DEPARTMENT OF MECHANICAL ENGINEERING

SCHEME OF INSTRUCTION AND SYLLABI OF

M.E.

(Mechanical Engineering)

Specialization:

CAD/CAM



2013

CHAITANYA BHARATHI INSTITUTE OF TECHNOLOGY (Autonomous) Affiliated to Osmania University Hyderabad – 500 075, A.P., INDIA

SI. No	Subject		ds per ek	Duration (Hrs)	Max.	Marks	Credits
INO		L/T	D/P		Univ. Exam	Sessional	
			Seme	ster - I	· · · ·		
1.	Core	4		3	75	25	3
2.	Core	4		3	75	25	3
3.	Core / Elective	4		3	75	25	3
4.	Core / Elective	4		3	75	25	3
5.	Core / Elective	4		3	75	25	3
6.	Elective	4		3	75	25	3
7.	Laboratory - I		3			50	2
8.	Seminar - I		3			50	2
	Total	24	6		450	250	22
		•	Seme	ster - II	••		
1.	Core	4		3	75	25	3
2.	Core	4		3	75	25	3
3.	Core / Elective	4		3	75	25	3
4.	Core / Elective	4		3	75	25	3
5.	Core / Elective	4		3	75	25	3
6.	Elective	4		3	75	25	3
7.	Laboratory - II		3			50	2
8.	Seminar - II		3			50	2
	Total	24	6		450	250	22
			Semes	ster – III			
1.	Project Seminar*		6			100**	4
			Semes	ster – IV			
1.	Dissertation		6		Viva - Voce (Grade ***)		16

Scheme of Instruction & Examination M.E. (Mechanical Engineering) 4 Semesters (Full Time)

Note: Six core subjects, Six elective subjects, Two Laboratory Courses and Two Seminars should normally be completed by the end of semester II.

- * Project seminar presentation on the topic of Dissertation only
- ** 50 marks awarded by the project guide and 50 marks by the internal committee.
- *** Excellent/Very Good/Good/Satisfactory/Unsatisfactory

Scheme of Instruction & Examination Post Graduate course in Mechanical Engineering

with specialization in CAD/CAM.

SI. No	Syllabus Ref.No.	-	Schen Instrue		Schem	e of Exam	nination	
			Period wee	-	Duration	Мах	. Marks	
			L/T	D/P	in Hours	Univ. Exam	Sessionals	Credits
		CORE SUBJECTS						
1.	ME 501	Automation	4		3	75	25	3
2.	ME 502	Finite Element Techniques	4		3	75	25	3
3.	ME 503	Computer Aided Modeling and Design	4		3	75	25	3
4.	ME 504	Computer Integrated Manufacturing	4		3	75	25	3
5.	ME 505	Failure Analysis and Design	4		3	75	25	3
6.	ME 506	Computer Aided Mechanical Design and Analysis	4		3	75	25	3
		ELECTIVES						
1.	ME 511	Integrated Mechanical Design	4		3	75	25	3
2.	ME 512	Robotic Engineering	4		3	75	25	3
3.	ME 513	Programming Methodology and Data Structures	4		3	75	25	3
4.	ME 514	Optimization Techniques	4		3	75	25	3
5.	ME 515	Vibrations Analysis and Condition Monitoring	4		3	75	25	3
6.	ME 516	Engineering Research Methodology	4		3	75	25	3
7.	ME 517	Tribology In Design	4		3	75	25	3
8.	ME 518	Advanced Mechanics Of Materials	4		3	75	25	3
9.	ME 519	Mechanics of Composite Materials	4		3	75	25	3
10.	ME 520	Theory of Elasticity and Plasticity	4		3	75	25	3
11.	ME 521	Experimental Techniques and Data Analysis	4		3	75	25	3
12.	ME 522	Design for Manufacture	4		3	75	25	3
13.	ME 523	Data Base Management Systems	4		3	75	25	3
14.	ME 524	Fracture Mechanics	4		3	75	25	3
15.	ME 525	Design of Press Tools	4		3	75	25	3
16.	ME 526	Design of Dies	4		3	75	25	3
17.	ME 602	Computational Fluid Dynamics	4		3	75	25	3
18.	ME 527	Rapid Prototyping Principles & Applications	4		3	75	25	3
19.		Flexible Manufacturing Systems	4		3	75	25	3
20.		Non-Traditional Machining & Forming	4		3	75	25	3
21.	ME 530	Product Design and Process Planning	4		3	75	25	3
	DEP	ARTMENTAL REQUIREMENTS						
1.	ME 551	CAD/CAM Lab (Lab –I)		3			50	2
2.	ME 552	Computation Lab (Lab –II)		3			50	2
3.	ME 553	Seminar – I		3			50	2
4.	ME 554	Seminar – II		3			50	2
5.	ME 555	Dissertation & Project Seminar		6				4
6.	ME 556	Dissertation		6		Viva- Voce (*Grade)		16

Course duration: 4 Semesters (Full – Time)

*Excellent / Very Good / Good / Satisfactory / Unsatisfactory

CBIT		utonom		-		1		
Department	Mechanical Engineering	U	amme (Code	& Name	M.E	E. (CAD/CA	AM)
<u> </u>		nester-l						
Course Code	Course Name	Hours	/Week		Credit		um Marks	
		L	Т	Р	С	E	1	Total
ME501	AUTOMATION	4	0	0	3	75	25	100
Objective (s)	To learn & understand basic con- industries. To understand Detroit type automa To conceptualize & design assemb To learn about automated material	tion & flo ly line ba handling	ow lines alancing g syster	s. g. ns	Ū	lincance	in manua	actunn
Outcome(s)	To design effective and appropriate Ability to conceptualize and design Ability to implement line balancing Ability to understand and develop operations. Ability to design, implement and us	automa concepts automa	ted flow in prod ted ma	r lines ductio aterial	n and ass handling	system	suitable fo	or plan
1 UNIT – I							Total Hrs	7
Information Pro Strategies, Proc Break-Even Ana	finition of automation, Types of pro ocessing in Manufacturing, Product luction Economics: Methods of Eval lysis, Unit cost of production, Cost of	ion con uating Ir	cepts ivestme	and I ent Al	Mathema [.] ternatives	tical Mo s, Costs	dels, Auto in Manufa process.	omation cturing,
2 UNIT – II							Total Hrs	9
The Line Balance to improve the I Automated Asso	ms and Line Balancing: The Assemb sing Problem, Methods of Line Baland Line Balancing, Flexible Manual Ass embly, Types of Automated Assem y Machines, Analysis of a Single Stati	cing, Cor embly Li oly Syst	nputeri nes. <i>A</i> ems, F	zed Li <i>utoma</i> Part F	ine Balan Ited Asse eeding D	cing Met	hods, Othe s <i>tems:</i> De	er ways sign for
4 UNIT – IV				aonin			Total Hrs	9
Analysis for Mat Systems. Autom Carousel Storag	erials Handling: The material hand erial Handling Systems, Design of the nated Storage Systems: Storage Syst le Systems, Work-in-process Storage	e System em Perfe	i, Conve ormanc	eyor S e, Aut	Systems, A comated S	Automate Storage/F age with	ed Guided Retrieval Sy Manufactu	Vehicle ystems iring.
5 UNIT – V							Total Hrs	9
Principles and I Other Contact II Manufacturing S Tools: Simulatio	ection and Testing: Inspection and t Methods, Sensor Technologies for A nspection Methods, Machine Vision, Systems: Role of Performance Moo In Models, Analytical Models. The F ed Factory, Human Workers in the Fu	outomate Other o deling, F <i>uture Au</i>	ed Inspe ptical li Perform <i>itomate</i>	ection nspec ance <i>d Fac</i>	, Coordin tion Meth Measure <i>tory:</i> Tren	ate Mea ods. <i>Mo</i> s, Perfo nds in M	Isuring Ma <i>deling Aut</i> rmance M anufacturii	ichines omated odeling
Total hours to be t								43
Text book (s)								
^L Education		is and \overline{C}	ompute	er Inte	grated Ma	anufactur	ing Doors	
2 C.Rav Asfa							ing, rears	on
							ing, reais	on
Reference(s)	Asia. ahl, Robots and manufacturing Sutom	ation, Jo	ohn Wile	ey and	d Sons Ne	ew York.		
Reference(s) 1 N.Viswana Hall India F	Asia. ahl, Robots and manufacturing Sutom dham and Y.Narahari, Performance N	ation, Jo Aodeling	ohn Wile of Auto	ey and omate	d Sons Ne	ew York. cturing S	bytems, Pri	ntice

CBIT		Autonomous Regulation							
Department	Mechanical Engineering	Pr	ogramn Na	ne Co Ime	de &	M.E. T	hermal E	ngine	eering
		emester			n	1			
Course Code	Course Name	Hours	s/Week	-	Credit		um Marks		
		L	T	Р	С	E		Т	otal
ME502	FINITE ELEMENT TECHNIQUES	4	0	0	3	75	25		100
Objective (s)	Identify mathematical model fo students to formulate the desi engineering simulations using Fi	gn probl nite Elerr	lems in nent Ana	ito FE alysis	A. Enat	ole the s	students	to p	erform
Outcome(s)	students are able to solve the concepts to develop higher ord analysis								
1 UNIT – I	•						Total H	rs	9
Strain-Displace One Dimension functions. Pote	Finite Element Method of solving fi ment relations. Stress-strain relation nal Problem: Finite element moon ntial Energy approach : Assembly ment of boundary conditions. Quad	ns. [`] eling. L of Glob	ocal, n al stiffn	atural ess m	and glo	bal coo	rdinates	and	shape
2 UNIT – II	· · · · · · · · · · · · · · · · · · ·						Total H	rs	9
	and a rotational degree of freedor		1110000.						
element. 3 UNIT – III . Finite element treatment of b integration. Finite elements.	ams: Element stiffness matrix for t modeling of two dimensional st oundary conditions. Two dimens te element modeling of Axisymmet	ess ana onal fo tric solic	alysis p ur node	roblen ed isc	ns with oparamet	constant ric elem	Total H strain tria ents and	rs angle nun	9 es and nerical
element. 3 UNIT – III . Finite element treatment of b integration. Fini- elements. Convergence re 4 UNIT – IV	t modeling of two dimensional st oundary conditions. Two dimens te element modeling of Axisymmer equirements and geometric isotrop	ress ana onal for itric solic	alysis p ur node ds subje	roblen ed isc ected c	ns with o paramet of axisym	constant ric elem ametric lo	Total H strain tria ents and bading with	rs angle nun h tria	9 es and nerical ngular 9
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element. 3 UNIT – III . Finite element treatment of b integration. Fini elements. Convergence re 4 UNIT – IV Steady state h analysis of thin Time dependen Dynamic analy beam. Evaluation Analysis of a un 5 UNIT – V	t modeling of two dimensional st oundary conditions. Two dimens te element modeling of Axisymmer equirements and geometric isotropy eat transfer analysis: One dimer plate. It field problems: Application to one sis: Formulation of finite element on of Eigen values and Eigen vector inform shaft subjected to torsion us	ess ana onal for tric solic sional a dimens modelin rs. ng Finite	alysis p ur node ds subje nalysis sional he g of Ei e Eleme	roblen ed isc ected c of a eat flo gen v nt Ana	ns with oparamet of axisym fin and w in a ro- alue pro alysis.	constant ric elem imetric lo two dim d.	Total H strain tria ents and bading with Total H ensional	rs nun h tria rs cond	9 es and nerical ngular 9 luction
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CBIT			omous I			1			
Department	Mechanical Engineering	Pr	ogramm Na	ne Co me	de &	M.E. T	hermal Er	ngineer	ing
	·	Semeste	r-I			•			
Course Code	Course Name	Hours	<u>s/ Week</u>	[Credit	Maximu	um Marks		
		L	Т	Р	С	E		Tot	al
ME503	COMPUTER AIDED MODELING AND DESIGN	4	0	0	3	75	25	100)
Objective (s)	Understand the basic and a application of CAD in geometr and Standards Introduce Ge modeling. Students will develo of curved surface representati Euler operators Understand dimensional geometric transfor Translation, Scaling, Rotation, a sequence of transforma using homogeneous coordinati modeling and analysis packag Upon completion of this course	ic modelin cometric p an unde on. Explai and be ormations Reflection ations in es. Have es e, the stuc	ng. Unde Modelin erstandir n solid r able to on two n, Shear to a an ove	erstan g to ng of mode o per o and ring, E single rview be ab	nd the CA the stud the theor ling repr fform tw three-di Be able to e comp of advan	AD Datab dents to ry and co resentatio vo-dimen mension o combin o site 3: ntages a	base, Data curve ar onstruct the on scheme isional a al objects ie the para x3 and nd disadv	Exchand and sur e elem es and and th ameters 4x4m antage	inge face ents the ree- ding s for atrix s of
	Ability to apply mathematics, software they use in the labora this theory - geometry manipu analysis. Evaluate mathemat	atory. Solv lation, cu	ve engir rve and	neerin surfa	g problei ice repre	ms on th sentatior	ne topics	include te elen	ed in hent
	solids. Differentiate between t of geometric modeling, Effecti	ne modeli	ng techr	nique	s, Catego	orise and	apply the	e princi	ples
1 UNIT – I	solids. Differentiate between t of geometric modeling, Effecti	ne modeli vely empl	ng techr oy solid	nique: mode	s, Catego eling too	orise and ls.	Total H	e princi rs	
Criteria for sele	solids. Differentiate between the of geometric modeling, Effective ction of CAD workstations, S	ne modeli vely empl	ng techr oy solid	nique: mode	s, Catego eling too	orise and ls.	apply the	e princi rs	ples
Criteria for sele modeling, entitie 2D & 3D Geome	solids. Differentiate between to of geometric modeling, Effective ection of CAD workstations, S ss, 2D & 3D Primitives. etric Transformations: Translation	ne modeli vely empl higle D	ng techr oy solid esign F	nique mode Proces	s, Catego eling too ss, Desig	orise and ls. gn criter	Total H ia, Geom	e princi rs etric	ples 9
Criteria for sele modeling, entitie 2D & 3D Geome	solids. Differentiate between the of geometric modeling, Effective ction of CAD workstations, Ses, 2D & 3D Primitives.	ne modeli vely empl higle D	ng techr oy solid esign F	nique mode Proces	s, Catego eling too ss, Desig	orise and ls. gn criter	Total H Total H ia, Geom aring, conl	e princi rs etric	ples 9
Criteria for sele modeling, entitie 2D & 3D Geome Graphics standa 2 UNIT – II Wire frame mod	solids. Differentiate between the of geometric modeling, Effective ction of CAD workstations, Ses, 2D & 3D Primitives. etric Transformations: Translationards: GKS IGES, PDES. eling: Curves: Curve representat	ne modeli vely empl higle D n, Scaling, on. Analy	ng techi oy solid esign F , Rotatic	nique: mode Proces on, Re	s, Catego eling too ss, Desig eflection a	orise and ls. gn criter and Shea	Total H Total H ia, Geom aring, conl	e princi rs letric atenati	ples 9
Criteria for sele modeling, entitie 2D & 3D Geome Graphics standa 2 UNIT – II Wire frame mod	solids. Differentiate between to of geometric modeling, Effective ection of CAD workstations, Ses, 2D & 3D Primitives. etric Transformations: Translation ards: GKS IGES, PDES.	ne modeli vely empl higle D n, Scaling, on. Analy	ng techi oy solid esign F , Rotatic	nique: mode Proces on, Re	s, Catego eling too ss, Desig eflection a	orise and ls. gn criter and Shea	Total H Total H ia, Geom aring, conl	e princi rs letric atenati	9 9 on.
Criteria for sele modeling, entitie 2D & 3D Geome Graphics standa 2 UNIT – II Wire frame mod Synthetic curves 3 UNIT – III	solids. Differentiate between the of geometric modeling, Effective ction of CAD workstations, Ses, 2D & 3D Primitives. etric Transformations: Translationards: GKS IGES, PDES. eling: Curves: Curve representat	ne modeli vely empl higle D n, Scaling, on. Analy 3S.	ng techr oy solid esign F , Rotatic tic curve	nique: mode Proces on, Re	s, Catego eling too ss, Desig eflection a	orise and ls. gn criter and Shea	Total H Total H ia, Geom aring, conl Hrs se, Conis.	e princi rs letric atenati	9 0n. 9
Criteria for sele modeling, entitie 2D & 3D Geome Graphics standa 2 UNIT – II Wire frame mod Synthetic curves 3 UNIT – III Surface Modelin Analytic Surface	solids. Differentiate between to of geometric modeling, Effective ection of CAD workstations, Ses, 2D & 3D Primitives. etric Transformations: Translation ards: GKS IGES, PDES. eling: Curves: Curve representat s – Cubic, Bezier, B-Spline, NUR og: Surface entities, Surface Representate – Plane Surface, Ruled Surface	higle D higle D h, Scaling, on. Analy BS. esentation o, Surface	ng techr oy solid esign F , Rotatic tic curve	niques mode Proces on, Re es – li	s, Catego eling too ss, Desiq eflection a nes, Circ	orise and ls. gn criter and Shea Total les, Ellip	Total H ia, Geom aring, conl Hrs se, Conis.	e princi rs letric atenati	9 0n. 9
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			Na	me				••••••
Course Code	Course Name	mester			Cro dit	Maxim	una Martica	
Course Code		Hours	/ Week	Р	Credit C	E	um Marks	Total
ME504	COMPUTER INTEGRATED MANUFACTURING	4	0	Р 0	3	75	25	100
Objective (s)	To develop an understanding o depth understanding of control and retrieval systems. To take u	of mar	nufactu	ring, a	automate	ed materi	al handli	
Outcome (s)	Ability to select the manufac store the details by database of lean manufacturing to development of a product.	turing mana	proces gemer	s for nt sys	the dev tems. A	elopmer bility to a	nt of a pl apply the	e concepts
1 UNIT – I	lanufacturing, Types of Manufactu				Total			9
software. Fundame Engineering: Defin Engineering, Chara Concurrent Engine (PLM), Collaborativ	concept or technology, Evolution entals of Communication: Communition, Sequential Engineering V acteristics of concurrent Engineer ering Techniques, Integrated Prove Product Development.	nicatior ′ersus ing, Fra	ns Matr Concur amewor	ix. Pro rent k for i nent(I	oduct De Engineer integratic PD), Pro	velopme ring, Ber on of Life duct Life	nt Cycle, nefits of -cycle ph -Cycle M	Concurrent Concurrent ases in CE,
2 UNIT – II	facturing Data: Types, sources; D				Total Hrs		9	
models, Database (SQL): Basic struc Language (store, Database. SQL as SQL Access, Syba 3 UNIT – III	Management System, DBMS Ar cture, Data definition Language (retrieve, update, delete). Illus s a Knowledge Base Query Lang se, DB2. Product Data Managem	chitectu Create, stration guage. ent (PD	ure, Qu , Alter, of Cre Featur 0M), Ad	ery L Drop eating es of vanta	anguage , Trunca and M commer <u>ges of P</u> Total	, Structu te, View) anipulatir cial DBN DM. Hrs	ral Query , Data M ng a Ma /IS: Orac	y Language Ianipulation Inufacturing Ie, MySQL, 9
Product Design:	Needs of the market, Design	and	Engine	orina	The d	esian P	rococc	
	DFM): Component Decian Decia							
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Steps in developinComputer-AidedPlanning (MRP –IApproaches: MachCell Design. ShopLogic Controllers,Types of FlexibilityMachine Layout, Log4UNIT – IVIntroduction to NetWAN; Selection ofMethods, SignalingNetwork InterconneCIM Models: ESPCorporation Model5UNIT – VLean ManufacturinValue of Product, Oof Lean Productionto Agile and Web ETotal hours to be taText book (s)1S.Kant Vajpay2Nanua Singh:	ng a process plan, Variant and Process Planning. Material Re- II), Cellular Manufacturing: Desi- nine–Component Group Analysis, -floor Control: Data Logging and Sensor Technology. Flexible Ma y, Layout Considerations: Linear S oop Layout; Operational Problems working, Principles of Networking Network Technology: Communic g methods; Network Architecture ection and Devices, Network Perfor PRIT-CIM OSA Model, NIST-AM , IBM Concept of CIM.	n for As Gener quireme gn of Simila I Acquis Inufactu Single N s of FM g, Netw ation m res and ormanc IRF Mc Manuton Wast upply C	ssembly rative F ents Pl Cellular rity Coe sition, A uring Sy Machine S. FMS ork Te edium, d Proto e. Fran odel, S facturin te, Rela hain, B	2. Con Process lannin r Mar efficie Autom ystem e Lay bene bene beness rmino Networ iemer g, Ch ationsl enefit	nputer-A ss Plann ng (MRF nufacturin nts-Base nated Da s: Physi- out, Circ efits. Total logy, Typ ork Topo OSI Mo ork for Ent naracteris hip of Wa s of Lea	ided Prod ing, Fea (), Manung Syste (d Approd ta Collect (cal Compular Mac (cal Computer Mac (cal Comp	cess Plar ature Rec ifacturing ems, Cell aches. E- ction, Pro ponents hine Layo etworks: edium acc P & TO vide Integ I, Digital Lean Mai rofit, Fou acturing. I	ning: Basic cognition in Resource Formation valuation of ogrammable of an FMS. out, Cluster 9 LAN, MAN, cess control P, TCP/IP, gration. Equipment 9 nufacturing, ar Functions Introduction 45
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CBIT	A	utonor	nous R	Regula	ation			
Department	Mechanical Engineering		ogramm Na	ne Co		М	.E. (CAD	/CAM)
	Se	mester	-1			•		
Course Code	Course Name	Hours	/Week		Credit	Maximu	im Marks	
		L	Т	Р	С	E		Total
ME 505	FAILURE ANALYSIS AND DESIGN	4	0	0	3	75	25	100
Objective (s) Outcome (s)	Failure analysis and design provi fracture including conceptual design Under the basics of fracture, cylin buckling. Plate with thick and thin course introduces standard design Design concepts along with fatigue	gn, eml drical c cases <u>procec</u> e, fractu	bodime configura for sta dures ar ure and	nt des ation tic an <u>nd fail</u> cracl	sign and is analyz id dynam ure pher < propag	failure m zed (thick nic loadin nomenon	node effe and thir g is disc	ct analysis. cases) for ussed. The
1 UNIT – I	through creative thinking methodol	ogies a	ind num	nerica	IS. Total			0
	design- The design process-Consi	idoratio	nc of (Good				9 f Docian
Organization fo	r design – Computer Aided Engine Identification – Competition Benc Product Design Specifications- Huma	ering - h mark	-Concu king. Id	rrent entific	Enginee cation of	ring – P custom	roduct a er needs	nd process - customer
2 UNIT – II					Total Hrs		9	
decomposition- Product Archite Modeling – Sim 3 UNIT – III	Problem Solving –Creativity methods Generating design concepts-Axioma ecture-Configuration Design- Paran ulation – Design for Reliability –Intro menon – Elastic Buckling of circular	atic De netric I duction	sign – Design. to Rob	Evalı Role ust D	uation m e of mo esign-Fa Total	ethods-E dels in o ilure moo Hrs	mbodime design-M le Effect	ent Design- athematical Analysis. 9
	nders or tubes under external press			supp	orts on E	lastic Bu	ckling of	Cylinders –
	combined External pressure and axia	al loadi	ng.					
4 UNIT – IV					Total			9
Fracture types	and determination of stress patte in tension—Fatigue crack growth– F vessels-Thermal stress fatigue.							
5 UNIT – V	5			Т	otal Hrs		9	
	hrough cracks emanating from hole ing-Fatigue crack growth binder- N analysis							
Total hours to b	•							45
Text book (s)	<u> </u>							
Internation	eorge E., "Engineering Design al Editions, Singapore, 2000.						ach", M	cGraw Hill,
2 Pahl, G, a	nd Beitz, W.," Engineering Design", S	Springe	r – Verl	ag, N	Y. 1984.			
References								
Publisher,							erdhoff li	nternational
	Kumar, "Elements of Fracture Mecha							
	arvey, Theory and Design of Pressur							
4 Henry H. E	Bedner, "Pressure Vessels, Design H	land Bo	ok, CB	S pub	lishers a	nd Distril	outors, 19	987

CBIT	A	lutono	mous I	Regul	ation			
Department	Mechanical Engineering	Pro	ogramm Na		de &	M.	E. (CAD/	CAM)
		nester-			1	n		
Course Code	Course Name	Hours	/Week		Credit		m Marks	
ME 506	COMPUTER AIDED MECHANICAL DESIGN AND ANALYSIS	L 4	0	P 0	С 3	Е 75	25	Total 100
Objective (s)	Ability to develop the necessary pressure vessels. To achieve find plates with various loading and l materials and structures using appreciate the importance of vibr concepts of matrix algebra. Stud methods.	undame bounda fracture ations i dents a	ental ur ry conc e mech n mech ble to	nderst litions anics nanica under	tanding o a Unders approad al design stand pr	of the the standing o ches. Fu and to ur ocedures	eory of t design pr Ily under nderstand for Finit	bending of inciples of stand and the basic e element
Outcomes (s)	Develop an ability to apply kno solving engineering problems. I problems for a given application the desired needs. Class R accomplishment of this outcome Be proficient in the use of softwa	Demons .) An a toom I e. An a	strate ti bility to Examin bility to	he ab designation designation	ility to ic gn a syst Score gn, analy design.	lentify, fo em or a above ze and in	ormulate compone 60% de	and solve int to meet monstrate
1 UNIT-I	re Vessels: Introduction and constru				Total			9
their significance. 2 UNIT-II Stresses in flat pl directions, Therm	ates: Introduction, Bending of plate al stresses in plates, Bending of cir	in one	directio	on, Be	Total Hrs	s plate in t	9 wo perpe	endicular
loaded plates of o	constant thickness.			- 1	Total	Ure		9
Fracture Mechan release rate of D0 toughness, Elasti Path independen	ics: Introduction, Modes of fracture CB specimen; Stress Intensity Fact c plastic analysis through J-integra ce, stress strain relation, Strain Ene	or: SIF'	s for ed d: Rele	lge ar evanc	vsis, Ener nd centre e and sc /s J-integ	rgy releas line crac ope, Defi gral.	k, Fractu	inergy re
4 UNIT-IV					Total			9
lateral vibration, S	plems: Properties of Eigen values a Sturm sequence. Subspace iteration lems applied to stepped beams and	n and L						
5 UNIT-V					Total			9
Dynamic Analysis	s: Direct integration method, Centra	al differ						
method, Mode su response, Rayleig	perposition, Single degree of freed gh damping, Condition for stability.	-			e, Multi d	legree of	rreedom	system
method, Mode su response, Rayleig	perposition, Single degree of freed gh damping, Condition for stability. d algorithms and codes to be practi	-			e, Multi d	legree of		system 45
method, Mode su response, Rayleig (Note: The related Total hours to be Text book (s) 1 1. John, V Press P	perposition, Single degree of freed gh damping, Condition for stability. d algorithms and codes to be practi taught . Harvey, Pressure Vessel Design: vt. Ltd., 1969.	ced by Nuclea	studen r and C	ts) Chemi	cal Applic	cations, A	Affiliated I	45 East West
method, Mode su response, Rayleig (Note: The related Total hours to be Text book (s) 1 1. John, V Press P 2 2. Prasant	perposition, Single degree of freed gh damping, Condition for stability. d algorithms and codes to be practi taught . Harvey, Pressure Vessel Design:	ced by Nuclea	studen r and C	ts) Chemi	cal Applic	cations, A	Affiliated I	45 East West
method, Mode su response, Rayleig (Note: The related Total hours to be Text book (s) 1 1. John, V Press P 2 2. Prasant References	perposition, Single degree of freed gh damping, Condition for stability. d algorithms and codes to be practi taught . Harvey, Pressure Vessel Design: vt. Ltd., 1969.	ced by Nuclea chanics	studen r and C , Whee	ts) Chemic	cal Applic	cations, <i>A</i>	Affiliated I	45 East West

CBIT	Autonomous Regulation								
Department	Mechanical Engineering		rogram				M.E. C	AD CAM	
		Sem	nester-I						
Course Code	Course Name	Hou	irs/We	ek	Credit		Maximu	m Marks	
		L	Т	Р	С	Е	I	Total	
ME511	INTEGRATED MECHANICAL DESIGN	4	0	0	3	75	25	100	
Objective (s)	To include the in –depth application of a scientific approach to design, the practice of a multi- disciplinary process, the practice of systems integration and the learning of typical values of design parameters.								
Outcome (s)									
1 UNIT – I				0				Total Hrs 9	
Tolerances – I assembly and i Oblique stress – Ductile vs. br Analysis and I Design for rigid	sign – Standardization and intendividual and group tolerances modular constructions – Concepes – Transformation Matrix – P ittle component design - Design of shafts for different ap lity.	- Selected ots of in rincipal	ection of itegration stress	of fits on –B es – I	for differe IS, ISO, E Maximum	ent desig DIN, BS, shear st	gn situati ASTM S ⁻ tress - Th	ons – Design for tandards. neories of Failure ng and casing –	
2 UNIT – II								Total Hrs 9	
Principles of gear tooth action – Gear correction – Gear tooth failure modes – Stresses and loads – Component design of spur, helical, bevel and worm gears – Design for sub assembly – Integrated design of speed reducers and multi-speed gear boxes – application of software packages.									
3 UNIT – III			-		I	<u> </u>		Total Hrs 9	
Dynamics and	I thermal aspects of vehicle	braking	g – In	tegrat	ted desig	in of br	akes for	machine tools,	
automobiles ar	nd mechanical handling equipme	ents.							
4 UNIT – IV								Total Hrs 9	
4 UNIT – IV Total Hrs 9 Integrated Design of systems consisting of shaft, bearings, springs, motor, gears, belt, rope, chain, pulleys, Cam & Follower, flywheel etc. Example - Design of Elevators, Escalators, Gear Box, Valve gear Mechanisms, Machine Tools.									

REFERENCES

- 1. Norton L. R., "Machine Design An Integrated Approach" Pearson Education, 2005
- 2. Newcomb, T.P. and Spur, R.T., "Automobile Brakes and Braking Systems", Chapman and Hall, 2nd Edition,1975.
- 3. Maitra G.M., "Hand Book of Gear Design", Tata McGraw Hill, 1985.
- 4. Shigley, J.E., "Mechanical Engineering Design", McGraw Hill, 1986.
- 5. Prasad. L. V., "Machine Design", Tata McGraw Hill, New Delhi, 1992.
- 6. Alexandrov, M., Materials Handling Equipments, MIR Publishers, 1981.
- 7. Boltzharol, A., Materials Handling Handbook, The Ronald Press Company, 1958.

APPROVED DATA BOOKS:

- 1. P.S.G. Tech., "Design Data Book", Kalaikathir Achchagam, Coimbatore, 2003.
- 2. Lingaiah. K. and Narayana Iyengar, "Machine Design Data Hand Book", Vol. 1 & 2, Suma 1983.

CBIT		Autono	mous F	Regul	ation			
Department	Mechanical Engineering	Progr Name	amme (e	Code	&	M.E. (C	AD/CAN	1)
	Se	mester-	·l					
Course Code	Course Name	Hours	s/ Week		Credit	Maximu	um Marks	6
		L	Т	Ρ	С	E	I	Total
ME 512	ROBOTIC ENGINEERING	4	0	0	3	75	25	100
Objective (s)	To educate mechanical enginee		are ca	pable	of solvin	g multidi	isciplinar	y technical
	problems in a global work enviro To produce individuals who co community involvement and asp	ontribut ire to lif	elong le	earnin	ig.			
Outcome (s)	An ability to design a robotic s within realistic constraints, such health and safety, manufacturab An ability to function on multidisc	n as eo ility, an	conomic d sustai	c, env inabili	/ironmen ty.	tal, socia	al, politic	
1 UNIT-I						Fotal Hrs		9
Degrees of from transmission, E Pneumatic, hydropots.	Types of robots, Overview of robot eedom of robots, Robot configura End effectors and Different types draulic and electrical actuators, app	ations of grip	and co pers, v	ncep acuu	t of wo m and o specifica	rkspace, other me ations of	Mechar ethods o differen	nisms and f gripping. t industrial
2 UNIT-II					Т	otal Hrs		9
Hartenberg not kinematics. 3 UNIT-III	es, Euler angle and RPY represen ation, representation of absolute pos atics, inverse orientation, inverse loc	sition a	nd orier	ntatio	n in term	s of joint otal Hrs	t parame	ters, direct
interpolation, ta	isk space interpolation, executing us The Tangent Bug Algorithm, The Inc	ser spe	cified ta	asks,	sensor b			
4 UNIT-IV					Total	Hrs		9
Newton-Euler f	alysis of RP type and RR type pl ormulations of RR and RP type p ator models, nonlinearity of manipula	lanar r	obots, ,	Inde	ependent	joint co	ntrol, PD	
5 UNIT-V			, -		Total			9
Sensors and co sensors, force s Robot vision: in Segmentation a	ontrollers: Internal and external sense sensors, laser range finder. nage processing fundamentals for ro and region characterization object rec	botic a	pplicatio	ons, ii	/ and acc	celeration	and prep	s, proximity processing.
Total hours to b	e lauyill						I	чJ
Text book (s)	and Mittal, "Robotics and Control", Ta	ata McC	raw_Li	1 200	13			
•				-			0	
	nd Vidhyasagar, "Robot Dynamics an	u Conti	UI, JOP		ey and s	ons, 200	0.	
Internatio							gence, M	lcGraw Hill
	Valle, "Planning Algorithms", Cambrid							
Sebastiar	noset, Kevin Lynch, Seth Hutchinso n Thurn, "Principles of Robot Motio dia, 2005.							

	CBIT		Autono	mous	Regu	lation			
Depa	artment	Mechanical Engineering	Progra Name	amme (e	Code	&	M.E. (C	AD/CAM)	
		Ser	mester-						
Cour	rse Code	Course Name	Hours	/Week		Credit	Maximu	ım Marks	
1			L	Т	Р	С	Е		Total
ME 5	513	PROGRAMMING							
		METHODOLOGY AND DATA STRUCTURES	4	0	0	3	75	25	100
Obje	ective (s)	To improve logical thinking of th Encourage the student to use hi Problems.	is own o	code to			iical engi	neering	
Outc	come (s)	Different types of data storage a Implementing the concepts with							
1 L	JNIT-I	·				Total	Hrs		9
Proç	gramming Met	thodology: Introduction, Algorith	m, Data	a Flow	Diag	rams, De	cision Tr	ee, Decis	sion Table
		Project Development.							
	JNIT-II					Total Hrs		9	
		'C': Data types & Memory size							
		Structures, Functions, Dynamic N	Jemory	/ Alloca	tion a	and Simp	ole progr	ams in N	lechanical
Ŭ	neering.								
	JNIT-III					Total			9
		ching Techniques: Selection s			rt, Ra	idix sort,	Heap s	ort. Linea	ar search,
		s and Applications in Mechanical I	Enginee	ering					
	JNIT-IV					Total			9
		Classification of Data Structures,	Definit	ions of					ts, Stacks
		ations and Implementations of S		lueues	and L				
Engi	neering Applic	ations and Implementations of S		lueues	and L				
Engi 5 L Adva	neering Applic JNIT-V anced Data S	ations and Implementations of S	ology,	Binary	Tree	Total s, Opera	Hrs tions on	Binary 1	lechanical 9
Engi 5 L Adva trave	neering Applic JNIT-V anced Data S ersals, Graph, (ations and Implementations of S ations Structures: Tree, Basic Termine Graph representation Adjacency r	ology,	Binary	Tree	Total s, Opera	Hrs tions on	Binary 1 ons.	lechanical 9
Engi 5 L Adva trave Tota	neering Applic JNIT-V anced Data S ersals, Graph, (I hours to be ta	ations and Implementations of S ations Structures: Tree, Basic Termine Graph representation Adjacency r	ology,	Binary	Tree	Total s, Opera	Hrs tions on	Binary 1 ons.	lechanical 9 ree, Tree
Engi 5 L Adva trave Tota	neering Applic JNIT-V anced Data S ersals, Graph, (I hours to be ta book (s) 1. G.Mic Devel	ations and Implementations of S ations Structures: Tree, Basic Terming Graph representation Adjacency r aught chael Schneider, Steven C.Br <i>lopment</i> ", Jaico Publishing House	ology, matrix, /	Binary Adjacer Concer	Trees ncy Li	Total s, Opera sts and A n Data	Hrs tions on Application	Binary tons.	lechanical 9 tree, Tree 45 Software
Engi 5 L Adva trave Tota Text	neering Applic JNIT-V anced Data S ersals, Graph, (I hours to be ta book (s) 1. G.Mic Devel	ations and Implementations of S ations Structures: Tree, Basic Terming Graph representation Adjacency r aught chael Schneider, Steven C.Br <i>lopment</i> ", Jaico Publishing House ghan B.W, Ritchie D.M, "The C	ology, matrix, /	Binary Adjacer Concer	Trees ncy Li	Total s, Opera sts and A n Data	Hrs tions on Application	Binary tons.	lechanical 9 tree, Tree 45 Software
Engi 5 L Adva trave Tota Text 1 2	neering Applica JNIT-V anced Data S ersals, Graph, G I hours to be ta book (s) 1. G.Mic Devel 1. Kernig	ations and Implementations of S ations Structures: Tree, Basic Terming Graph representation Adjacency r aught chael Schneider, Steven C.Br <i>lopment</i> ", Jaico Publishing House ghan B.W, Ritchie D.M, "The C	ology, matrix, /	Binary Adjacer Concer	Trees ncy Li	Total s, Opera sts and A n Data	Hrs tions on Application	Binary tons.	lechanical 9 tree, Tree 45 Software
Engi 5 L Adva trave Tota Text 1 2	neering Applic JNIT-V anced Data S ersals, Graph, (I hours to be ta book (s) 1. G.Mic Devel 1. Kernig India, erences	ations and Implementations of S ations Structures: Tree, Basic Terming Graph representation Adjacency r aught chael Schneider, Steven C.Br <i>lopment</i> ", Jaico Publishing House ghan B.W, Ritchie D.M, "The C	ology, matrix, / ruell, " 2,2002 Progra	Binary Adjacer Concer	Trees ncy Li ots ii	Total s, Opera sts and A n Data guage", 2	Hrs tions on Applicatio Structur 2 nd Editio	Binary to ons. Tes and on, Prenti	lechanical 9 tree, Tree 45 Software
Engi 5 L Adva trave Tota Text 1 2 Refe	neering Applic JNIT-V anced Data S ersals, Graph, (I hours to be ta book (s) 1. G.Mic Devel 1. Kernig India, erences Kruse RL, Bru	ations and Implementations of S ations Structures: Tree, Basic Termine <u>Graph representation Adjacency raught</u> chael Schneider, Steven C.Br <i>lopment</i> ", Jaico Publishing House ghan B.W, Ritchie D.M, " <i>The C</i> 2003	ology, matrix, / ruell, " 2,2002 Progra	Binary Adjacer Concer amming	Trees ncy Li ots ii Lang Desig	Total s, Opera sts and A n Data guage", 2 gn in C",	Hrs tions on Applicatio Structur 2 nd Editio PHI, 199	Binary for the second s	lechanical 9 rree, Tree 45 Software ce-Hall of

CBIT		Autono	mous I	Regul	ation			
Department	Mechanical Engineering	Progr Name	amme (e	Code	&	M.E. TI	nermal Er	ngineering
	S	emester-	·I			•		
Course Coo	e Course Name	Hours	s/ Week		Credit	Maxim	um Marks	i
		L	Т	Р	С	E		Total
ME 514	OPTIMIZATION TECHNIQUES	4	0	0	3	75	25	100
Objective (s					- 4			
Outcome (s	Students should able to plan an Capable of applying optimization Ability to use linear & non linean Ability to develop schedule for	on techni ar prograr	ques in nming t	engir echni	ieering a ques.			
1 UNIT –					Total	Hrs		9
Sensitivity A	f Optimization Problem, Linear Programalysis, Parametric Programming, and				em.	-	olex Meth	
2 UNIT –	I rogramming: Approach, Convergence				Total			9
3 UNIT –	escent, Conjugate Gradient, Newton, C II Optimization Direct Methods: Lagrance				Total	Hrs		9
	Beal's method, Indirect Method: Penalt							
4 UNIT –					Total			9
and Contin	to Dynamic Programming; Concept o Jous Dynamic Programming with Ap od; Branch and Bound method; Introdu	plication	s; Intro	ductic	on to Int	eger Pro	ogrammir	ig; Cutting
5 UNIT –	V			Ĩ	Total	Hrs		9
Projectsche	and Scheduling, Project Scheduling duling; Queuing Theory, Single and r Queues with priorities for service.							
	to be taught							45
Text book								
	S. Engineering "Optimization Theory a							
_ 0;	E.J.and Arora, J.S., "Applied Optimal D	esign", V	Viley Int	er Sc	ience Pu	blication	, NY, 197	9.
Reference								
	as J. Willde, "Globally Optimal Design",							
	on Ray C., "Optimum Design of Mecha					Sons, 19	981.	
	harma, S.D. "Operations Research", K				001.			
	Goldberg, "Genetic Algorithms", pearso							
	e cleric, "Particle Swarm Optimization"							
6 Prem	Kumar Gupta, "Operations Research",	S Chand	nunling	nne	2008			

CBIT	A	Autono	mous I	Regul	lation			
Department	Mechanical Engineering	Pro	ogramm Na		de &	M.	E. (CAD/	/CAM)
		nester-			•	•		
Course Code	Course Name		/Week		Credit		um Marks	1
ME 515	VIBRATION ANALYSIS AND CONDITION MONITORING	L 4	Т 0	Р 0	C 3	E 75	1 25	Total 100
Objective (s)	Familiarization with the basics o	f vibrati	on mea	asurei	nent and	l applicat	ion of the	e same for
, (- ,	condition monitoring of machiner							
Outcome (s)	Understand the failure types, inv Understand Single degree and m Understand Steady state and tra Simple harmonic motion, periodi Linear and logarithmic scales an Vibration measuring instruments Display and recording elements. Frequency analysis and filters. Vibration limits and standards. Contaminant analysis, SOAP an Special methods of vibration mea Shock pulse, kurtosis, acoustic e Cepstrum analysis, modal analysis	nulti deg nsient o c motio d phase : transd Vibratio d other asurem	gree of character n. Peak e angle lucers, on meter contament: char n monite	freed eristic to pe signa ers ar hinant ange oring.	om syste s of vibra eak, RMS I condition d analyz monitori in sound	ems. ation. S and ave oning elen ers. ing techni	erage val nents. iques.	lues.
1 UNIT-I	Shaft orbit position analysis.				Tatal		T	
	ate of vibration Vibrations of Sin				Total		Degree	9 of freedom
	cts of vibration. Vibrations of Sin state and transient characteristics			wo D	egree al	na multi	Degree	or freedom
2 UNIT-II								
				Т	otal Hrs		9	
UNIT-II Introduction to C Characteristics of & RMS, linear and	Condition Monitoring, Failure type vibration – SHM, Periodic motion, d logarithmic scales and phase and	Displa		on ar t, Velo	nd occur	rences. accelera	Causes	
UNIT-II Introduction to C Characteristics of & RMS, linear and 3 UNIT-III Vibration measur	vibration – SHM, Periodic motion, d logarithmic scales and phase and ing instruments, vibration transduc	Displa gle.	cement	on ar t, Velo	nd occur ocity and	rences. accelera	Causes ation. Pe	eak to peak
UNIT-II Introduction to C Characteristics of & RMS, linear and 3 UNIT-III Vibration measur elements. Vibrati	vibration – SHM, Periodic motion, d logarithmic scales and phase and	Displa gle.	cement	on ar t, Velo	nd occur ocity and fotal Hrs ning elem	rences. accelera nents. Dis	Causes ation. Pe	eak to peak
UNIT-II Introduction to C Characteristics of & RMS, linear and 3 UNIT-III Vibration measur elements. Vibrati 4 UNIT-IV	vibration – SHM, Periodic motion, d logarithmic scales and phase and ing instruments, vibration transduc on meters and analyzers	Displa gle. ers, sig	nal cor	on ar t, Velo T nditior	nd occur ocity and fotal Hrs ning elem Total	rences. accelera nents. Dis Hrs	Causes ation. Pe 9 splay and	eak to peak d recording 9
UNIT-IIIntroduction to CCharacteristics of& RMS, linear and3UNIT-IIIVibration measurelements. Vibrati4UNIT-IVCondition Monitosystems, vibratio	vibration – SHM, Periodic motion, d logarithmic scales and phase ang ing instruments, vibration transduc	Displa gle. ers, sig	nal cor	on ar t, Velo T nditior	nd occur ocity and fotal Hrs ning elem Total Filters, V	rences. accelera nents. Dis <u>Hrs</u> Vibration	Causes ation. Pe 9 splay and signature	d recording 9 re of active
UNIT-IIIntroduction to CCharacteristics of& RMS, linear and3UNIT-IIIVibration measurelements. Vibration4UNIT-IVCondition Monito	vibration – SHM, Periodic motion, d logarithmic scales and phase and ing instruments, vibration transduc on meters and analyzers ring through vibration analysis.	Displa gle. ers, sig	nal cor	on ar t, Velo T nditior	nd occur ocity and fotal Hrs ning elem Total Filters, V	rences. accelera nents. Dis Hrs Vibration ther conta	Causes ation. Pe 9 splay and signature	d recording 9 re of active
UNIT-IIIntroduction to CCharacteristics of& RMS, linear and3UNIT-IIIVibration measurelements. Vibration4UNIT-IVCondition Monitosystems, vibratiotechniques.5UNIT-VSpecial vibrationpulse measurem	vibration – SHM, Periodic motion, d logarithmic scales and phase ang ing instruments, vibration transduc on meters and analyzers ring through vibration analysis. F n limits and standards. Contamir measuring techniques - Change in ent, Kurtosis, Acoustic emission	Displa gle. ers, sig requen hant an sound	cement nal cor cy anal alysis, method	on ar , Velo T nditior lysis, SOAI 	nd occur ocity and fotal Hrs ning elem Total Filters, V P and of Total rasonic m	rences. accelera nents. Dis Hrs Vibration ther conta Hrs neasurem	Causes ation. Pe 9 splay and signature aminant ment meth	eak to peak d recording 9 re of active monitoring 9 hod, Shock
UNIT-IIIntroduction to CCharacteristics of& RMS, linear and3UNIT-IIIVibration measurelements. Vibrationelements. Vibration4UNIT-IVCondition Monitosystems, vibratiotechniques.5UNIT-VSpecial vibrationpulse measuremspeed analysis, STotal hours to be	vibration – SHM, Periodic motion, d logarithmic scales and phase and ing instruments, vibration transduc on meters and analyzers ring through vibration analysis. F n limits and standards. Contamir measuring techniques - Change in ent, Kurtosis, Acoustic emission shaft –orbit & position analysis.	Displa gle. ers, sig requen hant an sound	cement nal cor cy anal alysis, method	on ar , Velo T nditior lysis, SOAI 	nd occur ocity and fotal Hrs ning elem Total Filters, V P and of Total rasonic m	rences. accelera nents. Dis Hrs Vibration ther conta Hrs neasurem	Causes ation. Pe 9 splay and signature aminant ment meth	eak to peak d recording 9 re of active monitoring 9 hod, Shock
UNIT-II Introduction to C Characteristics of & RMS, linear and 3 UNIT-III Vibration measur elements. Vibration 4 UNIT-IV Condition Monito systems, vibratio techniques. 5 UNIT-V Special vibration pulse measurem speed analysis, S Total hours to be Text book (s) 1	vibration – SHM, Periodic motion, d logarithmic scales and phase and ing instruments, vibration transduc on meters and analyzers ring through vibration analysis. F n limits and standards. Contamir measuring techniques - Change in ent, Kurtosis, Acoustic emission shaft –orbit & position analysis.	Displa gle. ers, sig requen nant an sound monitor	cement nal cor cy anal alysis, methoo ing, Ce	on ar , Velo T nditior Jysis, SOAI J, Ultr epstru	nd occur ocity and otal Hrs ning elem Total Filters, Y P and of Total asonic m im analy	rences. accelera nents. Dis Hrs Vibration ther conta Hrs neasurem rsis, Mod	Causes ation. Pe 9 splay and signature aminant hent meth lal analys	eak to peak d recording 9 re of active monitoring 9 hod, Shock rsis, critical
UNIT-II Introduction to C Characteristics of & RMS, linear and 3 UNIT-III Vibration measurements. Vibration elements. Vibration 4 UNIT-IV Condition Monito systems, vibratio techniques. 5 UNIT-V Special vibration pulse measurem speed analysis, S Total hours to be Text book (s) 1 Collacott, R 1982. 2 John S. Mitt	vibration – SHM, Periodic motion, d logarithmic scales and phase ang ing instruments, vibration transduc on meters and analyzers ring through vibration analysis. F n limits and standards. Contamir measuring techniques - Change in ent, Kurtosis, Acoustic emission shaft –orbit & position analysis. taught .A., Mechanical Fault Diagnosis	Displa gle. ers, sig requen hant an sound monitor and Co	cement nal cor cy anal alysis, methoo ing, Ce ndition	on ar , Velo T nditior Jysis, SOAI J, Ultr epstru 	itoring,	rences. accelera nents. Dis Hrs Vibration ther conta Hrs neasurem rsis, Mod	Causes ation. Pe 9 splay and signature aminant lal analys an & Hall	eak to peak d recording 9 re of active monitoring 9 hod, Shock rsis, critical 45 I, London,
UNIT-II Introduction to C Characteristics of & RMS, linear and X INIT-III Vibration measure OBMIT-III Vibration measure Vibration measure OBMIT-IV Condition Monito Systems, vibratio techniques. JUNIT-V Special vibration pulse measurem special vibration pulse measurem Special vibration Pulse measurem Special vibration Pulse measurem Special hours to be Text book (s) 1 Collacott, R 1982. 2 John S. Mitt Well Publish References	vibration – SHM, Periodic motion, d logarithmic scales and phase and ing instruments, vibration transduct on meters and analyzers ring through vibration analysis. F n limits and standards. Contamir measuring techniques - Change in ent, Kurtosis, Acoustic emission Shaft –orbit & position analysis. taught .A., Mechanical Fault Diagnosis chell, Introduction to Machinery of ing Company, Tulsa, Oklahoma, f	Displa gle. ers, sig requen hant an sound monitor and Co Analysi.	cement nal cor cy anal alysis, methoo ing, Ce ndition s and I	on ar , Velo T nditior lysis, SOAI lysis, SOAI d, Ultr epstru Monito	nd occur ocity and otal Hrs ning elem Total Filters, V P and of Total rasonic m im analy <i>itoring,</i> F	rences. accelera nents. Dis Vibration ther conta Hrs neasurem rsis, Mod Chapma	Causes ation. Pe 9 splay and signature aminant lal analys an & Hall Il Books,	eak to peak d recording 9 re of active monitoring 9 hod, Shock rsis, critical 45 I, London, Penn
UNIT-II Introduction to C Characteristics of & RMS, linear and C 3 UNIT-III Vibration measure elements. Vibration Vibration Monito systems, vibratio techniques. 5 UNIT-IV Special vibration pulse measurem speed analysis, S Total hours to be Text book (s) 1 Collacott, R 1982. 2 2 John S. Mite Nakra, B.C. Productivity	vibration – SHM, Periodic motion, d logarithmic scales and phase and ing instruments, vibration transducton on meters and analyzers ring through vibration analysis. F n limits and standards. Contamir measuring techniques - Change in ent, Kurtosis, Acoustic emission shaft –orbit & position analysis. taught .A., <i>Mechanical Fault Diagnosis</i> chell, <i>Introduction to Machinery L</i> ing Company, Tulsa, Oklahoma, 1 Yadava, G.S. and Thuested, I Council, New Delhi, 1989.	Displa gle. ers, sig requen hant an sound monitor and Co Analysi.	cement nal cor cy anal alysis, methoo ing, Ce ndition s and I	on ar , Velo T nditior lysis, SOAI lysis, SOAI d, Ultr epstru Monito	nd occur ocity and otal Hrs ning elem Total Filters, V P and of Total rasonic m im analy <i>itoring,</i> F	rences. accelera hents. Dis Hrs Vibration ther conta Hrs neasurem sis, Mod Chapma	Causes ation. Pe 9 splay and signature aminant lal analys an & Hall Il Books,	eak to peak d recording 9 re of active monitoring 9 hod, Shock rsis, critical 45 I, London,
UNIT-II Introduction to C Characteristics of & RMS, linear and the sector of	vibration – SHM, Periodic motion, d logarithmic scales and phase and ing instruments, vibration transduction on meters and analyzers ring through vibration analysis. F n limits and standards. Contamir measuring techniques - Change in ent, Kurtosis, Acoustic emission Shaft –orbit & position analysis. taught .A., Mechanical Fault Diagnosis chell, Introduction to Machinery ing Company, Tulsa, Oklahoma, 1 Yadava, G.S. and Thuested, I	Displa gle. ers, sig requen nant an sound monitor and Co Analysia 1993.	cement nal cor cy anal alysis, methoo ing, Ce ndition s and I	on ar , Velo T nditior lysis, SOAI lysis, SOAI d, Ultr epstru Monito	nd occur ocity and otal Hrs ning elem Total Filters, V P and of Total rasonic m im analy <i>itoring,</i> F	rences. accelera nents. Dis Vibration ther conta Hrs neasurem rsis, Mod Chapma	Causes ation. Pe 9 splay and signature aminant lal analys an & Hall Il Books,	eak to peak d recording 9 re of active monitoring 9 hod, Shock rsis, critical 45 I, London, Penn

CBIT	A	utonon	nous R	egula	ntion			
Department	Mechanical Engineering	Pro	ogramm	ne Co	de &	N	1.E. Theri	mal
Department	•••			me		E	Engineeri	ng
		nester-l						
Course Code	Course Name	Hours	/Week	1	Credit		m Marks	
			Т	Р	C	E	I	Total
ME 516	ENGINEERING RESEARCH METHODOLOGY	4	0	0	3	75	25	100
Objective (s)	Students should able to understa collection and its design includin statistical tools to understand the statistical methodology. Students from the statistical analysis.	ig samp e data s should	ble des being d d able	ign S collec to dr	tudents ted and aw interp	should a applicat pretations	ble to ap ion of ap s and co	ply basic propriate nclusions
Outcome (s)	Students can apply suitable data Students can analyze any practic							
1 UNIT – I	•				Tota	al Hrs		9
	ope of research, objective/motiva in engineering, benefits to the socie			eristic	s and p	orerequis	ites of	research.
2 UNIT – II	in engineering, benefits to the soci	sty in ge	sileiai.		Total	Hrs	9	
Review of Litera	ture: Role of review, search for re				ne searc	h, and w	/eb-base	d search
	ature search. Evaluating, Organizir							
	describing the research. Finding the feature of the content of the content of a Good research the content of th		earch	Proble	em. Sou	rces of I	research	
3 UNIT – III	Characteristics of a Good research				Tota	al Hrs		9
	role of Data in Research. Linking	Data a	and Re	searc				-
	a collection. Choosing a Research							
	lity of Research Design. Establ							
	esearch Proposal preparation. C							research
	ation of proposal. Importance of Int	erpreta	tion of o	data a				
4 UNIT – IV	to Description and Analysis of D	-4- D-	1 (0	4-4:-4:		al Hrs		9
	ta. Description and Analysis of Datates of. Population. Parameters. I							
	s of Central tendency, Measures							
	tion, Hypothesis Testing. Use of Sta					of rolatio	nomp. n	norondar
	Deterministic and random data, u				tests fo	r signific	ance: Ch	ni-square.
student's 'ť' test.	Regression modeling, direct and in							
5 UNIT – V	and autoregressive modeling				Tota	al Hrs		9
	of the Research report. Style of v	vritina r	eport.	Refer			graphy.	
paper writing/Jou	Irnal report	5	•					
Total hours to be	taught							45
Text book (s)	du and lagran E. Orrend "Drasti			Diawa	in er ere el F	De e : e : e ?		
1 Paul D. Lee	edy and Jeanne E. Ormrod. "Praction of the section	cal Res	earcn:	Plann	ing and L	Design", (8th Ealti	on)
2 "A Hand Bo	ook of Education Research" - NCTE							
Reference (s)								
	S. "Methodology of Education Rese			"				
	R. "Research Methodology, Method				- ¹ ¹	Obeliati	- I N A - 41-	-l - "
	.P. "Tests, Measurements and Res							
	enkins; "Time Series Analysis, Fore						mancisc	U
j o j ⊓oiman, J.	P. "Experimental Methods for Engir	ieers,	vicera\	// ⊓1111	mil., New	TUIK.		

CBIT		Auto	nomol	ıs Re	gulation			
Department	Mechanical Engineering		Progra	amme	e Code & I	Name	1	M.E. CAD CAM
		Sem	ester-l					
Course Code	Course Name	Ηοι	urs/We	ek	Credit		Maxim	um Marks
		L	Т	Р	С	Е		Total
ME517	TRIBOLOGY IN DESIGN	4	0	0	3	75	25	100
Objective (s)	To impart knowledge in the fricting To understand the material presurfaces. To understand the analytical by based on analytical /theoretical	ropertie oehavic	es which or of di	ch inf	luence th	ne tribolo	ogical	characteristics of
Outcomes	Ability to select material / surface Methodology for deciding lubrica Analysis ability of different types	e prop ants ar	erties I d lubrid	cation	regimes	for differ	ent ope	erating conditions
1 UNIT – I						otal Hrs		9
Theory of Slid	of Surfaces – Surface features -P ing Friction –Rolling Friction-Frict nditions –Thermal considerations	tion pro	perties	of m				
2 UNIT – II						Total H		9
Topography m measurement						al stand	ards in	friction and wear
3 UNIT – I		'4				Total H		9
Lubricants- Lu Dry and margi	nd their physical properties- Visc bricants standards ISO,SAE,AGM nally lubricated contacts- Bounda ynamic - Magneto hydrodynamic	MA, BIS ary Lub	S stand ricatior	ards - I- Hyd	 Lubricat rodynami 	ion Regi c lubrica	mes –\$ tion ––	Solid Lubrication- - Elasto and
4 UNIT – I				iyaro		Total H		9
Reynolds Equ and Sommerf Hydrodynamic Thermal cons calculations-S	ation,-Assumptions and limitation feld boundary conditions- Press bearings-Long and short bearin siderations-Hydrostatic lubrication tiffness considerations- Various t	sure w gs-Pac on of	ave, fle I bearir Pad l	ow, lo igs ar bearin	oad capa nd Journa ig-Pressu	al Reyn city and I bearing re , flo	olds E I frictio gs- Squ	quation-Reynolds on calculations in ueeze film effects- oad and friction gs
5 UNIT – V								Total Hrs 9
contacts-Cont Reynolds equ thickness and REFERENCE 1. Rabinowid	cz.E, "Friction and Wear of materi	Elasto pricatio ngs- St als", Jo	Hydrod n Fil resses ohn Wil	dynam m sha and d ley &S	nic lubrica ape within eflections Sons ,UK,	ation The and out -Traction	eory-So tside co	oft and hard EHL- ontact zones-Film
3. Halling, J.	A. "Basic Lubrication Theory", El (Editor) – "Principles of Tribology J.A. "Engineering Tribology", Oxf	/ ", Ma	cmillian	- 198	84.			

Williams J.A. "Engineering Tribology", Oxford Univ. Press, 1994.
 S.K.Basu, S.N.Sengupta & B.B.Ahuja, "Fundamentals of Tribology", Prentice – Hall of India Pvt Ltd New Delhi, 2005
 G.W.Stachowiak & A.W. Batchelor, Engineering Tribology, Butterworth-Heinemann, UK, 2005.

CBIT					Regulat	ion			
Department	Mechanical Engineering	, F	rogran ۸	nme C Jame	ode &		M.E. CA	D CAM	
		Sem	ester-I						
Course Code	Course Name	Ηοι	urs/ We	ek	Credit		Maximur	n Marks	5
		L	Т	Р	С	E	I	Т	otal
	ADVANCED								~ ~
ME518	MECHANICS OF MATERIALS'	4	0	0	3	75	25	1	00
Objective (s)	Understand the basic co	ncepts	of med	hanic	s of mate	rials and	extend t	hese fo	r plates,
	curved members and nor	n – circ	ular se	ctions					
	With the knowledge ac	hieved	throug	h this	subject,	student	s will be	able to	apply
Outcome (s)	these concepts of adva subjected to various loa								
1 UNIT – I							Total I		9
	s of equilibrium-compatibil generalized hook's law - \$								
2 UNIT – II							Total I	Irs	9
	nter for various thin section	s - she	ear flow	s. Str	esses and	d Deflect	ions in be	eams su	bjected
	ding-kern of a section.							_	
3 UNIT – III	- l'al atura a su dafla ati a a						Total I		9
	adial stresses – deflections d uniform load - chain links							ing subj	ected to
4 UNIT – IV				000.	Solution	rectant	Total I	Inc	9
	ar cross section - St.Ver	ants t	heory -	elas	tic memb	rane an	= = = = =		1
	ress in hollow thin walled to		neory	ciuo			alogy	Turiuu	5 50055
5 UNIT – V							Total H		9
	stresses in solid disc and			n thick	ness and				
allowable speeds. Me	ethods of computing contact	ct stres	s-			d	leflection	of bodie	es in
point and line contact	applications.								

REFERENCES

- 1. Arthur P Boresi, Richard J. Schmidt, "Advanced mechanics of materials", John Wiley, 2002.
- 2. Timoshenko and Goodier, "Theory of Elasticity", McGraw Hill.
- 3. Robert D. Cook, Warren C. Young, "Advanced Mechanics of Materials", Mc-millan pub. Co., 1985.
- 4. Srinath. L.S., "Advanced Mechanics of solids", Tata McGraw Hill, 1992.
- 5. G H Ryder Strength of Materials Macmillan, India Ltd, 2007.
- 6. Allan F. Bower, "Applied Mechanics of Solids", CRC press Special Indian Edition -2012, 2010
- 7. K. Baskar and T.K. Varadan, "Theory of Isotropic/Orthotropic Elasticity", Ane Books Pvt. Ltd., New Delhi, 2009

CBIT	A	utonom	ious R	egula	tion			
Department	Mechanical Engineering	Pro	ogramm Na		de &	M.E	. (CAD/C	AM)
	Sem	ester-l	INd	me				
Course Code	Course Name		/Week	[Credit	Maximu	m Marks	
	1	L	Т	Р	С	E	Ι	Total
ME 519	MECHANICS OF COMPOSITE MATERIALS	4	0	0	3	75	25	100
Outcome (s)	composites, as well as some cor An ability to predict the elastic constituent properties. An ability to rotate stress, strain a A basic understanding of linear isotropic and anisotropic materia An ability to analyze a laminated from lamina properties. An ability to predict the failure str Knowledge of issues in fractur composites. An exposure to recent develop matrix composites. An ability to use the ideas dev composites in industrial application At the end of the course, student Should apply the knowledge gain	c prope and stiff elastic behav plate in rength c re of c oments reloped on.	rties o ness te city with ior. n bendi of a lam omposi in cor in the able to	f long ensors h emp ing, in inated ites a mposir anal	y fiber c s using id ohasis o cluding f d compos nd envir tes, inclu ysis of c yze the c evelop co	omposite leas from n the dif inding lar site plate commenta uding me composite composite	matrix a ference I minate pr I degrad etal and es toward e material structure	lgebra. between operties ation of ceramic ds using ls. s.
1 UNIT-I						Fotal Hrs		9
	res, Matrix materials, interfaces, p		matrix	com	posites,	metal m	atrix com	posites,
2 UNIT-II	mposites carbon fibre composites.					otal Hrs	9	
Transverse stress to fibre.	erties: Prediction of Elastic consta ses. Thermal properties: Hygrothe				hanics of	load tra	nsfer fror	n matrix
3 UNIT-III						Fotal Hrs	5	9
compliances, vari	of a lamina, relations between ation of lamina properties with or rientation, inter-laminar stresses a	ientatio	n, anal	lysis (of lamina nplified c	ated com	posites, s e beam s	stresses
	, fatigue and design:				•			
Single and multip composites. Effect Strength of an o	pressive strength of unidirectiona ple fracture, de-bonding, fibre p ct of variability of fibre strength. rthotropic lamina: Max stress th c interaction criteria. Designing with	ullout a neory, i	nd de max st	-lamir rain d	ation fa criteria, r	ilure, fat	igue of l	aminate
5 UNIT-V						otal Hrs		9
	s and stress: equations, Bending of composite p is of composite cylindrical shells u						ates of co	mposite
Total hours to be							4	-
Text book (s)								-5
1 Jones, R.M.,	Mechanics of Composite Materia							.5
1 Jones, R.M., 2 Calcote, L.R	, Mechanics of Composite Materia ., The Analysis of Laminated Com					rand, 196	<u>8</u> 9.	.5
1 Jones, R.M., 2 Calcote, L.R References 1 1 Whitney, I.M Prentice Hat	., The Analysis of Laminated Com . Daniel, R.B. Pipes, Experimenta	posite 3 I Mecha	Structur anics of	res, \ f Fibre	/an Nost Reinfore	ced Com	posite Ma	aterials,

CBIT	Au	Itonomo				1		
Department	Mechanical Engineering		gramm Na		de &	M.E	. (CAD/C	CAM)
		ester-l			0			
Course Code	Course Name	Hours/	Week		Credit		m Marks	
		L	I	Р	С	E	I	Total
ME 520	THEORY OF ELASTICITY AND PLASTICITY	4	0	0	3	75	25	100
Objective (s)	Students should able to solve th	ne proble	ems s	electe	ed to stre	ess-strair	n tensors	and an
	constitutive relations.							
	Students should be able to apply	y suitable	e plas	ticity	relations	to solve	the pro	blems in
	various metal forming operations.							
Outcome (s)	Students can analyze a simple loa	ading cor	ndition	in pr	actice an	d come o	out the st	ate of
	stress induced in the member.							
	Students can find force requireme		ny forn	ning c	peration	such as	forging,	
	extrusion, wire drawing, rolling etc) .						
1 UNIT-I					Total	-		9
	of Stress : Definition, State of Stres							
	s, stress ellipsoid, derivation for m							
stress, octahedra	al shear stress, Deviatoric and Hydr	rostatic c	compo	nents	of stres	s, Invaria	nce of D	eviatoric
stress tensor, pla	ine stress.							
2 UNIT-II				17	Fotal Hrs	5	9	
principle strains,	f Strain : Deformation tensor, Strain derivation for maximum shear str iatoric and Hydrostatic components	rain and	plane	es of i	maximun	n shear s	strain, oc	tahedral
principle strains,		rain and	plane	es of i	maximun	n shear s of Deviat	strain, oc oric straiı	tahedral
principle strains, shear strain, Dev plane strain. 3 UNIT-III	derivation for maximum shear sta	rain and s of strain	plane n tenso	es of i or, Inv	maximun ariance Total	n shear s of Deviat Hrs	strain, oc oric strai	tahedral n tensor, 9
principle strains, shear strain, Dev plane strain. 3 UNIT-III Generalized Hoo space, for plane	derivation for maximum shear str iatoric and Hydrostatic components ke's Law : Stress-strain relationsh stress and plane strain condition	rain and of strain ips for a ns, differ	plane n tenso an isot	es of I or, Inv	maximun ariance Total body for	n shear s of Deviat Hrs three di	strain, oc oric straii mension	tahedral n tensor, 9 al stress
principle strains, shear strain, Dev plane strain. 3 UNIT-III Generalized Hoo space, for plane	derivation for maximum shear str iatoric and Hydrostatic components ke's Law : Stress-strain relationsh	rain and of strain ips for a ns, differ	plane n tenso an isot	es of I or, Inv	maximun ariance Total body for	n shear s of Deviat Hrs three di equilibri	strain, oc oric straii mension um, com	tahedral n tensor, 9 al stress
principle strains, shear strain, Dev plane strain. 3 UNIT-III Generalized Hoo space, for plane equations, Materi 4 UNIT-IV	derivation for maximum shear str iatoric and Hydrostatic components ke's Law : Stress-strain relationsh stress and plane strain condition ial (D) matrix for Orthotropic Materia	rain and of strain ips for a ns, differ als	plane n tenso an isot rential	es of i or, Inv ropic equa	maximun rariance Total body for ttions of Total	n shear s of Deviat Hrs three di equilibri Hrs	strain, oc oric straii mension um, com	tahedral n tensor, 9 al stress patibility 9
principle strains, shear strain, Dev plane strain. 3 UNIT-III Generalized Hoo space, for plane equations, Mater 4 UNIT-IV True stress and	derivation for maximum shear str iatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia	rain and of strain ips for a ns, differ als esca yie	plane n tenso an isot rential	es of roor, Inv	Total body for ations of Total Haigh-V	n shear s of Deviat Hrs three di equilibri Hrs Westerga	strain, oc oric strain mension um, com um, com	tahedral n tensor, 9 al stress patibility 9 s space
principle strains, shear strain, Dev plane strain.3UNIT-IIIGeneralized Hoo space, for plane equations, Mater4UNIT-IVTrue stress and representation of	derivation for maximum shear str iatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia d true strain, von-Mise's and Tre f von - Mise's and Tresca yield crit	ips for a ns, differ als esca yie teria, effe	plane n tenso an isot rential eld crit ective	es of nor, Investigation of the second secon	Total body for ations of Total Haigh-\ s and ef	n shear s of Deviat Hrs three di equilibri Hrs Westerga fective st	strain, oc oric strain mensiona um, com um, com urd stres rrain, St.	tahedral n tensor, 9 al stress patibility 9 s space Venants
principle strains, shear strain, Dev plane strain.3UNIT-IIIGeneralized Hoo space, for plane equations, Mater4UNIT-IVTrue stress and representation of theory of plastic	derivation for maximum shear str iatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia d true strain, von-Mise's and Tre f von - Mise's and Tresca yield crit flow, Prandtle–Reuss and Levy-	rain and of strain ips for a ns, differ als esca yie teria, effe -Mise's o	plane n tenso an isot rential edd crit ective constit	es of i or, Inv ropic equa teria, stres tutive	Total body for ations of Total Haigh-\ s and ef	n shear s of Deviat Hrs three di equilibri Hrs Westerga fective st	strain, oc oric strain mensiona um, com um, com urd stres rrain, St.	s space Venants
principle strains, shear strain, Dev plane strain.3UNIT-IIIGeneralized Hoo space, for plane equations, Mater4UNIT-IVTrue stress and representation of theory of plastic	derivation for maximum shear str iatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia d true strain, von-Mise's and Tre f von - Mise's and Tresca yield crit	rain and of strain ips for a ns, differ als esca yie teria, effe -Mise's o	plane n tenso an isot rential edd crit ective constit	es of i or, Inv ropic equa teria, stres tutive	Total body for ations of Total Haigh-\ s and ef	n shear s of Deviat <u>Hrs</u> three di equilibri <u>Hrs</u> Westerga fective st ns of pla	strain, oc oric strain mension um, com um, com urd stres rrain, St. astic flow	s space Venants
principle strains, shear strain, Dev plane strain.3UNIT-IIIGeneralized Hoo space, for plane equations, Materi4UNIT-IVTrue stress and representation of theory of plastic hardening and we5UNIT-V	derivation for maximum shear str iatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia d true strain, von-Mise's and Tre f von - Mise's and Tresca yield crit flow, Prandtle–Reuss and Levy-	rain and of strain ips for a ns, differ als esca yie teria, effe -Mise's o stic defo	plane n tenso an isot rential ective constii rmatio	es of incomposition of incomposition of incomposition of the second seco	Total body for titions of Total Haigh–V s and ef equatio	n shear s of Deviat Hrs three di equilibri Hrs Westerga fective st ns of pla Hrs	strain, oc oric strain mension um, com um, com urd stres rrain, St. astic flov	etahedral n tensor, 9 al stress patibility 9 S space Venants v, Strain 9
principle strains, shear strain, Dev plane strain.3UNIT-IIIGeneralized Hoo space, for plane equations, Materi4UNIT-IVTrue stress and representation of theory of plastic hardening and we5UNIT-VAnalysis method	derivation for maximum shear str iatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia d true strain, von-Mise's and Tre f von - Mise's and Tresca yield crit f flow, Prandtle–Reuss and Levy- ork hardening theories, work of pla	rain and s of strain ips for a ns, differ als esca yie teria, effe stic defo thod, uni	plane n tenso an isot rential ective constii rmatio	es of lor, Inv ropic equa teria, stres tutive on.	Total body for titions of Total Haigh–V s and ef equatio Total nation e	n shear s of Deviat Hrs three di equilibri Hrs Westerga fective st ns of pla Hrs nergy me	strain, oc oric strain mension um, com um, com urd stres rrain, St. astic flov ethod, up	etahedral n tensor, 9 al stress patibility 9 s space Venants v, Strain 9 pper and
principle strains, shear strain, Dev plane strain.3UNIT-IIIGeneralized Hoo space, for plane equations, Materi4UNIT-IVTrue stress and representation of theory of plastic hardening and weight5UNIT-VAnalysis method	derivation for maximum shear str iatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia d true strain, von-Mise's and Tre f von - Mise's and Tresca yield crit e flow, Prandtle–Reuss and Levy- ork hardening theories, work of pla s: Slab method, Slip line field met	rain and s of strain ips for a ns, differ als esca yie teria, effe stic defo thod, uni	plane n tenso an isot rential ective constii rmatio	es of lor, Inv ropic equa teria, stres tutive on.	Total body for titions of Total Haigh–V s and ef equatio Total nation e	n shear s of Deviat Hrs three di equilibri Hrs Westerga fective st ns of pla Hrs nergy me	strain, oc oric strain mension um, com um, com urd stres rrain, St. astic flov ethod, up	etahedral n tensor, 9 al stress patibility 9 s space Venants v, Strain 9 pper and
principle strains, shear strain, Dev plane strain.3UNIT-IIIGeneralized Hoo space, for plane equations, Mater4UNIT-IVTrue stress and representation of theory of plastic hardening and work5UNIT-VAnalysis method lower bound so	derivation for maximum shear str iatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia d true strain, von-Mise's and Tre f von - Mise's and Tresca yield crit flow, Prandtle–Reuss and Levy- ork hardening theories, work of pla s: Slab method, Slip line field method lutions. Application of Slab method	rain and s of strain ips for a ns, differ als esca yie teria, effe stic defo thod, uni	plane n tenso an isot rential ective constii rmatio	es of lor, Inv ropic equa teria, stres tutive on.	Total body for titions of Total Haigh–V s and ef equatio Total nation e	n shear s of Deviat Hrs three di equilibri Hrs Westerga fective st ns of pla Hrs nergy me	strain, oc oric strain mensiona um, com um, com ard stres rain, St. astic flow ethod, up	etahedral n tensor, 9 al stress patibility 9 s space Venants v, Strain 9 pper and
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principle strains, shear strain, Dev plane strain.3UNIT-IIIGeneralized Hoo space, for plane equations, Materi4UNIT-IVTrue stress and representation of theory of plastic hardening and we5UNIT-VAnalysis method lower bound so processes.Total hours to be Text book (s)	derivation for maximum shear str iatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia d true strain, von-Mise's and Tre f von - Mise's and Tresca yield crit flow, Prandtle–Reuss and Levy- ork hardening theories, work of pla s: Slab method, Slip line field method lutions. Application of Slab method	rain and of strain ips for a ns, differ als esca yie teria, effe -Mise's o stic defor thod, uni nod to f	plane n tenso an isot rential ective constitue forging	es of lor, Inv ropic equa teria, stres tutive on. deforr g, wir	Total body for tions of Total Haigh–\ s and ef equatio Total nation e e drawin	n shear s of Deviat Hrs three di equilibri Hrs Westerga fective st ns of pla Hrs nergy me ng, extru	strain, oc oric strain mensiona um, com um, co	etahedral in tensor, 9 al stress apatibility 9 s space Venants v, Strain 9 9 pper and d rolling
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principle strains, shear strain, Dev plane strain.3UNIT-IIIGeneralized Hoo space, for plane equations, Materi4UNIT-IVTrue stress and representation of theory of plastic hardening and we5UNIT-VAnalysis method lower bound so processes.Total hours to be Text book (s)1Timoshenko	derivation for maximum shear striatoric and Hydrostatic components oke's Law : Stress-strain relationsh e stress and plane strain condition ial (D) matrix for Orthotropic Materia d true strain, von-Mise's and Tre f von - Mise's and Tresca yield crit e flow, Prandtle–Reuss and Levy- ork hardening theories, work of pla s: Slab method, Slip line field meth lutions. Application of Slab meth taught	rain and of strain ips for a ns, differ als esca yie teria, effe -Mise's o stic defor thod, uni nod to f	plane n tenso an isot rential ective constitue forging	es of lor, Inv ropic equa teria, stres tutive on. deforr g, wir	Total body for tions of Total Haigh–\ s and ef equatio Total nation e e drawin	n shear s of Deviat Hrs three di equilibri Hrs Westerga fective st ns of pla Hrs nergy me ng, extru	strain, oc oric strain mensiona um, com um, co	etahedral in tensor, 9 al stress apatibility 9 s space Venants v, Strain 9 9 pper and d rolling
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CBIT	Αι	utonom						
Department	Mechanical Engineering	Pro	ogramm Na	ne Co me	de &	M.E	. (CAD/0	CAM)
		nester-l						
Course Code	Course Name	Hours	/ Week		Credit		um Marks	
ME 521	EXPERIMENTAL TECHNIQUES AND DATA ANALYSIS	4	0	P 0	<u>С</u> 3	Е 75	25	Total 100
Objective (s)	To get acquainted with improvi parameters. To gain the knowledge regarding	•	-	•	-	ess by	studying	various
Outcome (s)	Students can suggest suitable me Students can able to apply suitable				•		nario.	
1 UNIT-I					Total	Hrs		9
measurements by2UNIT-IITemperature Measuremeexpanding fluid, eFlow MeasuremeObstruction andanemometer. Flow3UNIT-IIIMetallurgical Studying crystSurface Measuremeasuring machi4UNIT-IVExperiment design	onstruction, Bridge circuits. Instru y photoelasticity. Holography, inter easurement: Circuits and instr electrical resistance, thermister, the ent : Transducers for flow measure drag methods. Vortex shredding ow visualization techniques, Shadov dies: Optical and electron microsco al structure and residual stresses. ements: Micro hardness, roughness ines. gn & data analysis: Statistical met design. Replication and randomiz	ferome umenta ermocou ements flow n w graph ppy, X-F Electro s, accur thods, F ation.	ter, Moi tion fo ples, p of Nor neters. is, Schl Ray diff n spect acy of Random	ir tech or diff yrome -com Ultra lieren ractio trosco dimer	niques, s Fotal Hrs erent tra- eters. pressible asonic, L photogra Total n, Bragg py, elect asions ar Total block desi	strain gau ansducer ansducer ansducer aser Do aphy. Int Hrs y's Law a ron micro ad forms. Hrs sign, Lati	uge roset 9 s viz, b pler and erferome and its ap probe. 3-D co- in and or	tes. imetallic, le fluids. Hotwire ter. 9 plication •ordinate 9
Data Analysis: I student's 't' test. analysis, Autocor	Deterministic and random data, ur Regression modeling, direct an relation and autoregressive modelin	nd intera			s. ANO	VA, F-te	est. Tim	e Series
Data Analysis: I student's 't' test. analysis, Autocor 5 UNIT-V Taguchi Methods cause effect mo Performance eva	Deterministic and random data, ur Regression modeling, direct an	nd interand ng. g with (level.	Orthogo	onal a	s. ANO Total arrays an on of De	VA, F-te Hrs d linear əsign an	est. Tim graphs. Id noise	e Series 9 Additive factors.
Data Analysis: I student's 't' test. analysis, Autocor 5 UNIT-V Taguchi Methods cause effect mo Performance eva application.	Deterministic and random data, ur Regression modeling, direct an relation and autoregressive modeling s: Experiment design and planning odel. Optimization of response aluation and Optimization by signa	nd interand ng. g with (level.	Orthogo	onal a	s. ANO Total arrays an on of De	VA, F-te Hrs d linear əsign an	est. Tim graphs. Id noise function	e Series 9 Additive factors. and its
Data Analysis: I student's 't' test. analysis, Autocor 5 UNIT-V Taguchi Methods cause effect mo Performance eva application. Total hours to be	Deterministic and random data, ur Regression modeling, direct an relation and autoregressive modeling s: Experiment design and planning odel. Optimization of response aluation and Optimization by signa	nd interand ng. g with (level.	Orthogo	onal a	s. ANO Total arrays an on of De	VA, F-te Hrs d linear əsign an	est. Tim graphs. Id noise function	e Series 9 Additive factors.
Data Analysis: I student's 't' test. analysis, Autocor 5 UNIT-V Taguchi Methods cause effect mo Performance eva application. Total hours to be Text book (s)	Deterministic and random data, ur Regression modeling, direct an relation and autoregressive modeling s: Experiment design and planning odel. Optimization of response aluation and Optimization by signation taught	nd interang. g with (level. al to no	Orthogo Identi Dise ra	onal a ficatic tios.	s. ANO Total mrays an on of De Concep	VA, F-te Hrs d linear esign an t of loss	est. Tim graphs. Id noise function	e Series 9 Additive factors. and its
Data Analysis:Istudent's't' test.analysis, Autocon5UNIT-VTaguchi Methodscauseeffect modePerformance evaapplication.Total hours to beText book (s)11. Holman22. VenkateIndia, D	Deterministic and random data, ur Regression modeling, direct an relation and autoregressive modeling s: Experiment design and planning odel. Optimization of response aluation and Optimization by signation taught a, J.P.: <i>Experimental Methods for E</i> esh, V.C., and Chandrasekharan, <i>E</i>	nd interang. g with (level. al to no Enginee	Orthogo Identi oise ra	effects onal a ficatic tios. Graw	s. ANO Total mrays an on of De Concep Hill Int., N	VA, F-te Hrs d linear esign an t of loss New York	est. Tim graphs. Id noise function	e Series 9 Additive factors. and its 15
Data Analysis:Istudent's't' test.analysis, Autocor5UNIT-VTaguchi Methodscauseeffect modePerformance evaapplication.Total hours to beText book (s)11. Holman22. Venkate	Deterministic and random data, ur Regression modeling, direct an relation and autoregressive modeling s: Experiment design and planning odel. Optimization of response aluation and Optimization by signation taught a, J.P.: <i>Experimental Methods for E</i> esh, V.C., and Chandrasekharan, <i>E</i>	nd interang. g with (level. al to no Enginee	Orthogo Identi oise ra	effects onal a ficatic tios. Graw	s. ANO Total mrays an on of De Concep Hill Int., N	VA, F-te Hrs d linear esign an t of loss New York	est. Tim graphs. Id noise function	e Series 9 Additive factors. and its 15
DataAnalysis:Istudent's't' test.analysis, Autocor5UNIT-VTaguchiMethodscauseeffectPerformanceevaapplication.Total hours to beText book (s)11. Holman22. VenkateIndia, DReferences1Davis, O.V.;	Deterministic and random data, ur Regression modeling, direct an relation and autoregressive modelin s: Experiment design and planning odel. Optimization of response aluation and Optimization by signa taught n, J.P.: <i>Experimental Methods for E</i> esh, V.C., and Chandrasekharan, <i>E</i> yelhi.	d interang. g with 0 level. al to no Engineen Experim	Orthogo Identi Dise ra	effects onal a ficatic tios. Graw fethoo	s. ANO Total mrays an on of De Concep Hill Int., f ds in Meta ongman,	VA, F-te Hrs d linear esign an t of loss New York al Cutting London.	est. Tim graphs. Id noise function (. c. g, Prentic	e Series 9 Additive factors. and its 15
DataAnalysis:Istudent's't' test.analysis, Autocor5UNIT-VTaguchiMethodscauseeffectPerformanceevaapplication.Total hours to beText book (s)11. Holman22. VenkateIndia, DReferences1Davis, O.V.;2Box and Jer	Deterministic and random data, ur Regression modeling, direct an relation and autoregressive modelin s: Experiment design and planning odel. Optimization of response aluation and Optimization by signa taught n, J.P.: <i>Experimental Methods for E</i> esh, V.C., and Chandrasekharan, <i>E</i> helhi.	nd interang. g with o level. al to no Enginee. Experim trial Exp asting an	Orthoge Identi Dise ra rs, McC ental M Derimer nd cont	effects onal a ficatic tios. Graw <i>Aethoc</i> <i>nts, Lo</i> <i>trol, H</i>	s. ANO Total arrays an on of De Concep Hill Int., I ds in Meta ongman, olden Da	VA, F-te Hrs d linear esign an t of loss New York al Cutting London. y, Sanfra	est. Tim graphs. Id noise function c. g, Prentic	e Series 9 Additive factors. and its 15 e Hall of

CBIT		Auto	nomou	s Reg	gulation			
Department	Mechanical Engineering	Pro	ogramm Na	ne Co me	de &	M.E	E. (CAD/C	CAM)
		ester-l						
Course Code	Course Name	-	/Week		Credit		um Marks	
		L	Т	Р	С	E	l	Total
ME 522	DESIGN FOR MANUFACTURE	4	0	0	3	75	25	100
Objective (s)	To provide understanding	g of mar	nufactu	ring p	rocesses	s and des	sign conc	epts
	To make the students u manufacturing.	Indersta	and the	e linka	age requ	ired betv	ween des	sign and
Outcome (s)	Ability to design suitable & non metallic componen		cturing	proce	ess .Capa	able of de	esigning	metallic
1 UNIT-I					Total	Hrs		9
mechanisms selection, ev Economic Use of Raw M ferrous materials aluminiu	lesign principles for ma valuation method, geometri laterials: Ferrous steel, ho m, copper, brass, non met	cal tole t rolled	rances, steel,	tolera cold f	ance con finished	trol and steel, sta	utilization ainless st	i. :eel, non
2 UNIT-II				Т	otal Hrs		9	
	arts, cold headed parts, e s, forging electro forming illed parts, milled parts.							
3 UNIT-III					Total	-		9
Non Metallic Components blow moulded, welded pla	s Design: Thermosetting plastic articles, ceramics.	lastic, ir	njection	mou	lded and	l rotation	al moulde	ed parts,
4 UNIT-IV					Total			9
Assembled Parts Design: bearing assembly.	Welded parts, arc, resista	ance, b	razed a	and so	oldered p	oarts, ge	ar box as	ssembly,
5 UNIT-V					Total			9
centred connections, pre machining, group techn requirements.	n: Retension, bolted com ess fitted connections, su ology, low cost automat	rface fi tion, co	nishing ompute	, plat r aide	ed parts ed man	, heat ti ufacture,	reated pa	arts, NC
Total hours to be taught							4	15
Text book (s) 1 1. James G. Bralla,	, "Hand book of product de	sign foi	r manut	facturi	ing" McC	Graw Hill	Co., 198	6
2 2. K.G. Swift "Know	vledge based design for M	anufact	ure", Ko	ogan	page Lirr	nited, 198	37.	

	CBIT	Αι	Itonom	ous Re	egula	tion			
De	partment	Mechanical Engineering	Pro	ogramn Na	ne Co me	de &	M.E	. (CAD/C	AM)
			nester-l						
Cour	se Code	Course Name	Hours	/Week	1	Credit		ım Marks	
			L	Т	Р	С	E	I	Total
ME 5	23	DATA BASE MANAGEMENT SYSTEMS	4	0	0	3	75	25	100
Obje	ctive (s)	Knowledge of DBMS, both in terr Application of DBMS to various n							
Outc	ome (s)	To get awareness of different type How to use data base systems to	es of da	tabase	S				
1 U	NIT-I					Total	Hrs	9	9
Intro	duction and	E.R. Model: Purpose of databa	se syst	ems,	Data	abstrac	tion Dat	a models	s, data
		, DML, DBA. Entities and entity				os and r	elationsh	nip sets N	Mapping
cons	traints, Prima	ary Keys E-R diagrams, reducing E	-R Diag	ram to	table	s.		-	
	INIT-II					Fotal Hrs		9	
		l and relational database desig							
		nercial query languages. Modifyir	ng the c	latabas	se vie	ws. Pitfa	alls in re	lational d	atabase
	in and norm	alization.						r .	
	NIT-III					Total			9
		odel and hierarchical data model:							
	y, virtual rec	odate and set processing facility,	Inree	Structu	ire dia	agram, c	lata retri	eval and	update
	NIT-IV	olus.				Total	Hrs		9
		Structure, Indexing and Hashing	. Phys	ical st	orage				
		apping relations, networks and hi							
	ked files.								
5 U	NIT-V					Total	Hrs	ļ	9
Distri	buted datab	base, security and integrity: Des	ign, tra	nspare	ncy a	ind auto	nomy, q	uery pro	cessing,
		rency control, deadlock handling a							
datat	base applica	tion.							
	hours to be	taught						4	5
	book (s)								
1	1. Korth, H	I.F. Silbenhatz, A., Database Con	cepts,	Mc Gr	aw Hi	l, 1986.			
2	2. Gio Wie	ederhold, Database Design, Mc G	raw Hill	1983.					
Refe	rences								
1		1. Daniel, R.B. Pipes, <i>Experimenta</i> all. 1984.	l Mecha	anics oi	f Fibre	Reinfor	ced Com	posite Ma	aterials,
	Prentice H	all, 1984.			f Fibre	Reinfor	ced Com	posite Ma	aterials,
1 2 3	Prentice H 3. Jefferey		system	S.			ced Com	posite Ma	aterials,

CBIT	AL	ıtonom	ous Re	egulat	tion			
Department	Mechanical Engineering	Pro	ogramm Na		de &	M.E	. (CAD/C	AM)
		ester-l						
Course Code	Course Name	Hours	/Week		Credit		m Marks	
		L	Т	Р	С	E		Total
ME 524	FRACTURE MECHANICS	4	0	0	3	75	25	100
Objective (s)	The course introducer the co fundamentals of elastic plastic fi solved to understand fracture pa toughness, crack propagation rate	racture ramete e.	mecha rs such	anics. 1 as s	As an e train ene	extension ergy relea	, numeri ase rate,	cals are fracture
Outcome	Due to cabin pressurization and d fatigue conditions and the concep applicable to solve real time probl	ts inhei						
1 UNIT-I					Total	Hrs		9
	ack in a Structure – Griffth Criteri ce failure analysis.	on – C	leavag	e frac	cture – [Ductile fr	acture -	Fatigue
					Fotal Hrs		9	
strain. 3 UNIT-III	·				Total			9
crack arrest – Crack Grack Gra	e: Energy release rate – Criterion for rack arrest in practice.		-		ick resist	ance cur	ve – Prin	ciples of
acioi - vanaoie	Browth: Fatigue crack growth test, s	stress ir	ntensity	facto	r, factors	s affectin	g stress	intensity
	Growth: Fatigue crack growth test, s amplitude service loading, retardati	stress ir on moo	ntensity lel.	facto			-	-
4 UNIT-IV Elastic Plastic F	amplitude service loading, retardati racture Mechanics: Elastic plastic fr	on moo	lel.		Total	Hrs	-	9
4 UNIT-IV Elastic Plastic F	amplitude service loading, retardati	on moo	lel.		Total	Hrs opening c	displacem	9
4UNIT-IVElastic Plastic Fintegral technique5UNIT-VApplication of F	amplitude service loading, retardati racture Mechanics: Elastic plastic fr	acture	concep	it – Ci	Total rack tip c Total	Hrs opening o Hrs	displacem	9 nent – J- 9
4UNIT-IVElastic Plastic Fintegral technique5UNIT-VApplication of F	amplitude service loading, retardati racture Mechanics: Elastic plastic fr ie; Determination of J-using FEM. racture Mechanics: Fracture design ntensity factor range – Use of crack	acture	concep	it – Ci	Total rack tip c Total	Hrs opening o Hrs	displacem crack gro	9 nent – J- 9
4UNIT-IVElastic Plastic Fintegral technique5UNIT-VApplication of Fcurve – Stress inTotal hours to beText book (s)	amplitude service loading, retardati racture Mechanics: Elastic plastic fr le; Determination of J-using FEM. racture Mechanics: Fracture design ntensity factor range – Use of crack g e taught	on moo acture n – Sele growth	del. concep ection o law.	t – Ci	Total rack tip c Total terials –	Hrs opening o Hrs fatigue o	displacem crack gro	9 nent – J- 9 wth rate
4 UNIT-IV Elastic Plastic F integral technique 5 UNIT-V Application of F curve – Stress in Total hours to be Text book (s) 1 1. David Publish	e amplitude service loading, retardati racture Mechanics: Elastic plastic fr ie; Determination of J-using FEM. racture Mechanics: Fracture design intensity factor range – Use of crack taught Broek – Elementary Engineering iners – 1978.	on moo acture growth Fractur	ection of law.	t – Ci of ma	Total rack tip c Total terials – s: Sifth o	Hrs opening o Hrs fatigue o off an N	displacem crack gro	9 nent – J- 9 wth rate
4UNIT-IVElastic Plastic Fintegral technique5UNIT-VApplication of Fcurve – Stress inTotal hours to beText book (s)11. DavidPublish	amplitude service loading, retardati racture Mechanics: Elastic plastic fr ie; Determination of J-using FEM. racture Mechanics: Fracture design intensity factor range – Use of crack taught Broek – Elementary Engineering	on moo acture growth Fractur	ection of law.	t – Ci of ma	Total rack tip c Total terials – s: Sifth o	Hrs opening o Hrs fatigue o off an N	displacem crack gro	9 nent – J- 9 wth rate
4 UNIT-IV Elastic Plastic F integral technique 5 UNIT-V Application of F curve – Stress in Total hours to be Text book (s) 1 1. David Publish 2 Calcote, L. References	e amplitude service loading, retardati racture Mechanics: Elastic plastic fr ie; Determination of J-using FEM. racture Mechanics: Fracture design intensity factor range – Use of crack taught Broek – Elementary Engineering iners – 1978.	on moc acture n – Selo growth Fractur	ection of law.	t – Ci of ma hanics	Total rack tip c Total terials – s: Sifth o /an Nost	Hrs opening c Hrs fatigue c off an N rand, 196	displacem crack gro loordhoff	9 hent – J- 9 wth rate 5 Internal

CBIT	Αι	tonom	ous Re	egula	tion			
Department	Mechanical Engineering	Pro	gramn Na	ne Co me	de &	M.E. (C	AD/CAM)
	Sem	ester-l						
Course Code	Course Name	Hours/	'Week		Credit	Maximu	um Marks	5
		L	<u>T</u>	P	C	E		Total
ME 525	DESIGN OF PRESS TOOLS	4	0	0	3	75	25	100
Objective (s)	To make the students understand					-	• •	
	To make students capable of de	0 0		•	ess tools	which a	are safe,	easy to
	operate, reliable and economical			-				
Outcome (s)	The students will understand the l	pasic co	ncepts	s and	principle	involved	in desigr	ning
	press tools,							
	The students will be in a position	o indep	enden	tly de	sign vari	ous press	s tools wi	nich will
1 UNIT-I	cater to requirement of industry.				Total		1	•
	f Mechanical, Hydraulic, and pneum	otio pro		Droop				9
	bles of stretch forming machines, pr							
principles of pre		ncipies		ung		aung eq	upment.	Design
2 UNIT-II					Total Hrs	5	9	
Design of Dies	: Introduction terminology shearir	na dies-	types					shearing
	e and tolerances of die opening and							
	with inclined edges - strip layouts,						5	
3 UNIT-III					Total			9
Elements of sh	earing dies – die plates – split dies							
		, ruies c	of deve	elopm	ent for s	split dies,	inserts,	types of
	holders, punches – strippers – calc							
punches, punch – pilots – stock		ulation	of spri		ind rubbe	er ejector		
punches, punch – pilots – stock 4 UNIT-IV	n holders, punches – strippers – calo guides – alignment system design fo	ulation r press t	of spri tools.	ngs a	nd rubbe	er ejector Hrs	, shedde	rs, stops 9
punches, punch – pilots – stock 4 UNIT-IV Compound dies	h holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de	r press tevices –	of spri tools.	ngs a	nd rubbe Total ted die, ł	er ejector Hrs norn dies	, shedde	rs, stops 9 ub-press
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi	n holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, l	vilation r press t vices – aminatic	of spri tools. cam a on die	ngs a	nd rubbe Total ted die, f Bending	er ejector Hrs norn dies dies, th	, shedde (type, s eory of	rs, stops 9 ub-press bending
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of	h holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de	vilation r press t vices – aminatic	of spri tools. cam a on die	ngs a	nd rubbe Total ted die, I Bending es, bendir	Hrs Hrs norn dies dies, th ng on pre	, shedde (type, s eory of ess brake	rs, stops 9 ub-press bending
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V	n holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, l blank, spring back, curling, flanging	vices – aminatic and pres	of spri tools. cam a on die ss bral	ngs a actuat s – ke die	nd rubbe Total ted die, I Bending es, bendir Total	Hrs Hrs norn dies dies, th ng on pre Hrs	, shedde s (type, s heory of ess brake	rs, stops 9 ub-press bending 9
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and for	h holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, l blank, spring back, curling, flanging prming Dies: Theory of drawing, b	ulation r r press t evices – aminatic and pres	of spri tools. cam a on die ss bral	ngs a actua s – ke die nent,	nd rubbe Total ted die, I Bending is, bendir Total strain fa	Hrs horn dies dies, th hg on pre Hrs lactor, cal	, shedde (type, s heory of ess brake culation	rs, stops 9 ub-press bending 9 of force,
punches, punch <u>pilots – stock</u> <u>4</u> UNIT-IV Compound dies dies) – precisi development of <u>5</u> UNIT-V Drawing and for construction of	h holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, k blank, spring back, curling, flanging prming Dies: Theory of drawing, b drawing and drawing dies – Drawi	ulation r press f evices – aminatic and pres lank de ng of re	of spri tools. cam a on die ss bral velopr ectang	ngs a actua s – ke die nent, ular (Total ted die, I Bending s, bendir Total strain fa compone	Hrs horn dies dies, th ng on pre Hrs lotor, cal nts (dev	; shedde (type, s heory of ess brake culation elopment	rs, stops 9 ub-press bending 9 of force
punches, punch <u>pilots – stock</u> 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and for construction of draw beeds) –	h holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, k blank, spring back, curling, flanging prming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy	ulation r press f evices – aminatic and pres lank de ng of re /draulic	of spri tools. cam a on die ss bral velopr ectang syster	ngs a actua s – ke die nent, ular (n) – l	Total ted die, I Bending s, bendir Total strain fa compone Defects i	Hrs horn dies dies, th ng on pre Hrs hotor, cal nts (dev n deep d	; shedde ; (type, s heory of ess brake culation elopment frawing –	rs, stops 9 ub-press bending 9 of force
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and for construction of draw beeds) – Metal forming te	h holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, la blank, spring back, curling, flanging prming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy echniques – Discussion of various co	ulation r press f evices – aminatic and pres lank de ng of re /draulic	of spri tools. cam a on die ss bral velopr ectang syster	ngs a actua s – ke die nent, ular (n) – l	Total ted die, I Bending s, bendir Total strain fa compone Defects i	Hrs horn dies dies, th ng on pre Hrs hotor, cal nts (dev n deep d	; shedde (type, s heory of ess brake culation elopment trawing – gn.	rs, stops 9 ub-press bending 9 of force, t, stages Modern
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and for construction of draw beeds) – Metal forming te Total hours to b	h holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, la blank, spring back, curling, flanging prming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy echniques – Discussion of various co	ulation r press f evices – aminatic and pres lank de ng of re /draulic	of spri tools. cam a on die ss bral velopr ectang syster	ngs a actua s – ke die nent, ular (n) – l	Total ted die, I Bending s, bendir Total strain fa compone Defects i	Hrs horn dies dies, th ng on pre Hrs hotor, cal nts (dev n deep d	; shedde (type, s heory of ess brake culation elopment trawing – gn.	rs, stops 9 ub-press bending 9 of force
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and for construction of draw beeds) – Metal forming te Total hours to b Text book (s)	a holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, l blank, spring back, curling, flanging prming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy echniques – Discussion of various co e taught	ulation r press f aminatic and pres lank de ng of re ng of re mputer s	of spri tools. cam a on die ss bral velopr ectang syster softwa	ngs a actuar s – ke die nent, ular (n) – l re for	nd rubbe Total ted die, I Bending s, bendir Total strain fa compone Defects i sheet m	er ejector Hrs norn dies dies, th ng on pre Hrs ictor, cal nts (dev n deep c etal desig	; shedde (type, s heory of ess brake culation elopment trawing – gn.	rs, stops 9 bending 9 of force 4, stages
punches, punch pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and for construction of draw beeds) – Metal forming ter Total hours to b Text book (s) 1 1. Funda	a holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, la blank, spring back, curling, flanging prming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy echniques – Discussion of various co e taught	evices – aminatic and pres lank de ng of re /draulic mputer s	of spri tools. cam a on die ss bral velopr ectang syster softwa lall, Ne	ngs a actuar s – ke die nent, ular o n) – l re for	nd rubbe Total ted die, I Bending is, bendir Total strain fa compone Defects i sheet m elhi, 1987	er ejector Hrs norn dies dies, th ng on pre Hrs ictor, cal nts (dev n deep c etal desig	; shedde (type, s heory of ess brake culation elopment trawing – gn.	rs, stops 9 ub-press bending 9 of force t, stages Moderr
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and for construction of draw beeds) – Metal forming ter Total hours to b Text book (s) 1 1. Funda 2 2. Die de	a holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, l blank, spring back, curling, flanging prming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy echniques – Discussion of various co e taught	evices – aminatic and pres lank de ng of re /draulic mputer s	of spri tools. cam a on die ss bral velopr ectang syster softwa lall, Ne	ngs a actuar s – ke die nent, ular o n) – l re for	nd rubbe Total ted die, I Bending is, bendir Total strain fa compone Defects i sheet m elhi, 1987	er ejector Hrs norn dies dies, th ng on pre Hrs ictor, cal nts (dev n deep c etal desig	; shedde (type, s heory of ess brake culation elopment trawing – gn.	rs, stops 9 ub-press bending 9 of force t, stages Moderr
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and for construction of draw beeds) – Metal forming te Total hours to b Text book (s) 1 1. Funda 2 2. Die de References	a holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, la blank, spring back, curling, flanging orming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy echniques – Discussion of various co e taught omentals of tool Design – ASTME, Pr esign Hand book – AISME, Mc Graw	evices – aminatic and pres lank de ng of re vdraulic mputer s entice H Hills, Ne	of spri tools. cam a on die ss bral velopr ectang syster softwa lall, Ne ew Yor	ngs a actuar s – ke die nent, ular (n) – l re for ew De k, 19	nd rubbe Total ted die, I Bending is, bendir Total strain fa compone Defects i sheet m elhi, 1987 65	er ejector Hrs norn dies dies, th ng on pre Hrs ictor, cal nts (dev n deep c etal desig	; shedde (type, s heory of ess brake culation elopment trawing – gn.	rs, stops 9 ub-press bending 9 of force t, stages Moderr
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and for construction of draw beeds) – Metal forming te Total hours to b Text book (s) 1 1. Funda 2 2. Die de References 1 3. Heinrin	a holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, l blank, spring back, curling, flanging prming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy echniques – Discussion of various co e taught mentals of tool Design – ASTME, Pr esign Hand book – AISME, Mc Graw ch Makelt, <i>Mechanical Presses</i> , Edw	evices – aminatic and pres lank de ng of re /draulic mputer s entice H Hills, Ne ard Arno	of spri tools. cam a cam a con die ss bral velopr ectang syster softwa lall, Ne ew Yor old, Lo	ngs a actua s – ke die nent, ular (n) – l re for ew De k, 190	Total ted die, I Bending s, bendir Total strain fa compone Defects i sheet m elhi, 1987 65	er ejector Hrs norn dies dies, th ng on pre Hrs ictor, cal nts (dev n deep c etal desig	; shedde (type, s heory of ess brake culation elopment trawing – gn.	rs, stops 9 ub-press bending 9 of force t, stages Moderr
punches, punch – pilots – stock 4 UNIT-IV Compound dies dies) – precisi development of 5 UNIT-V Drawing and fc construction of draw beeds) – Metal forming te Total hours to b Text book (s) 1 1. Funda 2 2. Die de References 1 3. Heinrin 2 4. Serop	a holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, l blank, spring back, curling, flanging orming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy echniques – Discussion of various co e taught omentals of tool Design – ASTME, Pr esign Hand book – AISME, Mc Graw ch Makelt, Mechanical Presses, Edw e Kalpakjain, Mechanical Processing	evices – aminatic and pres lank de ng of re /draulic mputer s entice H Hills, Ne ard Arno in Mate	of spri tools. cam a cam a cam a son die ss bral velopr ectang syster softwa lall, Ne ew Yor old, Lo orials,	ngs a actua s – ke die nent, ular (n) – l re for ew De k, 190	Total ted die, I Bending s, bendir Total strain fa compone Defects i sheet m elhi, 1987 65	er ejector Hrs norn dies dies, th ng on pre Hrs ictor, cal nts (dev n deep c etal desig	; shedde (type, s heory of ess brake culation elopment trawing – gn.	rs, stops 9 ub-press bending 9 of force t, stages Moderr
punches, punch -pilots - stock 4 UNIT-IV Compound dies dies) - precisi development of 5 UNIT-V Drawing and for construction of draw beeds) - Metal forming ter Total hours to b Text book (s) 1 1. Funda 2 2. Die de References 1 3. Heinrif 2 4. Serop 3 5. Javoro	a holders, punches – strippers – calo guides – alignment system design fo s, progressive dies, stock feeding de on shearing dies, shaving dies, li blank, spring back, curling, flanging orming Dies: Theory of drawing, b drawing and drawing dies – Drawi Ironing (application of rubber and hy echniques – Discussion of various co te taught omentals of tool Design – ASTME, Pr esign Hand book – AISME, Mc Graw ch Makelt, Mechanical Presses, Edw e Kalpakjain, Mechanical Processing onkov V.A and Chaturvedi. <i>R.C. Rolli</i>	evices – aminatic and pres lank de ng of re /draulic mputer s entice H Hills, Ne ard Arno in Mate ng of Me	of spri tools. cam a cam a cam a cam a son die ss bral velopr ectang syster softwa lall, Ne ew Yor old, Lo erials, etals.	ngs a actua s – ke die nent, ular o n) – l re for ew De k, 190 hdon 1967.	Total ted die, I Bending is, bendir Total strain fa compone Defects i sheet m	er ejector Hrs norn dies dies, th ng on pre Hrs nctor, cal nts (dev n deep c etal desig	; shedde (type, s heory of ess brake culation elopment trawing – gn.	rs, stops 9 ub-press bending 9 of force t, stages Moderr
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	AL	Itonomous					
Department	Mechanical Engineering	Progra	amme Co Name	ode &	M.E	E. (CAD/0	CAM)
	Sem	lester-l	Nume				
Course Code	Course Name	Hours/W	eek	Credit	Maximu	um Marks	3
		L T	P	С	E	1	Total
ME 526	DESIGN OF DIES	4 0	0	3	75	25	100
Objective (s)	To make students understand th	e various	steps ar	nd proced	ure invo	lved in d	lesigning
	and manufacturing dies.						
	To make students capable of so	lving comp	lex geor	netric pro	blems re	elated to	tool and
	die making.	0 1	U	•			
Outcome (s)	The students will understand the	orocedure	involved	in desian	ing and r	nanufact	uring of
	dies.						
	The student will be in a position to	independ	ently des	sign dies r	equired f	for the in	dustry.
1 UNIT-I	-			Total	Hrs		9
Design principles	s for dies of thermo-plastic and th	ermo-setti	ng comp	onents.	Impress	ion core	cavities,
	es, guide pillars and bushes, eje						
	of actuating the splits, moulds of						
	ler – feed systems. Design prin	ciples and	l standa	rds for T	ransfer a	and com	pression
moulding dies.							
	Mould for a spindle component w	with sleeve,	pin ejec	tion. Mo	uld with	splits Mu	ulti-cavity
	er plate, inserts, ejectors.			Fotal Hrs			
2 UNIT-II	r metal mould Castings, Die casting			otal Hrs		9	
	s, injection systems, rack and pinic						0.1
	ng machines.		ut pins a		-	-	
3 UNIT-III	ng machines.		-	Total	Hrs	-	9
3 UNIT-III Design of various	ng machines. s types of dies – Single cavity, mult	i cavity, co	mbinatic	Total	Hrs es. Align	ment of	9 dies with
3 UNIT-III Design of various sprue. Design a	ng machines. s types of dies – Single cavity, mult pproach for die elements. Selectio	i cavity, co on of mater	mbinatic rials and	Total n, unit die heat trea	Hrs es. Align tment fo	ment of r die cas	9 dies with ting dies
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3UNIT-IIIDesign of varioussprue.Design aland elements – cdetails.FinishingBulk forming tools4UNIT-IVOpen die forging.tolerances.Methforging.Calculatdie forging as per5UNIT-VDie blocks for forBlocker impressionand cutter calcuHorizontal forging.reducer rollers.Fextrusion.Total hours to beText book (s)11.References	ing machines. a types of dies – Single cavity, mult pproach for die elements. Selectic die casting alloys – types of die cas g, Trimming, and inspection. Graves a data a second second second second b, Advantages of open die forging of tods of open die forging. Design of b, Advantages of open die forging of tods of open die forging. Design of fulle tods of open die forging of tods of open die forging of taught f S.E., Forging & Forming Metals, T	i cavity, co on of mater ting alloys, vity die cas ver closed f dies. Clo f dies. Clo f dies. Clo ng in furna er impressi tools. Plar forging, dies. Calo e shop. Ro	mbinatic rials and , Case si sting – E die forg osed die ces. All on, Roll on, Roll nning lay piercing, culations Il forming	Total n, unit die heat trea udies on bie design Total ing. Calc forging. I owances Total er impres out of mu and trin on upse g, wire dra	Hrs es. Align tment fo executed with co Hrs ulation co Preparati and tole Hrs sion, Be Iti impres ming dies awing for	iment of r die cas d dies an res and of allowar ion of ma rances for ender imp ssion die es, coini s – Pres ward & b	9 dies with sting dies d design inserts - 9 nces and aterial for or closed 9 pression s. Flash ing dies s forging packward

1	CBIT		Autor	nomou	s Reg	ulation				
	Department	Mechanical	Pro	gramm	ne Co	de &	М	.E. Thern	nal	
	Department	Engineering		Na	me		E	ngineerir	ng	
			ester-l							
Cour	se Code	Course Name	Hours	/Week		Credit		m Marks		
			L	Т	Ρ	С	E	I	Total	
ME 6	502	COMPUTATIONAL FLUID DYNAMICS	4	0	0	3	75	25	100	
Obje	ctive (s)	To create the awareness of the importance of principles of fluid dynamics in engineering applications such as aerodynamic, heat transfer, turbo-machinery etc,.							hinery	
Outc	ome (s)	To enable to the students To interpret the results o						erent flow	/S.	
1 L	INIT – I		otainoa	by the		Total		9	9	
N – equa	S equations. Differe	nd Energy equations, Navie Intial equations for steady Introduction to turbulence	and u	nstead	y stat	e heat c	onductio	n. Differe	ential	
	JNIT – II					Total	Hrs	ę	9	
Ellipt	ic, parabolic and hyp	erbolic equations, Initial an	d boun	dary va	lue pi	oblems.				
		erence methods - forwa					differen	ce. Error	ъ,	
		lysis by von Neumann. Co	nvergei	nce crit	eria.					
	JNIT – III					Total		-	9	
		f grid O,H,C. Coordinate tra	ansform	nation, a	algebi	aic meth	ods. Uns	structured	l grid	
4 L	INIT – IV								-	
Jaco	bi, Gauss Seidel, AD		generation Total Hrs 9 4 UNIT – IV Total Hrs 9 Finite difference solutions-Parabolic PDEs – Euler, Crank Nicholson, Implicit methods, Elliptic PDEs – Euler Provide the formation of the solution							
- v0	rticity method & MAC		or Visco	ous inc	ompre	essidie ti	ow using	Stream		
Jacobi, Gauss Seidel, ADI, methods. FD- solution for Viscous incompressible flow using Stream function – Vorticity method & MAC method. 5 UNIT – V Introduction to Finite volume method. Finite volume formulations for diffusion equation, convection									function	
5 L Intro diffus	INIT – V duction to Finite vo	method.	me for	nulatio	ns fo	Total r diffusio	Hrs on equat	ion, conv	function 9 /ection	
5 U Intro diffus grids	INIT – V duction to Finite vo sion equation. Solutio	; method. lume method. Finite volu	me for	nulatio	ns fo	Total r diffusio	Hrs on equat	ion, conv e of Stag	function 9 /ection	
5 U Introd diffus grids Total	INIT – V duction to Finite vo sion equation. Soluti SIMPLE Algorithm. hours to be taught book (s):	; method. lume method. Finite volu on algorithm for pressure	me forr velocity	mulatio ⁷ coupli	ns fo ng in	Total r diffusio steady f	Hrs on equat lows. Us	ion, conv e of Stag	function 9 vection ggered 5	
5LIntrodiffusgridsTotalText1	NIT – V duction to Finite vo sion equation. Soluti SIMPLE Algorithm. hours to be taught book (s): Pradip Niyogi, Chał Pearson Education,	method. Iume method. Finite volu on algorithm for pressure krabartty S.K, Laha M.K., 2005.	me forr velocity	mulatio coupli	ns fo ng in	Total r diffusio steady f mputatio	Hrs on equat lows. Us nal Fluid	ion, conv e of Stag 4 Dynami	function 9 vection ggered 5 cs',	
5LIntrodiffusgridsTotalText12	INIT – V duction to Finite vo sion equation. Solutio SIMPLE Algorithm. hours to be taught book (s): Pradip Niyogi, Chal Pearson Education, Muralidhar K, Sund House, 2003.	method. Iume method. Finite volu on algorithm for pressure krabartty S.K, Laha M.K.,	me forr velocity	mulatio coupli	ns fo ng in	Total r diffusio steady f mputatio	Hrs on equat lows. Us nal Fluid	ion, conv e of Stag 4 Dynami	function 9 vection ggered 5 cs',	
5LIntro diffus gridsTotalText12	INIT – V duction to Finite vo sion equation. Solution SIMPLE Algorithm. I hours to be taught book (s): Pradip Niyogi, Chal Pearson Education, Muralidhar K, Sunda House, 2003. rence(s):	method. Iume method. Finite volu on algorithm for pressure crabartty S.K, Laha M.K., 2005. ararajan T, 'Computationa	me forr velocity 'Introdu	r coupli uction 1	ns fo ng in to Co	Total r diffusic steady f mputatio at transf	Hrs on equat lows. Us nal Fluid	ion, conv e of Stag 4 Dynami	function 9 vection ggered 5 cs',	
5LIntroddiffusgridsTotalText12Refe3	INIT – V duction to Finite vo sion equation. Solution SIMPLE Algorithm. I hours to be taught book (s): Pradip Niyogi, Chal- Pearson Education, Muralidhar K, Sunda House, 2003. rence(s): John D Anderson, 'O	method. lume method. Finite volu on algorithm for pressure krabartty S.K, Laha M.K., 2005. ararajan T, 'Computationa Computational Fluid Dynam	me forr velocity 'Introdu I Fluid	r coupli uction f flow ar	ns fo ng in to Co nd He Hill, Ir	Total r diffusic steady f mputatio at transf	Hrs on equat lows. Us nal Fluid fer', Narc	ion, conv e of Stag <u>4</u> Dynami sa Publis	function yection ggered 5 cs', shing	
5UIntrodiffusgridsTotalText12Refe	INIT – V duction to Finite vo sion equation. Solution SIMPLE Algorithm. I hours to be taught book (s): Pradip Niyogi, Chal- Pearson Education, Muralidhar K, Sunda House, 2003. rence(s): John D Anderson, 'C Patankar, S.V, 'Num York, 1980.	method. Iume method. Finite volu on algorithm for pressure crabartty S.K, Laha M.K., 2005. ararajan T, 'Computationa	me forr velocity 'Introdu I Fluid lics', Mc	mulatio coupli uction f flow ar : Graw w', Her	ns fo ng in to Co nd He Hill, Ir	Total r diffusic steady f mputatio at transf nc., 1995 ere Publi	Hrs on equat lows. Us nal Fluid rer', Narc shing Co	ion, conv e of Stag <u>4</u> Dynami sa Publis	function yection ggered 5 cs', shing	

CBIT	Au	itonon	nous R	egula	tion			
Department	Mechanical Engineering	Pr	ogram		de &	ME	E. (CAD/C	
Department			-	ame		IVI. L		
	Sem	ester-			-			
Course Code	Course Name		urs/We		Credit		ximum M	
		L	Т	Р	С	E		Total
ME 527	RAPID PROTOTYPING PRINCIPLES AND APPLICATIONS	4	0	0	3	75	25	100
Objective (s)	To make students understand	the	basic (conce	ots of v	arious i	rapid pro	ototyping
,	technologies. To understand and for any given application.			-				
Outcome (s)	 Describe various CAD issues model manipulation, formulate ar surface reconstruction from phys based surface fitting. explain and summarize the prin commonly used RP systems: & e for quick batch production of plast 	nd solv sical p ciples explain	and ke	cal pro e moo ey chai ummai	blems o dels thro racteristic	n revers ugh digit cs of RP	e engine iizing and technolo	ering for d spline- gies and
1 UNIT-I			motar		Total	Hrs		9
Introduction: Pr Advantages and Rapid Prototyping	rototyping fundamentals, Historica Limitations of Rapid Prototyping, (g Process Chain: Fundamental Auto	Comm	only us	ed Te sses,	ndamenta rms, Cla Process	als of R ssificatio Chain.	apid Pro n of RP	totyping,
2 UNIT-II	apid Prototyping Systems: S				otal Hrs		9	
laser and laser so (SGC): Models Disadvantages, C Solid-based Ra specifications, Pr Fused Deposition Advantages and D 3 UNIT-III Powder Based F Process, workin dimensional Prir Advantages and D Rapid Tooling: Tooling Classific Ceramic tools, In	pid Prototyping Systems: Lan rocess, working principle, Applicat n Modeling (FDM): Models and sp Disadvantages, Case studies. Rapid Prototyping Systems: Sele g principle, Applications, Advar nting (3DP): Models and specif Disadvantages, Case studies. Introduction to Rapid Tooling (RT ation: Indirect Rapid Tooling Me westment Casting, Spin Casting, D pirect AIM, LOM Tools, DTM Rapid	and Di workin ninatec ions, A ecifica ctive la ntages fication), Cor thods: Die cas	sadvan g prir d Obje Advanta tions, I aser sir aser sir and is, Pro iventior Spray sting, S	tages, nciple, ct Ma ages a Proces Disad Disad Disad Disad Disad Disad Cess, Mal To Meta and C	, Case st Applica anufactur and Disa ss, worki <u>Total</u> (SLS): I vantages working oling Vs al Depos casting, 3	udies. So ations, / ing (LO dvantage ng princi Hrs Models a s, Case g princip RT, Nee SD Keltoo : Tool Pr	blid grour Advantag M): Mod es, Case ple, Appl nd specif studies ble, Appl ed for R TV Epox of proces rocess ar	d curing es and lels and studies. lications, . Three lications, T. Rapid y Tools, s. Direct
	na Data Formata: CTL Format		Droble					-
Invalid Tessellate Formats. Rapid Prototypin Expert, 3 D View,	ng Data Formats: STL Format, S ed Models, STL file Repairs: Ge ng Software's: Features of various Velocity 2, Rhino, STL View 3 Dat	eneric s RP s	Solutio oftware	on, Ot	her Tran Magics, 3 D do	nslators, Mimics, octor.	Newly P Solid Vie	Proposed ew, View
5 UNIT-V					Total			9
Analysis and Pla application, Arts simulation of cor	: Application – Material Relationsh anning, Aerospace Industry, Auton and Architecture. RP Medica mplex surgery, Customised Implar c Science and Anthropology, Visuliz	notive I and nts &	Industr Bioen Prosthe	ry, Jev ginee esis, E	velry Ind ring Ap Design a	lustry, Co plication	oin Indus I s: Planr	stry, GIS ning and
Total hours to be	taught						4	45
C.S, World 2 2. Rapid Man References	otyping: Principles and Applications - C Scientific publications , Third Edition, 2 ufacturing – D.T. Pham and S.S. Dimo	2010. v, Sprir	nger , 20	001	and LIM			
13. Wholers R24. Rapid Prote	eport 2000 – Terry Wohlers, Wohlers A otyping & Manufacturing – Paul F.Jaco	ssociat bs, ASI	es, 200 ME Pres	0 ss, 199	6.			

CBIT	Au	Itonom	ous Re	egula	tion			
Department	Mechanical Engineering		ogramn Na	ne Co me	de &	M.E	. (CAD/C	AM)
		ester-l				r		
Course Code	Course Name	Hours	/Week		Credit		m Marks	
		L	Т	Р	С	E		Total
ME 528	FLEXIBLE MANUFACTURING SYSTEMS	4	0	0	3	75	25	100
Objective (s) The course covers the significance of manufacturing systems over numerical control machining methods. The fundamentals of flexible manufacturing system are clearly stated from the design concepts that include usage of operation cycle description, robot automatic guided vehicle, chip removal, washing station, fixturing etc								arly n, robot,
Outcome (s)	Upon crediting the subject, the i Students can independently de performed for manufacturing of programmable logical controller.	velop	the se	quenc	ce of op unders	perations tand the	that are	e to be
1 UNIT-I					Total			9
Evolution of Ma	anufacturing Systems: FMS defini	ition ar	nd des	criptic	on, Gene	eral FMS	6 conside	erations,
Systems Plannir selection, system staff considerati	ells, Cellular versus Flexible Manufa ng: Objective, introduction planning n description and sizing, facility pr ons, team work, communication ssifications, employee training.	g, prep eparati	aration on plaı	nning,	FMS la	youts. H	uman re	sources:
2 UNIT-II	<u>.</u>			-	Total Hrs	3	9	
	Driving Force: Definition, description	tion an	d char					acturina
quantity applica manufacturing ce Group Technolog	escription, benefits and relationshi tion principles. Single manufactu ells. gy: Concepts, classification and coc rank order clustering technique.	ure Ce	ell — c	desigr	n schedu	uling of	jobs or	single
3 UNIT-III	rank order clustering technique.				Total	Uro		9
	sing Bottleneck, Extended bottlened	k mod	ale Dro					
centres, Machin information, wor and deburring - coordinate meas	 k-holding and work-changing equip station types and operation desuring machines, types, construction 	rations oment, escriptic	perfor automa on, imp	med, ated f portar	axes, p eatures ice to a	and capa	ning, and abilities, d manufa	l format cleaning acturing,
4 UNIT-IV					Total	Hrs	9	9
	ement and storage systems-AGVs	s, Robo	ots, aut	omat				
storage space d recovery system control of cutting guidelines, work workstations – M	esign, queuing carousels and auto s, auxiliary support equipment, cutt tools, Tool Management, tool strate holding considerations, General fixt anual, automated and transfer lines	matic v ing too egies, d turing, N	vork ch ls and ata trar Aodula	hange tool M hsfer, r fixtu	rs, coola lanagem tool mon ring. FM\$	nt and c ent – int itoring ar S and the	hip Dispo roduction nd fault do relations	osal and , getting etection, ship with
5 UNIT-V					Total			9
	Hardware, Software, Communicatio							
	ing usages, hardware configuration networks. FMS implementation.	on, pro	gramm	able	logic co	ntrollers,	cell co	ntrollers,
Total hours to be	e taught						4	5
Text book (s)								
1 1. Parrish	, D.J., ' <i>Flexible Manufacturing</i> ', - Bu	tter Wo	rths – I	Heine	mann, O	xford, 19	93.	
2 2. Groove	r, M.P., 'Automation, Production Sy	stems a	and CIN	⁄/, - Р	rentice H	lall India,	1989.	
References								
	A., 'Intelligent Manufacturing Syste							
Hall, 19							<i>ion</i> ',-Cha	pman &
3 5. Ranky,	P.G., 'Design and Operation of FM	S', - IFS	S Publis	shers,	UK, 198	8		

	A	utonom	ous R	egula	tion			
Department	Mechanical Engineering	Pro	gramm		de &	ME	E. (CAD/C	:AM)
Boparanona		L .	Na	me				,,
<u> </u>		ester-l						
Course Code	Course Name	Hours/			Credit		um Marks	
ME 529	NON-TRADITIONAL MACHINING AND FORMING	L 4	Т 0	Р 0	C 3	E 75	25	Total 100
Objective (s)	To make the students underst	and the	nood	and	the ann	lications	of pontr	aditional
Objective (3)	machining processes. Students should able to choose t							autional
Outcome (s)	Students can select economical							
	Students can compare different premoval rate and surface finish reference			given	application	on based	l on meta	I
1 UNIT-I					Total	Hrs		9
	eed for non-traditional machini	ng prod	cesses	. Pro			n, class	ification,
	of different processes.	0 1					,	,
	ess: Ultrasonic Machining-Definiti	on-Mech	nanism	of m	etal elen	nents of	the proce	ess- Tool
feed mechanism.	Theories of mechanics of causing	effect of	param	neter	applicatio	ons.		
Abrasive Jet M	achining: Principles - paramet	ers of	the p	roces	s, applio	cations,	advantag	ges and
disadvantages.								
	ning (WJM): Schematic diagram, e	equipme	nt use				lications.	
2 UNIT-II					Fotal Hrs		9	
	emoval Process: Electric dischar							
	sic EDM circuitry-spark erosion.							
	circuits- critical resistance param							
	oplications. Wire EDM principle	and ope	eration	. Wir	e materi	als, wire	e tension	and its
parameters. Appli	cations						1	•
3 UNIT-III					Total			9
	and Chemical Processes: Ele							
	of ECM Chemistry of the ECM pa	irameter	SOLU				alion of l	
	inomian of ECM propage Undrag				roooo r	o lo rizoti		
	ynamics of ECM process-Hydroc	lynamics	s of E				on. Tool	Design-
advantages and	disadvantages - applications. E	lynamics	s of E				on. Tool	Design-
advantages and Electrochemical d	disadvantages - applications. E eburring.	lynamics lectro (s of E Chemio	cal Ġ	Frinding-E	Electro C	on. Tool Chemical	Design- holding
advantages and Electrochemical d Plasma Arc Mac	disadvantages - applications. E eburring. hining: Introduction-Plasma-Gene	lynamics lectro (ration of	s of E Chemic Plasn	cal Ġ na an	Frinding-E	Electro C	on. Tool Chemical	Design- holding
advantages and Electrochemical d Plasma Arc Mac removal, PAN par	disadvantages - applications. E eburring.	lynamics lectro (ration of	s of E Chemic Plasn	cal Ġ na an	Frinding-E d equipm cations.	Electro (on. Tool Chemical chanism c	Design- holding of metals
advantages and Electrochemical d Plasma Arc Mac removal, PAN par 4 UNIT-IV	disadvantages - applications. E eburring. hining: Introduction-Plasma-Gene ameters-process characteristics -	lynamics Electro (ration of type of to	s of E Chemio f Plasn orches	cal Ġ na an appli	brinding-E d equipm cations. Total	Electro (nent Mec Hrs	on. Tool Chemical chanism c	Design- holding of metals 9
advantages and Electrochemical d Plasma Arc Mac removal, PAN par 4 UNIT-IV Electron Beam M	disadvantages - applications. E eburring. hining: Introduction-Plasma-Gene ameters-process characteristics - f Machining (EBM): Introduction-Ec	lynamics Electro (ration of type of to quipmen	s of E Chemio f Plasn orches t for p	cal Ġ na an appli roduc	d equipm <u>cations.</u> Total tion of E	Electro (nent Mec Hrs Ilectron b	on. Tool Chemical chanism c	Design- holding of metals 9
advantages and Electrochemical d Plasma Arc Mac removal, PAN par 4 UNIT-IV Electron Beam M electron beam ma	disadvantages - applications. E eburring. hining: Introduction-Plasma-Gene ameters-process characteristics - f lachining (EBM) : Introduction-Ec ichining Thermal & Non thermal typ	lynamics lectro (ration of type of to quipmen poes char	s of E Chemia f Plasn orches t for p racteris	cal G na an appli appli roduc stics -	d equipm cations. Total tion of E - applicat	Electro (nent Mec Hrs Electron b ions.	on. Tool Chemical chanism c beam - T	Design- holding of metals 9 heory of
advantages and Electrochemical d Plasma Arc Mac removal, PAN par 4 UNIT-IV Electron Beam Mac Laser Beam Mac	disadvantages - applications. E eburring. hining: Introduction-Plasma-Gene ameters-process characteristics - Machining (EBM): Introduction-Ec chining Thermal & Non thermal type chining (LBM): Introduction-princi	lynamics lectro (ration of type of to quipmen bes char ple of g	s of E Chemic Plasn orches t for p cacteris enerat	cal G na an appli roduc stics - ion of	d equipm cations. Total tion of E applicat	Electro (ment Mec Hrs Ilectron t ions. Equipment	on. Tool Chemical chanism c beam - T nt and M	Design- holding of metals 9 heory of
advantages and Electrochemical d Plasma Arc Mach removal, PAN par 4 UNIT-IV Electron Beam Mach electron beam mach Laser Beam Mach procedure-Types	disadvantages - applications. E eburring. hining: Introduction-Plasma-Gene ameters-process characteristics - f lachining (EBM) : Introduction-Ec ichining Thermal & Non thermal typ	lynamics lectro (ration of type of to quipmen bes char ple of g advanta	s of E Chemic Plasn orches t for p racteris enerat ges an	cal G na an appli roduc stics - ion of d limi	d equipm cations. Total tion of E applicat lasers f tations-a	Electro (ment Mec Hrs Electron to ions. Equipment pplication	on. Tool Chemical chanism o Deam - T nt and M ns	Design- holding of metals 9 heory of achining
advantages and Electrochemical d Plasma Arc Mach removal, PAN par 4 UNIT-IV Electron Beam Mach electron beam mach Laser Beam Mach procedure-Types	disadvantages - applications. E eburring. hining: Introduction-Plasma-Gene ameters-process characteristics - Machining (EBM): Introduction-Ec chining Thermal & Non thermal typ chining (LBM): Introduction-princi of Lasers-Process characteristics- ining: Introduction-Mechanism o	lynamics lectro (ration of type of to quipmen bes char ple of g advanta	s of E Chemic Plasn orches t for p racteris enerat ges an	cal G na an appli roduc stics - ion of d limi	d equipm cations. Total tion of E applicat lasers f tations-a	Electro (ment Mec Hrs Electron to ions. Equipment pplication	on. Tool Chemical chanism o Deam - T nt and M ns	Design- holding of metals 9 heory of achining
advantages and Electrochemical d Plasma Arc Mac removal, PAN par 4 UNIT-IV Electron Beam Mac procedure-Types Ion Beam Mach	disadvantages - applications. E eburring. hining: Introduction-Plasma-Gene ameters-process characteristics - Machining (EBM): Introduction-Ec chining Thermal & Non thermal typ chining (LBM): Introduction-princi of Lasers-Process characteristics- ining: Introduction-Mechanism o	lynamics lectro (ration of type of to quipmen bes char ple of g advanta	s of E Chemic Plasn orches t for p racteris enerat ges an	cal G na an appli roduc stics - ion of d limi	d equipm cations. Total tion of E applicat lasers f tations-a	Electro (ment Mec Hrs Electron b ions. Equipmen pplication ciated ec	on. Tool Chemical chanism c beam - T nt and M ns quipment	Design- holding of metals 9 heory of achining
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Department	Mechanical Engineering	Prog	ramm Na		de &	M.E. (C	AD/CAM)
	Sem	ester-l						
Course Code	Course Name	Hours/ \	Week	1	Credit	Maximu	im Marks	
		L	Т	Ρ	С	E	I	Total
ME 530	PRODUCT DESIGN AND PROCESS PLANNING	4	0	0	3	75	25	100
Objective (s)	To enable students gain knowled	ge about	t proc	cedur	e of des	igning ar	nd manuf	acturing
	new products.							
	To understand agronomical princip			e use	of comp	uters as t	tool in ma	aking an
	effective designing and manufactur							
Outcome (s)	Apply coherent and advance know							
	contexts and applications using crit							
	production skill and processes to m		produ	ict de	sign, by r	nanaging	j time, an	a utilize
	the resources effectively and efficie		ial an	dara		nd thair i	nfluonoo	~ ~
	Apply new and emerging technolog	gy, materi	iai an	a pro	cesses a	na their i	nnuence	on
	product design. Design a product using suitable ma	storiale wi	uith the	o into	ntion of i	morovina	accacto	of the
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	and process design functions, sele							
	ology of design, sources of new in tion procedure-Flow chart. Quali	fications						
	of a product. Value of appearance, of						er. Cri	lena ior
2 UNIT-II	or a product. Value of appearance, c	Joiours ai	nu La		otal Hrs	nce.	9	
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		3, Manun						
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	ions, classes of patents, applying		nts. ⁻	Trade	marks a	nd copyr	ights. C	
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CAD/CAM LABORATORY

Instruction Sessional

3 periods/week 50 Marks

Objectives:

- 1. Be able to produce CAD drawings which communicate the appropriate manufacturing details, standards, and specifications.
- 2. Have the ability to effectively communicate with others using oral, written, and graphical methods and procedures.
- 3. Be able to function effectively on teams or on group projects and assume leadership roles when appropriate.
- 4. Perform in a professional and ethical manner and maintain currency in technological advancements. **Outcomes**:
- 1. Solve design and manufacturing problems using sound engineering principles and practices.
- 2. Produce CAD drawings which communicate the appropriate manufacturing details, standards, and specifications.
- 3. Effectively communicate with others using verbal, written, and graphical methods and procedures.
- 4. Function effectively on teams or on group projects, and assume leadership roles when appropriate.
- 5. Perform in a professional and ethical manner and maintain currency in technological advancements.
- 6. Info management (computer & research skills appropriate to degree level and type).
- 7. Written and oral communication (appropriate to degree level and type).
- 8. Critical thinking (problem solving, reasoning skills appropriate to degree level and type).

List of Exercises:

CAD

- 1. Understanding of various CAD commands and creating simple objects
- 2. Understanding of holes, cuts and model tree relations
- 3. Creation shafts, rounds, chamfers and slots
- 4. Sketch Tools & Datum planes
- 5. Creation of objects by revolved features, patterns and copies, sweeps and blends
- 6. Creation of engineering drawing details such as dimensioning, sectional views, adding esthetics
- 7. Assembling of part models using constraints
- 8. Assembly operations part modifications, adding another assembly features display.

CAM

- 1. Understanding of CNC Machines and CNC Programming and Creation of 2-D contour Pockets, Slots
- 2. Drills and Facing, 2-D high Speed blend
- 3. Surface Roughing for Bottle die
- 4. Surface finishing for Phone die
- 5. Manufacturing of Crane Hook
- 6. Manufacturing of Connecting Rod
- 7. Manufacturing of Turbine Blade
- 8. 3-D Machining using ball nose cutters

COMPUTATIONAL LABORATORY

Instruction Sessional 3 periods / week 50 Marks

Objective: Computation lab introduces various elements that are used to model real time structures that find application in daily life. The course will cover a wide range of elements starting from link, beam, plane, solid and shell elements for structural, thermal and vibration analysis. Link element is used to represent transmission tower. Columns and bridges use beam elements. To model plane stress and plane strain cases in a plate, plane, solid and shell elements are selected. The later part of the course will deal with the analysis of solidification of casting, thermal analysis and explicit dynamics. All these simulations are carried out in ANSYS.

Outcomes: The inputs in this lab can be extended to complicated structures that find application in automobile and aerospace industry

List of Experiments:

- 1. Introduction to Finite Element Analysis Software.
- 2. Static analysis of a corner bracket.
- 3. Statically indeterminate reaction force analysis.
- 4. Determination of Beam stresses and Deflection.
- 5. Bending analysis of a Tee-shaped beam.
- 6. Analysis of cylindrical shell under pressure.
- 7. Bending of a circular plate using axisymmetric shell element.
- 8. Stress analysis in a long cylinder.
- 9. Solidification of a casting.
- 10. Transient Heat transfer in an infinite slab.
- 11. Transient Thermal stress in a cylinder.
- 12. Vibration analysis of a simply supported beam.
- 13. Natural frequency of a motor generator.
- 14. Thermal structural contact of two bodies.
- 15. Drop test of a container (Explicit Dynamics).