters of E al Grindi Generat	Ro Circu materia ro chem of the p CM pro ing-Elect ion of Pl	uit-Die ele s, wire te ical mach rocesses poess-pol tro Chem asma and	nining (EC -determin arization. ical holdir	Is- Electro its param CM) Classi ation of th Tool De ng Electroo	interest for interest. Ap interest. Ap infication I e metal esign-adv chemical nism of r	surface oplication I Hrs ECM pro removal rantages deburrin netals re	finish. ns 9 ocess- rate - s and ig. emoval,
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4.	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a applications. Electro Chemica <b>achining</b> : Introduction-Plasma-( s-process characteristics - type	ters in m. Wire s: Electri meters s of E al Grindi Generat of torch	Ro Circu material ro chem of the p CM pro ing-Elect ion of Pl nes appli	uit-Die ele s, wire te rocesses ocess-pol tro Chem asma and cations	nining (EC -determin arization. ical holdir d equipme	Is- Electro I its param CM) Classi ation of th Tool De ng Electroo ent Mecha	interest for statements of the statements of the statement of the statemen	surface oplication I Hrs ECM pro- removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal remo	finish. ns 9 ocess- rate - s and ng. emoval, 9
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Bea	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics achining: Introduction-Plasma-( s-process characteristics - type <b>m Machining (EBM)</b> : Introduction	s: Election meters of E al Grindi Generat of torch	Ro Circu materia ro chem of the p CM pro ing-Elect ion of Pl nes appli	it-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma and cations	nining (EC -determin arization. ical holdir d equipme	Is- Electro I its param CM) Classi ation of th Tool De ng Electroo ent Mecha	interest for statements of the statements of the statement of the statemen	surface oplication I Hrs ECM pro- removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal removal remo	finish. ns 9 ocess- rate - s and ng. emoval, 9
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Bear beam machini	uits- critical resistance parame Vire EDM principle and operation <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a applications. Electro Chemica achining: Introduction-Plasma-( s-process characteristics - type <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type	s: Election meters al Grindi Generat of torch on-Equi s charac	Ro Circu material ro chem of the p CM pro ing-Elect ion of Pl ies appli	it-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma and cations or produce – applica	nining (EC -determin arization. ical holdir d equipme ction of Ele ations.	Is- Electro I its param CM) Classi ation of th Tool De ng Electroo ent Mecha ectron bea	interes. Agent interes. Agent ification I e metal esign-adv chemical nism of r Tota m - Theo	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele	finish. ns 9 ocess- rate - and ig. emoval, 9 ectron
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Bear beam machini Laser Beam	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics achining: Introduction-Plasma-( s-process characteristics - type <b>m Machining (EBM)</b> : Introduction	ters in on. Wire s: Electri meters s of E al Grindi Generat of torch on-Equi s charac on-princ	Ro Circu material ro chem of the p CM pro ing-Elect ion of Pl nes appli ipment for cteristics ciple of	it-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma an cations or produc – applica generatio	nining (EC -determin arization. ical holdir d equipme ction of Ele ations. on of las	Is- Electro I its param CM) Classi ation of th Tool De ng Electro ent Mecha ectron bea	interes. Application I fication I e metal esign-adv chemical nism of r Tota m - Theo oment a	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele	finish. ns 9 ocess- rate - and ig. emoval, 9 ectron
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Bear beam machini Laser Beam	uits- critical resistance parame Vire EDM principle and operation <b>fical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics achining: Introduction-Plasma-( s-process characteristics - type <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction	ters in on. Wire s: Electri meters s of E al Grindi Generat of torch on-Equi s charac on-princ	Ro Circu material ro chem of the p CM pro ing-Elect ion of Pl nes appli ipment for cteristics ciple of	it-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma an cations or produc – applica generatio	nining (EC -determin arization. ical holdir d equipme ction of Ele ations. on of las	Is- Electro I its param CM) Classi ation of th Tool De ng Electro ent Mecha ectron bea	interest of a meters. Application I and fication I and the metal and the metallation and the metallation a	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele	finish. ns 9 ocess- rate - and ng. emoval, 9 ectron
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Beam beam machini Laser Beam procedure-Typ 5. High Velocity	uits- critical resistance parame Vire EDM principle and operation <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a - applications. Electro Chemica <b>achining</b> : Introduction-Plasma-C s-process characteristics - type <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction bes of Lasers-Process characteristics <b>Forming Process</b> : introduction	s: Electri meters a of E al Grindi Generat of torch on-Equi s charac on-prince ristics-ac	Ro Circu material ro chem of the p CM pro- cing-Elect ion of Pl nes appli ipment for cteristics ciple of dvantage developr	ical mach rocesses boess-pol tro Chem asma and cations or produc generations agenerations	ectric fluid ension and determin arization. ical holdir d equipment tion of Ele ations. on of las nitations-a	As- Electro d its param CM) Classi ation of th Tool De og Electroo ent Mecha ectron bea sers Equip pplication	interest for statements of a statement and statement a	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele nd Macl I Hrs compari	finish. ns <b>9</b> ocess- rate - s and ag. emoval, ectron hining <b>9</b> son of
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Beam beam machini Laser Beam procedure-Typ 5. High Velocity conventional an	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a applications. Electro Chemica <b>achining</b> : Introduction-Plasma-( s-process characteristics - type <b>m Machining (EBM)</b> : Introduction m <b>Machining (LBM)</b> : Introduction <b>bes of Lasers-Process character</b> <b>Forming Process</b> : introduction <b>high velocity forming metho</b>	s: Electri meters s of E al Grindi Generat of torch on-Equi s charac on-prince cistics-ac	Ro Circu material ro chem of the p CM pro- ing-Elect ion of Pl nes appli ipment for cteristics ciple of dvantage developri ypes of	it-Die ele s, wire te ical mach rocesses boess-pol tro Chem asma an cations or produc generati es and lin nent of high ve	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme ction of Ele ations. on of las nitations-a specific locity forr	As- Electro d its param CM) Classi ation of the Tool De ang Electroc ent Mecha ectron bea ectron bea ectron bea process s ning meth	interest. Ap interest. Ap <b>Tota</b> ification I e metal esign-adv chemical nism of r <b>Tota</b> m - Theo oment al selection- nods- exp	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele nd Mach I Hrs compari- polosion f	finish. ns 9 occess- rate - s and ng. emoval, emoval, 9 ectron hining 9 ison of forming
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Beam beam machini Laser Beam procedure-Typ 5. High Velocity conventional an process-elector	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a applications. Electro Chemica <b>achining</b> : Introduction-Plasma-( s-process characteristics - type <b>m Machining (EBM)</b> : Introduction m <b>Machining (LBM)</b> : Introduction <b>m Second Second Second Second</b> <b>m Machining (LBM)</b> : Introduction <b>m Second Second Second</b> <b>m Second Second Second</b> <b>m Machining (LBM)</b> : Introduction <b>m Second Second Second Second</b> <b>m Second Second Second</b> <b>m Second Second Second</b> <b>m Second Second Second</b> <b>m Second Second Second Second</b> <b>m Second Second Second Second Second Second Second</b> <b>m Second S</b>	s: Electri meters s of E al Grindi Generat of torch on-Equi s charac on-prince ristics-ac ion - c ods - T pulse	Ro Circu material ro chem of the p CM pro- ing-Elect ion of Pl nes appli ipment for cteristics siple of dvantage developri ypes of forming.	it-Die ele s, wire te ical mach rocesses boess-pol tro Chem asma an cations or produc – applica generatives and lin nent of high ve Electro-	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme etion of Ele ations. on of las nitations-a specific locity forr Magnetic	As- Electro d its param CM) Classi ation of the Tool De ang Electroc ent Mecha ectron bea ectron bea sers Equip process sening meth Forming.	initial for a second se	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele nd Mach I Hrs compari plosion f Pad Fo	finish. ns 9 occess- rate - and ng. emoval emoval ectron hining son of forming orming:
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Beam beam machini Laser Beam procedure-Typ 5. High Velocity conventional an process-elector Principle of the	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a applications. Electro Chemica <b>achining</b> : Introduction-Plasma-( <u>s-process characteristics - type</u> <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction bes of Lasers-Process character <b>Forming Process</b> : introduction hydraulics forming magnetic e process, process details, pro-	s: Electri meters s of E al Grindi Generat of torch on-Equi s charac on-prince ristics-ac ion - c ods - T pulse	Ro Circu material ro chem of the p CM pro- ing-Elect ion of Pl nes appli ipment for cteristics siple of dvantage developri ypes of forming.	it-Die ele s, wire te ical mach rocesses boess-pol tro Chem asma an cations or produc – applica generatives and lin nent of high ve Electro-	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme etion of Ele ations. on of las nitations-a specific locity forr Magnetic	As- Electro d its param CM) Classi ation of the Tool De ang Electroc ent Mecha ectron bea ectron bea sers Equip process sening meth Forming.	initial for a second se	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele nd Mach I Hrs compari plosion f Pad Fo	finish. ns 9 occess- rate - and ig. emoval, emoval, <b>9</b> ectron hining ison of forming orming:
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Beam beam machini Laser Beam procedure-Typ 5. High Velocity conventional an process-elector	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a applications. Electro Chemica <b>achining</b> : Introduction-Plasma-( <u>s-process characteristics - type</u> <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction bes of Lasers-Process character <b>Forming Process</b> : introduction hydraulics forming magnetic e process, process details, pro-	s: Electri meters s of E al Grindi Generat of torch on-Equi s charac on-prince ristics-ac ion - c ods - T pulse	Ro Circu material ro chem of the p CM pro- ing-Elect ion of Pl nes appli ipment for cteristics siple of dvantage developri ypes of forming.	it-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma an cations or produc – applica generati es and lin nent of high ve Electro- - Guerin,	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme ction of Ele ations. on of las nitations-a specific locity forr Magnetic wheelon	As- Electro d its param CM) Classi ation of th Tool De and Electro ent Mecha ectron bea ectron bea ectron bea process s ning meth Forming. , Marform	ification I e metal esign-adv chemical nism of r <b>Tota</b> oment a selection- iods- exp Rubber ing and	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele M Macl I Hrs compari plosion f Pad Fo Hydro f	finish. ns 9 ocess- rate - s and ig. emoval, emoval, 9 ectron hining 5 orming forming
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Bear beam machini Laser Beam procedure-Typ 5. High Velocity conventional ar process-elector Principle of the processes and a	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a applications. Electro Chemica <b>achining</b> : Introduction-Plasma-( <u>s-process characteristics - type</u> <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction bes of Lasers-Process character <b>Forming Process</b> : introduction hydraulics forming magnetic e process, process details, pro-	s: Electri meters s of E al Grindi Generat of torch on-Equi s charac on-prince ristics-ac ion - c ods - T pulse	Ro Circu material ro chem of the p CM pro- ing-Elect ion of Pl nes appli ipment for cteristics siple of dvantage developri ypes of forming.	it-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma an cations or produc – applica generati es and lin nent of high ve Electro- - Guerin,	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme ction of Ele ations. on of las nitations-a specific locity forr Magnetic wheelon	As- Electro d its param CM) Classi ation of the Tool De ang Electroc ent Mecha ectron bea ectron bea sers Equip process sening meth Forming.	ification I e metal esign-adv chemical nism of r <b>Tota</b> oment a selection- iods- exp Rubber ing and	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele nd Mach I Hrs compari plosion f Pad Fo	finish. ns 9 occess- rate - and ng. emoval, emoval, <b>9</b> ectron hining ison of forming orming:
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Beat beam machini Laser Beam procedure-Typ 5. High Velocity conventional an process-elector Principle of the processes and a Text book (s)	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a - applications. Electro Chemical <b>achining</b> : Introduction-Plasma-C s-process characteristics - type <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction bes of Lasers-Process character <b>Forming Process</b> : introduction hydraulics forming magnetic process, process details, pro- applications	ters in m. Wire s: Electin meters of E al Grindi Generat of torch on-Equi s charac on-princ ristics-ac cods - T pulse to occess view	Ro Circu material ro chem of the p CM pro- ion of Pl nes appli ipment for cteristics ciple of dvantage developr ypes of forming. ariants	uit-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma and cations or produc - applica generations or produc s and lin nent of high ve Electro- - Guerin, To	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme ction of Ele ations. on of las nitations-a specific locity forr Magnetic wheelon	As- Electro d its param CM) Classi ation of th Tool De and Electro ent Mecha ectron bea ectron bea ectron bea process s ning meth Forming. , Marform	ification I e metal esign-adv chemical nism of r <b>Tota</b> oment a selection- iods- exp Rubber ing and	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele M Macl I Hrs compari plosion f Pad Fo Hydro f	finish. ns 9 ocess- rate - s and ng. emoval, 9 ectron hining 5on of forming forming
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Beam procedure-Typ 5. High Velocity conventional an process-elector Principle of the processes and a Text book (s) 1. New Tec	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a - applications. Electro Chemica <b>achining</b> : Introduction-Plasma-C s-process characteristics - type <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction bes of Lasers-Process character <b>Forming Process</b> : introduction hydraulics forming magnetic e process, process details, pro- applications hnology Institution of Engineers	ters in lin. Wire s: Electri meters a of E al Grindi Generat of torch on-Equi s charac on-prince ristics-ac ion - c ods - T pulse f occess vi - Bhatta	Ro Circu material ro chem of the p CM pro- ing-Elect ion of Pl nes appli ipment for cteristics ciple of dvantage developr ypes of forming. ariants	uit-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma and cations or produc generations or produc generations or produc generations nent of high ve Electro- Guerin, To - India	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme ction of Ele ations. on of las nitations-a specific locity forr Magnetic wheelon	As- Electro d its param CM) Classi ation of th Tool De and Electro ent Mecha ectron bea ectron bea ectron bea process s ning meth Forming. , Marform	ification I e metal esign-adv chemical nism of r <b>Tota</b> oment a selection- iods- exp Rubber ing and	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele M Macl I Hrs compari plosion f Pad Fo Hydro f	finish. ns 9 ocess- rate - s and ng. emoval, 9 ectron hining 5on of forming forming
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Bean beam machini Laser Beam procedure-Typ 5. High Velocity conventional an process-elector Principle of the processes and a Text book (s) 1. New Tec 2. Production	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a - applications. Electro Chemical <b>achining</b> : Introduction-Plasma-C s-process characteristics - type <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction bes of Lasers-Process character <b>Forming Process</b> : introduction hydraulics forming magnetic process, process details, pro- applications	ters in lin. Wire s: Electri meters a of E al Grindi Generat of torch on-Equi s charac on-prince ristics-ac ion - c ods - T pulse f occess vi - Bhatta	Ro Circu material ro chem of the p CM pro- ing-Elect ion of Pl nes appli ipment for cteristics ciple of dvantage developr ypes of forming. ariants	uit-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma and cations or produc generations or produc generations or produc generations nent of high ve Electro- Guerin, To - India	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme ction of Ele ations. on of las nitations-a specific locity forr Magnetic wheelon	As- Electro d its param CM) Classi ation of th Tool De and Electro ent Mecha ectron bea ectron bea ectron bea process s ning meth Forming. , Marform	ification I e metal esign-adv chemical nism of r <b>Tota</b> oment a selection- iods- exp Rubber ing and	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele M Macl I Hrs compari plosion f Pad Fo Hydro f	finish. ns 9 ocess- rate - s and ig. emoval, emoval, 9 ectron hining 5 orming forming
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Beam beam machini Laser Beam procedure-Typ 5. High Velocity conventional an process-elector Principle of the processes and a Text book (s) 1. New Tec 2. Productio Reference(s)	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a applications. Electro Chemica <b>achining</b> : Introduction-Plasma-( s-process characteristics - type <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction bes of Lasers-Process character <b>Forming Process</b> : introduction hydraulics forming magnetic e process, process details, pro- applications hnology Institution of Engineers on Technology - HMT - Tata Mc	ters in lin. Wire s: Electri meters a of E al Grindi Generat of torch on-Equi s charac on-prince cistics-ac ion - co ods - T pulse f ocess vi - Bhatta Graw H	Ro Circu material ro chem of the p CM pro- ing-Elect ion of Pl es appli ipment for cteristics siple of dvantage developr ypes of forming. ariants acharya lill - ISBI	uit-Die ele s, wire te ical mach rocesses ocess-pol tro Chem asma and cations or produc generative s and lin nent of high ve Electro- Guerin, To - India N-10	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme ction of Ele ations. on of las nitations-a specific locity forr Magnetic wheelon	As- Electro tits param CM) Classi ation of the Tool De ag Electroce ent Mecha ectron bea ectron bea application process sening mether Forming. , Marform to be taug	ification I e metal esign-adv chemical nism of r <b>Tota</b> oment a selection- iods- exp Rubber ing and	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele M Macl I Hrs compari plosion f Pad Fo Hydro f	finish. ns 9 ocess- rate - s and ig. emoval, emoval, 9 ectron hining 5 orming forming
relaxation circ Applications. V 3. Electro Chem principle of EC dynamics of disadvantages Plasma Arc Ma PAN parameter 4. Electron Beam beam machini Laser Beam procedure-Typ 5. High Velocity conventional an process-elector Principle of the processes and Text book (s) 1. New Tec 2. Productio Reference(s) 1. Modern	uits- critical resistance parame <u>Vire EDM principle and operation</u> <b>nical and Chemical Processes</b> CM Chemistry of the ECM para ECM process-Hydrodynamics a - applications. Electro Chemica <b>achining</b> : Introduction-Plasma-C s-process characteristics - type <b>m Machining (EBM)</b> : Introduction ng Thermal & Non thermal type <b>Machining (LBM)</b> : Introduction bes of Lasers-Process character <b>Forming Process</b> : introduction hydraulics forming magnetic e process, process details, pro- applications hnology Institution of Engineers	ters in lin. Wire ters in Wire s: Electri meters s of E al Grindi Generat of torch on-Equi s charac on-prince ristics-ac ods - T pulse f ocess vi - Bhatta Graw H	Ro Circu material ro chem of the p CM pro- ing-Elect ion of Pl nes appli ipment for cteristics siple of dvantage developr ypes of forming. ariants acharya iill - ISBI	ait-Die ele s, wire te ical mach rocesses boess-pol tro Chem asma and cations or produc – applica generations or produc – applica generations – applica generations – applica generations – applica generations	ectric fluid ension and hining (EC -determin arization. ical holdir d equipme etion of Ele ations. on of las nitations-a locity forr Magnetic wheelon tal hours	As- Electro A its param CM) Classi ation of th Tool De ag Electroc ent Mecha ectron bea application process s ning meth Forming. , Marform to be taug	odes for ieters. Ap <b>Tota</b> ification I e metal esign-adv chemical nism of r <b>Tota</b> m - Theo oment al selection- iods- exp Rubber ing and ht <b>Tot</b>	surface oplication I Hrs ECM pro- removal rantages deburrin netals re I Hrs ory of ele M Macl I Hrs compari plosion f Pad Fo Hydro f	finish. ns 9 ocess- rate - s and ng. emoval, 9 ectron hining 5on of forming forming

CBIT	Autonomous Regulation						AY - 200	AY - 2006-17			
Department	Mechanical Engineering	Progra	amme C	ode & Na	me		M.E. CAD	D/CAM			
Course Code	Course Name	Hours	/Week		Credit	Maximu	um Marks				
16MEE 121	PRODUCT DESIGN AND	L	Т	Р	С	E	1	To	tal		
	PROCESS PLANNING	3	0	0	3	70	30	10	00		
Objective (s)											
	2. To understand the ergonom										
Outcome (s)	1. Imparting basic foundation a	and adv	anced c	oncepts a	about Des	ign and N	lanufactur	ing			
	Engineering.										
	2. Root cause analysis of a de					basic and	d engineer	ing scier	nces.		
	3. Understanding and learning										
	4. Imparting research activities										
	5. Solving complex design eng		g proble	ms. and	apply late	st engine	ering tools	s with			
	advanced software knowled 6 .Mechanical engineering solu		aroon	and quate	vinabla da	volonmor	<b>,</b>				
1.	o intechanical engineering solo		J green a	anu susia		velopmer		Hre	9		
	and process design functions	soloci	ion of a	right pro	duct occ	ontial fac			-		
	design, sources of new ideas										
	v chart. Qualifications of produc										
	, colours and Laws of appearance		g						laide		
<b>2.</b>							Tota	Hrs	9		
	ity, Mortality Curve, Reliability s	vstems	. Manufa	acturina r	eliabilitv a	nd quality			-		
	sses of patents, applying for pat								of		
	ents of cost of a product, costin										
	k even analysis Charts. Value ei										
		igineer	ing in pr	oduct des	sign, creat	ivity aspe	ects and te	chnique			
	value analysis – cost reduction,					ivity aspe	ects and te	chnique			
Procedures of <b>3</b> .	value analysis - cost reduction,	materia	al and p	ocess se	lection.		Tota	Hrs	s. <b>9</b>		
Procedures of 3. Various manufa	value analysis – cost reduction, cturing processes, degree of ac	materia	al and pr	ocess se sh obtaina	lection. able, proc	ess capa	Total	<b>Hrs</b> es. Meth	s. <u>9</u> nods of		
Procedures of <b>3</b> . Various manufactimproving tolerations	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r	materia curacy ules fo	al and pr and finis r Castin	ocess se sh obtaina g, Forgir	lection. able, proc ng, Machi	ess capa ning, Sh	<b>Tota</b> bility studi eet metal	Hrs es. Meth and W	s. 9 nods of elding.		
Procedures of 3. Various manufaci improving tolera Physical proper	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a	materia curacy ules fo	al and pr and finis r Castin	ocess se sh obtaina g, Forgir	lection. able, proc ng, Machi	ess capa ning, Sh	<b>Tota</b> bility studi eet metal	Hrs es. Meth and W	s. 9 nods of elding.		
Procedures of 3. Various manufactimproving tolera Physical properticeramics for pro-	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a	materia curacy ules fo	al and pr and finis r Castin	ocess se sh obtaina g, Forgir	lection. able, proc ng, Machi	ess capa ning, Sh	Total bility studi eet metal of plastic	Hrs es. Meth and W cs, rubb	s. nods of elding. er and		
Procedures of 3. Various manufactimproving tolera Physical properticeramics for pro 4.	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design	materia curacy ules fo nd their	al and pr and finis r Castin r importa	ocess se sh obtaina g, Forgir ance on	lection. able, proc ng, Machi products.	ess capa ning, Sh Selectior	Total bility studi eet metal of plastic	Hrs es. Meth and W cs, rubb	s. nods of elding. er and 9		
Procedures of 3. Various manufactimproving toleration Physical propertion ceramics for pro- 4. Industrial ergon	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design	materia curacy ules fo nd their ations,	al and pr and finis r Castin r importa ease of	sh obtaina g, Forgir ance on maintena	able, proc ng, Machi products.	ess capa ning, Sh Selectior	Total bility studi eet metal of plastic Total ponsideratio	Hrs es. Meth and W cs, rubb	s. 9 nods of elding. er and 9 oduct		
Procedures of 3. Various manufatimproving toleratimproving toleration Physical propertion ceramics for pro- 4. Industrial ergonistication design-Anthrop	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine considera	materia curacy ules fo nd their ations, an-mac	al and pr and finis r Castin r importa ease of hine info	nocess se sh obtaina g, Forgir ance on maintena prmation	able, proc ng, Machi products. nce. Ergc exchange	ess capa ning, Sh Selectior nomic cc	Total bility studi eet metal of plastic Total onsideratio s sheet de	Hrs es. Meth and W cs, rubb Hrs ns in pro etail and	s. 9 nods of elding. er and 9 oduct their		
Procedures of 3. Various manufact improving tolerat Physical propert ceramics for pro 4. Industrial ergon design-Anthrop importance, Act	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine considera bometry, Design of controls, ma dvanced techniques for higher p	materia curacy ules fo nd their ations, an-mac producti	al and pr and finis r Castin r importa ease of hine info vity. Jus	mocess se sh obtaina g, Forgir ance on maintena ormation t-in-time	able, proc ng, Machi products. nce. Ergc exchange	ess capa ning, Sh Selectior nomic cc	Total bility studi eet metal of plastic Total onsideratio s sheet de	Hrs es. Meth and W cs, rubb Hrs ns in pro etail and	s. 9 nods of elding. er and 9 oduct their		
Procedures of 3. Various manufact improving tolerat Physical propert ceramics for pro 4. Industrial ergon design-Anthrop importance, Act to product desi	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine considera	materia curacy ules fo nd their ations, an-mac producti	al and pr and finis r Castin r importa ease of hine info vity. Jus	mocess se sh obtaina g, Forgir ance on maintena ormation t-in-time	able, proc ng, Machi products. nce. Ergc exchange	ess capa ning, Sh Selectior nomic cc	Total bility studi eet metal of plastic Total onsideratio s sheet de m. Modern	Hrs es. Meth and W cs, rubb Hrs ns in pro etail and n approa	s. 9 nods of elding. er and 9 oduct their aches		
Procedures of 3. Various manufact improving tolerat Physical propert ceramics for pro 4. Industrial ergon design-Anthrop importance, Act to product desi 5.	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen	materia curacy ules fo nd their ations, an-mac producti at, Rapid	al and pr and finis r Castin r importa ease of hine info vity. Jus d prototy	mocess se sh obtaina g, Forgir ance on maintena prmation t-in-time rping	able, proc ng, Machi products. Ince. Ergc exchange and Kanb	ess capa ning, Sh Selectior nomic cc . Process an Syste	Total bility studi eet metal of plastic Total onsideratio s sheet de m. Modern	Hrs es. Meth and W cs, rubb Hrs ns in pro etail and n approa	s. 9 nods of elding. er and 9 oduct their aches 9		
Procedures of 3. Various manufact improving tolerat Physical propert ceramics for pro- 4. Industrial ergon design-Anthrop importance, Act to product desi 5. Role of comput	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider oometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and mar	materia curacy ules fo nd their ations, an-mac producti at, Rapid	al and pr and finis r Castin r importa ease of hine info vity. Jus d prototy nt of m	maintena process se sh obtaina g, Forgir ance on maintena primation t-in-time ping anufactur	able, proc ng, Machi products. nnce. Ergo exchange and Kanb	ess capa ning, Sh Selectior nomic cc . Process an Syste	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern Total anufacturi	Hrs es. Meth and W cs, rubb Hrs ns in pro- tail and n approa	s. 9 nods of elding. er and 9 oduct their aches 9 base,		
Procedures of 3. Various manufact improving tolerat Physical propert ceramics for pro- 4. Industrial ergon design-Anthrop importance, Act to product desi 5. Role of computer Computer Integr	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and man grated Manufacturing, commu	materia curacy ules fo nd their ations, an-mac producti at, Rapio nageme nicatior	and finis r Castin r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo	maintena process se sh obtaina g, Forgir ance on maintena primation t-in-time rping anufactur rk, produ	able, proc ng, Machi products. ance. Ergo exchange and Kanb ring, creat uction flo	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern Total anufacturi sis, Group	Hrs es. Meth and W cs, rubb hrs in pro- etail and hr approa	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology,		
Procedures of 3. Various manufadi improving toleral Physical propertion ceramics for pro- 4. Industrial ergoni design-Anthropi importance, Action to product desi 5. Role of computer Computer Integrity Computer Aideo	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider oometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and mar	materia curacy ules fo nd their ations, an-mac producti at, Rapio nageme nicatior	and finis r Castin r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo	maintena process se sh obtaina g, Forgir ance on maintena primation t-in-time rping anufactur rk, produ	able, proc ng, Machi products. ance. Ergo exchange and Kanb ring, creat uction flo	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern Total anufacturi sis, Group	Hrs es. Meth and W cs, rubb hrs in pro- etail and hr approa Hrs ng data br Techr	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology,		
Procedures of 3. Various manufact improving tolerat Physical propert ceramics for pro- 4. Industrial ergon design-Anthrop importance, Act to product desi 5. Role of computer Computer Integr	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and man grated Manufacturing, commu	materia curacy ules fo nd their ations, an-mac producti at, Rapio nageme nicatior	and finis r Castin r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo	maintena process se sh obtaina g, Forgir ance on maintena prmation t-in-time ping anufactur rk, produ prating pr	ilection. able, proc ng, Machi products. ince. Ergc exchange and Kanb ring, creat uction flo oduct des	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys ign, mar	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern Total anufacturi sis, Group ufacture a	Hrs es. Meth and W cs, rubb I Hrs ns in pro- etail and n approa	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology, duction		
Procedures of 3. Various manufatimproving toleration Physical propertion ceramics for pro- 4. Industrial ergonic design-Anthropic importance, Action to product desi 5. Role of computer Computer Integrity Computer Aideon control	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and man grated Manufacturing, commu	materia curacy ules fo nd their ations, an-mac producti at, Rapio nageme nicatior	and finis r Castin r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo	maintena process se sh obtaina g, Forgir ance on maintena prmation t-in-time ping anufactur rk, produ prating pr	able, proc ng, Machi products. ance. Ergo exchange and Kanb ring, creat uction flo	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys ign, mar	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern Total anufacturi sis, Group ufacture a	Hrs es. Meth and W cs, rubb hrs in pro- etail and hr approa Hrs ng data br Techr	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology,		
Procedures of 3. Various manufatimproving toleration Physical propertion ceramics for pro- 4. Industrial ergonic design-Anthropic importance, Action to product desi 5. Role of computer Computer Integrity Computer Aideon control Text book (s)	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine considera bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and man grated Manufacturing, commu d product design and process.	materia curacy ules fo nd their ations, an-mac producti at, Rapio nication Plannir	al and pr and finis r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo ng. Integ	maintena process se sh obtaina g, Forgir ance on maintena prmation t-in-time rping anufactur rk, produ grating pr To	able, proc ng, Machi products. Ince. Ergc exchange and Kanb ring, creat uction flo oduct des tal hours t	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys ign, man o be taug	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern Total anufacturi sis, Group oufacture a	Hrs es. Meth and W cs, rubb ns in pro- etail and n approa Hrs ng data o Techr and proc al Hrs	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology, duction 45		
Procedures of 3. Various manufact improving tolera Physical propert ceramics for pro- 4. Industrial ergon design-Anthrop importance, Act to product desi 5. Role of computer Computer Integ Computer Aideo control Text book (s) 1 Niebel, B.	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and man grated Manufacturing, commu d product design and process. W., and Draper, A.B., Product	materia curacy ules fo nd their ations, an-mac producti at, Rapio nication Plannir	al and pr and finis r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo ng. Integ	maintena process se sh obtaina g, Forgir ance on maintena prmation t-in-time rping anufactur rk, produ grating pr To	able, proc ng, Machi products. Ince. Ergc exchange and Kanb ring, creat uction flo oduct des tal hours t	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys ign, man o be taug	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern Total anufacturi sis, Group oufacture a	Hrs es. Meth and W cs, rubb ns in pro- etail and n approa Hrs ng data o Techr and proc al Hrs	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology, duction 45		
Procedures of 3. Various manufact improving tolera Physical propert ceramics for pro- 4. Industrial ergon design-Anthrop importance, Act to product desi 5. Role of computer Computer Integ Computer Aideo control Text book (s) 1 Niebel, B. Tokyo, 19	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and man grated Manufacturing, commu d product design and process. W., and Draper, A.B., Product	materia curacy ules fo nd their ations, an-mac producti nageme nication Plannir design	and finis r Castin r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo ng. Integ and prot	maintena process se sh obtaina g, Forgir ance on maintena prmation t-in-time pring anufactur rk, produ grating pr To cess Eng	able, proc ng, Machi products. ance. Ergo exchange and Kanb ring, creat uction flo oduct des tal hours t	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys ign, mar o be taug	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern <b>Total</b> anufacturi sis, Group ufacture a oht <b>Tota</b>	Hrs es. Meth and W cs, rubb hrs in pro- etail and n approa Hrs ng data o Techr and proc al Hrs	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology, duction 45 Ltd.,		
Procedures of 3. Various manufact improving tolera Physical propert ceramics for pro- 4. Industrial ergon design-Anthrop importance, Act to product desi 5. Role of computer Computer Integ Computer Aideo control Text book (s) 1 Niebel, B. Tokyo, 19	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and man grated Manufacturing, commu d product design and process. W., and Draper, A.B., Product W., and Gupta, R.C., Product	materia curacy ules fo nd their ations, an-mac producti nageme nication Plannir design	and finis r Castin r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo ng. Integ and prot	maintena process se sh obtaina g, Forgir ance on maintena prmation t-in-time pring anufactur rk, produ grating pr To cess Eng	able, proc ng, Machi products. ance. Ergo exchange and Kanb ring, creat uction flo oduct des tal hours t	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys ign, mar o be taug	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern <b>Total</b> anufacturi sis, Group ufacture a oht <b>Tota</b>	Hrs es. Meth and W cs, rubb hrs in pro- etail and n approa Hrs ng data o Techr and proc al Hrs	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology, duction 45 Ltd.,		
Procedures of 3. Various manufact improving tolera Physical propert ceramics for pro 4. Industrial ergon design-Anthrop importance, Act to product desi 5. Role of computer Computer Integ Computer Aideo control Text book (s) 1 Niebel, B. Tokyo, 19 2 Chitale, A	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and man grated Manufacturing, commu d product design and process. W., and Draper, A.B., Product W., and Gupta, R.C., Product	materia curacy ules fo nd their ations, an-mac producti nageme nication Plannir design	and finis r Castin r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo ng. Integ and prot	maintena process se sh obtaina g, Forgir ance on maintena prmation t-in-time pring anufactur rk, produ grating pr To cess Eng	able, proc ng, Machi products. ance. Ergo exchange and Kanb ring, creat uction flo oduct des tal hours t	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys ign, mar o be taug	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern <b>Total</b> anufacturi sis, Group ufacture a oht <b>Tota</b>	Hrs es. Meth and W cs, rubb hrs in pro- etail and n approa Hrs ng data o Techr and proc al Hrs	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology, duction 45 Ltd.,		
Procedures of 3. Various manufadir improving tolerat Physical propertion ceramics for pro- 4. Industrial ergonic design-Anthropic importance, Action to product desite 5. Role of computer Computer Integrity Computer Aideor control Text book (s) 1 Niebel, Bartokyo, 19 2 Chitale, A Delhi, 200 Reference(s)	value analysis – cost reduction, cturing processes, degree of ac ances. Basic product design r ties of engineering materials a duct design nomics: Man-machine consider bometry, Design of controls, ma dvanced techniques for higher p gn; quality function developmen er in product design and man grated Manufacturing, commu d product design and process. W., and Draper, A.B., Product W., and Gupta, R.C., Product	materia curacy ules fo nd their ations, an-mac producti tt, Rapid nageme nication Plannir design Design	and finis r Castin r Castin r importa ease of hine info vity. Jus d prototy nt of m n netwo ng. Integ and prototy and Ma	anufactur rk, produ grating pr cess Eng anufactur	ilection. able, proc ng, Machi products. ince. Ergc exchange and Kanb ring, creat uction flo oduct des tal hours t ineering, I ing, Prent	ess capa ning, Sh Selectior nomic cc . Process an Syste ion of m w analys ign, man <u>o be tauç</u> Mc Graw ice Hall	Total bility studie eet metal of plastic Total onsideratio s sheet de m. Modern <b>Total</b> anufacturi sis, Group ufacture a ght <b>Tota</b> Hill – Kog of India P	Hrs es. Meth and W cs, rubb hrs in pro- etail and n approa Hrs ng data o Techr and proc al Hrs	s. 9 nods of elding. er and 9 oduct their aches 9 base, nology, duction 45 Ltd.,		

CBIT	Autonomous Regulation	Semester-1				AY - 2006-17		
Department	Mechanical Engineering	Progra	amme C	ode & Na	me	M.E. CAD/CAM		
Course Code	Course Name	Hours	/Week		Credit	Maximum Marks		
		L T P C			E	- 1	Total	
16MEC 106	CAD/CAM LABORATORY	0	0	3	2		50	50

## Objective(s):

- 1. To produce CAD drawings which communicate the appropriate manufacturing details, standards, and specifications..
- 2. To effectively communicate with others using oral, written, and graphical methods and procedures..
- 3. To function effectively on teams or on group projects and assume leadership roles when appropriate..
  - 4 To introduce STUDENTS to the basic tools of computer-aided design (CAD) and computeraided manufacturing (CAM)
  - 5 To understand the basic analytical fundamentals that are used to create and manipulate geometric models in a computer program
  - 6 To prepare the student to be an effective user of a CAD/CAM system.

Outcome(s): After the completion of the course, students will be able to

- 1. use parametric CAD software for geometric modeling of mechanical designs
- 2. visualize of machine components and assemblies before their actual
- fabrication through modeling, animation, shading, rendering, lighting and coloring
- 3. apply of CAD computational analysis tools to engineering design.
- 4. create a complete CAD documentation for an engineering design.
- 5. model complex shapes including freeform curves and surfacesExplain the basic concepts of CNC programming and machining
- 6. implement CNC programs for milling and turning machining operations

## List of Exercises:

# CAD

- 1. Understanding of various CAD commands and creating simple objects.
- 2. Understanding of holes, cuts and model tree relations.
- 3. Creation shafts, rounds, chamfers and slots.
- 4. Sketch Tools & Datum planes.
- 5. Creation of objects by revolved features, patterns and copies, sweeps and blends.
- 6. Creation of engineering drawing details such as dimensioning, sectional views, adding esthetics.
- 7. Assembling of part models using constraints with bill of materials.
- 8. Assembly operations part modifications, adding another assembly features display.
- 9. Mass properties and tolerance analysis.

## CAM

- 1. Understanding of CNC Machines and CNC Programming and Creation of 2-D contour Pockets, Slots
- 2. Drills and Facing, 2-D high Speed blend
- 3. Surface Roughing for Bottle die
- 4. Surface finishing for Phone die
- 5. Manufacturing of Crane Hook
- 6. Manufacturing of Connecting Rod
- 7. Manufacturing of Turbine Blade
- 8. 3-D Machining using ball nose cutters

CBIT	Autonomous Regulation	Semester-1				AY - 2006-17		
Department	Mechanical Engineering	Programme Code & Name				M.E. CAD/CAM		
Course Code	Course Name	Hours	/Week		Credit	Maximum Marks		
	COMPUTATIONAL	L	L T P			E	Ι	Total
16MEC 107	LABORATORY	0	0	3	2		50	50

## Objective(s)

- 1. To understand how and why finite element technique works
- 2. To learn the selection of the element type for a defined problem.
- 3. To use ANSYS package to solve engineering problems for a variety of application
- 4. To learn to use finite element analysis in design
- 5. To know various fields of engineering where these tools can be effectively used to improve the output of a product
- 6. To impart the fundamental knowledge on using various analytical tools like ANSYS Engineering Simulation.

## Outcome(s):

Students will be able to:

- 1. Use the tools like ANSYS in solving real time problems and day to day problems.
- 2. Apply the Finite Element Method for the calculation stresses, strains and deformations in any component
- 3. critically evaluate the model results in comparison to simplified analytical solutions
- 4. Versatility in using these tools for any engineering and real time applications.
- 5. Gain knowledge on utilizing these tools for a better project in their curriculum
- 6. Face industry with confidence in using these tools in their respective jobs

# List of Experiments:

- 1. Introduction to Finite Element Analysis Software.
- 2. Static analysis of a corner bracket.
- 3. Statically indeterminate reaction force analysis.
- 4. Determination of Beam stresses and Deflection.
- 5. Bending analysis of a Tee-shaped beam.
- 6. Analysis of cylindrical shell under pressure.
- 7. Bending of a circular plate using axisymmetric shell element.
- 8. Stress analysis in a long cylinder.
- 9. Solidification of a casting.
- 10. Transient Heat transfer in an infinite slab.
- 11. Transient Thermal stress in a cylinder.
- 12. Vibration analysis of a simply supported beam.
- 13. Natural frequency of a motor generator.
- 14. Thermal structural contact analysis of two bodies.
- 15. Drop test of a container (Explicit Dynamics).

16MEC 110

#### MINIPROJECT GUIDELINES

Instruction Sessional Credits

#### 2 Hrs / week 50 Marks 01

#### **Objectives:**

First year ME students will each do a 14-week mini project, each generally comprising about one week of prior reading, twelve weeks of active research, and finally a presentation of their work for assessment (see assessment information below). Each student will be allotted to a Faculty supervisor for mentoring.

Mini projects should present students with an accessible challenge on which to demonstrate competence in research techniques, plus the opportunity to contribute something more original. Mini projects should have inter disciplinary/ industry relevance. The students can select a mathematical modeling based/Experimental investigations or Numerical modeling. All the investigations are clearly stated and documented with the reasons/explanations. All the projects should contain A clear statement of the research objectives, background of work, Literature review, techniques used, prospective deliverables, benefit from this [line of] research, Detailed discussion on results, Conclusions and references.

#### Outcomes:

Students are able to

- 1. Formulate a specific problem and give solution
- 2. Develop model/models either theoretical/practical/numerical form
- 3. Solve, interpret/correlate the results and discussions
- 4. Conclude the results obtained and write the documentation in standard format

#### Assessment:

1. 50 % of marks for a scientific report on the project.

Regarding the formatting and structure, the report should be written as a journal article using the style file of a journal appropriate for the field of the research (which journal format is most appropriate should be agreed between student and supervisor). If the journal you selected has a page limit, it can be ignored but the report should not exceed 8000 words (common sense should be used if there are a lot of equations).

Regarding content, the report should be understandable by your fellow students, so the introduction and literature review could be a bit more detailed than in a research paper. The results and discussions are in elaborate form and at end conclusions and include references.

2. 50 % of marks for an oral presentation which will take place at the end of the semester and evaluation by a committee consist of Supervisor, one senior faculty and Head of the department or his nominee.